Symmetry and Its Breaking in Path Integral Approach to Quantum Brownian Motion

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- Classical stochastic thermodynamics: thermodynamic quantity \Leftrightarrow individual stochastic trajectory
- No unique notion of a quantum trajectory
 - > Quantum FT: Two projective energy measurement scheme (TPM)
 - Many other definitions for quantum work
- How far can we take ideas of classical stochastic thermodynamics to quantum regime?
- Take Symmetry in path integral as a guiding principle
- Ref.: J. Yeo, arXiv:1909.08212 to appear in Phys. Rev. E.

Stochastic Thermodynamics and Path Integrals

• Symmtery and its Breaking in Classical Systems

Quantum Brownian Motion

- Standard Path Integral Formalism Kadanoff-Baym contour
- Path Integral on Deformed Keldysh Contour

3 Equilibrium

4 Nonequilibrium

5 Summary and Outlook

Langevin equation

$$\dot{x}=f(x,\lambda_t)+\xi(t),$$

where $\langle \xi(t)\xi(t')
angle = 2 T \delta(t-t')$

• Transition probability (Onsager-Machlup):

$$P[x_1,\tau|x_0,0] = \int_{x(0)=x_0}^{x(\tau)=x_1} \mathcal{D}x(t) \ e^{-S_{\rm OM}[x]},$$

where

Onsager-Machlup

$$S_{\rm OM}[x] = \int_0^\tau dt \; \frac{1}{4T} (\dot{x}(t) - f)^2.$$

• Path probability ${\cal P}$ is obtained from $\exp[-S_{\rm OM}]P_i(x(0))$.

• Irreversibility:

$$\mathcal{R}[\mathbf{x}] = \ln rac{\mathcal{P}[\mathbf{x}]}{ ilde{\mathcal{P}}[ilde{\mathbf{x}}]}$$

- Can we use the similar concept in the quantum case?
- Convenient to use an alternative representation

Martin-Siggia-Rose-Janssen-De Dominicis formalism

• Introduce an auxiliary field \hat{x}

$$P[x_1,\tau|x_0,0] = \int_{x(0)=x_0}^{x(\tau)=x_1} \mathcal{D}x(t) \int \mathcal{D}\hat{x}(t) \ e^{-S_{\text{MSRJD}}[x,\hat{x}]},$$

where

$$S_{\text{MSRJD}}[x,\hat{x}] = \int_0^\tau dt \left[T\hat{x}(t)^2 + i\hat{x}(t)\{\dot{x} - f\} \right].$$

Integrate over \hat{x} to get Onsager-Machlup.

• FTs are obtained from transformation properties of fields

$$\left(egin{array}{ccc} x(t) &
ightarrow ~~ ilde{x}(t) \equiv x(au-t) \ \hat{x}(t) &
ightarrow ~~ ilde{x}(t) \equiv \hat{x}(au-t) - rac{i}{ au} rac{d}{dt} x(au-t) \end{array}$$

• Equilibrium (no λ_t): Symmetry in action. Equilibrium FDR \leftarrow Ward identity

• Nonequilibrium: Broken symmetry. FT follows from the change in action

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Symmtery and its Breaking in Classical Systems

Total action

$$S_{
m tot}[x,\hat{x};\lambda]\equiv S_{
m MSRJD}[x,\hat{x};\lambda]-\ln P_i(x(0);\lambda_0)$$

• Equilibrium (no λ): $f(x) = -\nabla U(x)$

$$S_{\text{tot}}[\tilde{x}, \tilde{\hat{x}}] = S_{\text{tot}}[x, \hat{x}]$$

• Nonequilibrium:
$$f(x; \lambda) = -\nabla U(x; \lambda)$$

$$S_{\text{tot}}[\tilde{x}, \tilde{\tilde{x}}; \tilde{\lambda}] = S_{\text{tot}}[x, \hat{x}; \lambda] + \frac{1}{T}[F_{\tau} - F_{0}] + \frac{1}{T}\underbrace{\int_{0}^{\tau} dt \, \dot{\lambda}_{t} \frac{\partial U}{\partial \lambda_{t}}}_{\Delta W}.$$

where

$$\tilde{\lambda}_t \equiv \lambda_{\tau-t}.$$

Why MSRJD? Road to Quantum: Schwinger-Keldysh

- MSRJD is classical limit of SK
- Quantum dynamics: $ho(t) = U(t,0)
 ho(0)U^{\dagger}(t,0)$
- Forward and backward paths



• "Classical" and "Quantum" fields:

$$x_c(t) = \frac{1}{2}(x_+(t) + x_-(t)), \qquad x_q(t) = x_+(t) - x_-(t)$$

• Classical limit (for dissipative quantum systems): Connection with MSR fields

$$x_c(t) o x(t), \qquad x_q(t) o \hbar \hat{x}(t)$$

Q: Can we find transformations for x_\pm that correspond to MSRJD ones in classical limit?

We also want

- The action is symmetric for equilibrium case (no time dependent protocol)
- Symmetry is broken for nonequilibrium case
- The change in the action for nonequilibrium leads to quantum FT
- Identify quantum work as a functional of quantum path? (not based on two-measurement scheme)

Previous Works and What We Do

• Previous Works

- Funo and Quan, Phys. Rev. Lett. 121, 040601 (2018) : Path Integral Formalism for TPM work.
- > Sieberer, et al., Phys. Rev. B 92, 134307 (2015)
 - Established symmetry for equilibrium; Nonequilibrium was not considered
 - Dynamics from $t = -\infty$ to $t = \infty$; Fourier components of fields are considered.
 - Hard to apply to get finite-time changes.
- > Aron, Biroli and Cugliandolo, SciPost Phys. 4, 008 (2018)
 - Closed system (but with time-dependent protocol)
 - Deformation of Keldysh contour for a finite-time interval
 - No dissipation into a reservoir.
- Present Work
 - Generalize Aron et al. to an open system with a reservoir.
 - Establish quantum formalism whose classical limit is classical Langevin systems

Quantum Brownian Motion

Caldeira-Leggett Model

Treat a heat bath as a collection of harmonic oscillators:

System

$$H_S = \frac{p^2}{2m} + V(x, \lambda_t)$$

Bath

$$H_B = \sum_n \left(\frac{p_n^2}{2m_n} + \frac{1}{2}m_n\omega_n^2 q_n^2 \right)$$

• Interaction:

$$H_I = -x \sum_n c_n q_n + \sum_n \frac{c_n^2}{2m_n \omega_n^2} x^2$$

• Total Hamiltonian $H_{tot} = H_S + H_B + H_I$

$$H_{\rm tot} = \frac{p^2}{2m} + V(x,\lambda_t) + \sum_n \left(\frac{p_n^2}{2m_n} + \frac{m_n\omega_n^2}{2}(q_n - \frac{c_n}{m_n\omega_n^2}x)^2\right)$$

• Density matrix of the total system: $ho(t) = U(t,0)
ho(0)U^{\dagger}(t,0)$ where

$$U(t,0) = \mathbb{T}\exp(-rac{i}{\hbar}\int_0^t H(t')dt')$$

• Reduced density matrix:

$$\rho_r(t) \equiv \mathrm{Tr}_B \rho(t)$$

• In this work, we focus on the case where the system and the bath are initially at equilibrium, i.e.

$$\rho(0) = \frac{1}{Z_{\beta}} e^{-\beta H(0)}, \quad Z_{\beta} = \text{Tr} e^{-\beta H(0)}$$

Standard Path Integral Formalism

Kadanoff-Baym contour

$$\rho_r(x_f, x'_f; t) = \frac{1}{Z} \int dx_i \int dx'_i \int_{x_i}^{x_f} \mathcal{D}x \int_{x'_i}^{x'_f} \mathcal{D}x' \int_{x'_i}^{x_i} \mathcal{D}\bar{x}$$
$$\times \exp\left[\frac{i}{\hbar}(S_S[x] - S_S[x']) - \frac{1}{\hbar}S_S^E[\bar{x}] - \frac{1}{\hbar}\Psi[x, x', \bar{x}]\right]$$



- $Z = Z_{\beta}/Z_B$ with $Z_B = \mathrm{Tr}_B e^{-\beta H_B}$
- Ψ: Feynman-Vernon Influence Functional

Path Integral on Deformed Keldysh Contour

- $\bullet\,$ To find desired transformations for $x_\pm,$ we need to deform the Kadanoff-Baym contour
- Based on Aron et al. (2018).
- Usual approach: Insert a completeness relation at a time slice t_k

$$1=\int dx_k doldsymbol{q}_k \ |x_k,oldsymbol{q}_k
angle \langle x_k,oldsymbol{q}_k|$$

alternative form

$$1=\int d\mathsf{x}_k doldsymbol{q}_k \; e^{i heta(t_k)\mathcal{H}(t_k)/\hbar}|\mathsf{x}_k,oldsymbol{q}_k\rangle\langle\mathsf{x}_k,oldsymbol{q}_k|e^{-i heta(t_k)\mathcal{H}(t_k)/\hbar}$$

• Use $\theta_{\pm}(t)$ for forward and backward paths

• In the *k*-th time slice (forward path)

$$\begin{aligned} &\langle x_{k+1}, \boldsymbol{q}_{k+1} | e^{-i\theta_+(t_{k+1})H_{\text{tot}}/\hbar} e^{-iH_{\text{tot}}(dt)/\hbar} e^{i\theta_+(t_k)H_{\text{tot}}/\hbar} | x_k, \boldsymbol{q}_k \rangle \\ = &\langle x_{k+1}, \boldsymbol{q}_{k+1} | e^{-i(1+\partial_t\theta_+(t_k))(dt)H_{\text{tot}}/\hbar} | x_k, \boldsymbol{q}_k \rangle, \end{aligned}$$

• Reparametrization of time

$$dz = (1 + \partial_t heta_+(t))dt, \quad ext{or} \quad z(t) = t + heta_+(t)$$

Lagrangian

$$(ext{k-th matrix element}) = \exp\left[rac{i}{\hbar}(dz)\mathcal{L}(x(z), oldsymbol{q}(z))
ight]$$

•
$$\mathcal{L}_{\text{tot}}^{\pm} = \mathcal{L}_{\text{S}}^{\pm} + \mathcal{L}_{\text{B}}^{\pm} + \mathcal{L}_{\text{I}}^{\pm}$$

$$\mathcal{L}_{\text{S}}^{\pm} = \frac{m}{2} \left(\frac{dx_{\pm}}{dz_{\pm}}\right)^2 - V(x_{\pm}(z_{\pm})),$$

$$\begin{split} \mathcal{L}_{\mathrm{B}}^{\pm} &= \sum_{n} \left[\frac{m_n}{2} \left(\frac{dq_{\pm,n}}{dz_{\pm}} \right)^2 - \frac{1}{2} m_n \omega_n^2 q_{\pm,n}^2(z_{\pm}) \right], \\ \mathcal{L}_{\mathrm{I}}^{\pm} &= x_{\pm}(z_{\pm}) \sum_{n} c_n q_{\pm,n}(z_{\pm}) - \frac{\mu}{2} x_{\pm}^2(z_{\pm}). \end{split}$$

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Deformed Path: $\theta_{\pm}(t) = \pm i\hbar\beta/4$



• Upon integrating over $oldsymbol{q}_{\pm}$, we obtain

$$1 = \frac{1}{Z(0)} \int dx_i \int dx_f \int_{x_i}^{x_f} \mathcal{D}x_+(z) \int_{x_f}^{x_i} \mathcal{D}x_-(z)$$

 $\times \exp\left(\frac{i}{\hbar}S_+[x_+] + \frac{i}{\hbar}S_-[x_-] - \frac{1}{\hbar}\Psi[x_+, x_-]\right),$

where

$$S_{\pm}[x_{\pm}] = \int_{\mathcal{C}_{\pm}} dz \ \mathcal{L}_{\mathrm{S}}^{\pm}(x_{\pm}(z))$$

is the system action

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Influence Functional

• The effect of the coupling to the bath is reflected in

$$\begin{split} \Psi[x_{+},x_{-}] &= \int\limits_{C_{+}} dz \int\limits_{C_{+}, z > z'} dz' \ x_{+}(z) \mathcal{K}(z-z') x_{+}(z') \\ &+ \int\limits_{C_{-}} dz \int\limits_{C_{-}, z > z'} dz' \ x_{-}(z) \mathcal{K}(z-z') x_{-}(z') \\ &+ \int\limits_{C_{-}} dz \int\limits_{C_{+}} dz' \ x_{-}(z) \mathcal{K}(z-z') x_{+}(z'), \end{split}$$

where

$$K(z) \equiv \sum_{n} \frac{c_n^2}{2m_n \omega_n} \frac{\cosh(\frac{1}{2}\beta \hbar \omega_n - i\omega_n z)}{\sinh(\frac{1}{2}\beta \hbar \omega_n)}$$

Equilibrium Symmetry

Field Transformations

$$egin{aligned} & x_+(z) o ilde{x}_+(z) \equiv x_+\left(t-z+rac{i\hbareta}{2}
ight) \ & x_-(z) o ilde{x}_-(z) \equiv x_-\left(t-z-rac{i\hbareta}{2}
ight) \end{aligned}$$



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Symmetry in Path Integrals of Open Quantum System

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One can show

Equilibrium Symmetry

$$S_{\pm}[\tilde{x}_{\pm}] = S_{\pm}[x_{\pm}], \quad \Psi[\tilde{x}_{+}, \tilde{x}_{-}] = \Psi[x_{+}, x_{-}]$$

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Equilibrium Fluctuation Dissipation Relations

• Apply field transformation to correlation functions (Green's functions)

$$\begin{split} &iG^{>}(t_{1},t_{2}) = \operatorname{Tr}[\hat{x}(t_{1})\hat{x}(t_{2})\hat{\rho}(0)] = \langle x_{-}(t_{1})x_{+}(t_{2})\rangle \\ &iG^{<}(t_{1},t_{2}) = \operatorname{Tr}[\hat{x}(t_{2})\hat{x}(t_{1})\hat{\rho}(0)] = \langle x_{+}(t_{1})x_{-}(t_{2})\rangle, \end{split}$$

where $\hat{x}(t) = e^{i\hat{H}_{\rm tot}t/\hbar}\hat{x}e^{-i\hat{H}_{\rm tot}t/\hbar}$.

Equilibrium FDR



Equilibrium FDR

• Contour after field transformations



• $e^{-\beta \hat{H}_{tot}/2} \hat{x} e^{\beta \hat{H}_{tot}/2}$ at $t - t_2$ • $e^{\beta \hat{H}_{tot}/2} \hat{x} e^{-\beta \hat{H}_{tot}/2}$ at $t - t_1$

Equilibrium FDR

• Equilibrium symmetry gives

FDR

$$G^>(t_1,t_2)=G^<(t-t_2+rac{i\hbareta}{2},t-t_1-rac{i\hbareta}{2})$$

Using $\tau \equiv t_1 - t_2$,

$$G^{>}(\tau) = G^{<}(\tau + i\hbar\beta)$$

• Relationship with retarded, advanced and Keldysh Green's functions

$$G^{R}(\tau) - G^{A}(\tau) = G^{>}(\tau) - G^{<}(\tau), \quad G^{K}(\tau) = G^{>}(\tau) + G^{<}(\tau)$$

$$\cosh\left(rac{i\hbareta}{2}\partial_{ au}
ight)\left[G^{
m R}(au)-G^{
m A}(au)
ight]=2\sinh\left(rac{i\hbareta}{2}\partial_{ au}
ight)G^{
m K}(au).$$

Time-dependent $H_{\rm S}$

• Evaluate
$$\langle x_{k+1}, \boldsymbol{q}_{k+1} | M_k^+ | x_k, \boldsymbol{q}_k \rangle$$

$$\begin{split} M_k^+ = & e^{-\frac{i}{\hbar}\theta_+(s_{k+1})H_{\text{tot}}(s_{k+1})} e^{-\frac{i}{\hbar}H_{\text{tot}}(s_k)ds} e^{\frac{i}{\hbar}\theta_+(s_k)H_{\text{tot}}(s_k)} \\ \simeq & 1 - \frac{i}{\hbar}ds(1 + \dot{\theta}_+(s_k))H_{\text{tot}}(s_k) \\ & -\frac{i}{\hbar}ds\theta_+(s_k)\int_0^1 d\xi \ e^{-\frac{i}{\hbar}\xi\theta_+(s_k)H_{\text{tot}}(s_k)}(\partial_s H_{\text{tot}}(s_k)) e^{\frac{i}{\hbar}\xi\theta_+(s_k)H_{\text{tot}}(s_k)}, \end{split}$$

Identity

$$\frac{d}{dt}e^{O(t)} = \int_0^1 d\xi \; e^{\xi O(t)} \frac{dO(t)}{dt} e^{(1-\xi)O(t)}$$

 \bullet On \mathcal{C}_2^+ , modified system Lagrangian $\widehat{\mathcal{L}}_{\mathrm{S}}^+$ at time slice s_k

$$e^{rac{i}{\hbar}ds\widehat{\mathcal{L}}_{\mathrm{S}}^{+}} = \langle x_{k+1}|1-rac{i}{\hbar}ds(H_{\mathrm{S}}(s_{k})+F_{+}(s_{k}))|x_{k}
angle$$

where

$$F_{+}(s)\equiv irac{\beta\hbar}{4}\int_{0}^{1}d\xi\;e^{rac{1}{4}\xieta H_{\mathrm{S}}(s)}\partial_{s}H_{\mathrm{S}}(s)e^{-rac{1}{4}\xieta H_{\mathrm{S}}(s)}.$$

 \bullet On \mathcal{C}_2^- modified system Lagrangian $\widehat{\mathcal{L}}_{\mathrm{S}}^-$ at time slice s_k

$$e^{-\frac{i}{\hbar}ds\widehat{\mathcal{L}}_{\mathrm{S}}^{-}} = \langle x_{k}|1 + \frac{i}{\hbar}ds(H_{\mathrm{S}}(s_{k}) + F_{-}(s_{k}))|x_{k+1}\rangle,$$

where

$$F_{-}(s) \equiv -i rac{\beta \hbar}{4} \int_{0}^{1} d\xi \; e^{-rac{1}{4}\xi eta H_{\mathrm{S}}(s)} \partial_{s} H_{\mathrm{S}}(s) e^{rac{1}{4}\xi eta H_{\mathrm{S}}(s)}.$$

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Modified system action

$$\widehat{S}_{\pm}[x_{\pm};\lambda] = \widehat{S}_1^{\pm}[x_{\pm};\lambda_0] + \widehat{S}_3^{\pm}[x_{\pm};\lambda_t] + \widehat{S}_2^{\pm}[x_{\pm};\lambda],$$

• $\widehat{\mathcal{S}}_1$ and $\widehat{\mathcal{S}}_3$ use the same Lagrangian

$$\widehat{S}_{1}^{\pm}[x_{\pm};\lambda_{0}] = \int_{\mathcal{C}_{1}^{\pm}} dz \ \mathcal{L}_{\mathrm{S}}^{\pm}(x_{\pm}(z), \dot{x}_{\pm}(z); \lambda_{0})$$
$$\widehat{S}_{3}^{\pm}[x_{\pm};\lambda_{t}] = \int_{\mathcal{C}_{3}^{\pm}} dz \ \mathcal{L}_{\mathrm{S}}^{\pm}(x_{\pm}(z), \dot{x}_{\pm}(z); \lambda_{t})$$

• Modified Lagrangian for \widehat{S}_2 :

$$\widehat{S}_{2}^{\pm}[x_{\pm};\lambda] = \pm \int_{0}^{t} ds \ \widehat{\mathcal{L}}_{\mathrm{S}}^{\pm}(x_{\pm}(s\pm \frac{i\hbar\beta}{4}),\dot{x}_{\pm}(s\pm \frac{i\hbar\beta}{4});\lambda_{s})$$

• Behavior of modified actions under field transformations

$$\begin{split} \widehat{S}_1^{\pm}[\widetilde{x}_{\pm};\lambda_0] &= \widehat{S}_3^{\pm}[x_{\pm};\lambda_0] \equiv \widehat{S}_3^{\pm}[x_{\pm};\widetilde{\lambda}_t] \\ \widehat{S}_3^{\pm}[\widetilde{x}_{\pm};\lambda_t] &= \widehat{S}_1^{\pm}[x_{\pm};\lambda_t] \equiv \widehat{S}_1^{\pm}[x_{\pm};\widetilde{\lambda}_0], \end{split}$$

where time-reversed protocol: $\tilde{\lambda}_s \equiv \lambda_{t-s}$

$$\widehat{S}_{2}^{\pm}[\widetilde{x}_{\pm};\lambda] = \widehat{S}_{2}^{\pm}[x_{\pm};\widetilde{\lambda}] \pm \Sigma_{\pm}[x_{\pm};\widetilde{\lambda}],$$

with

$$\Sigma_{\pm}[x_{\pm}; \tilde{\lambda}] = -\Sigma_{\pm}[\tilde{x}_{\pm}; \lambda].$$

Consider

$$\begin{split} \left\langle e^{\frac{i}{\hbar} (\Sigma_{+}[x_{+};\lambda] + \Sigma_{-}[x_{-};\lambda])} \right\rangle &= \frac{1}{Z(0)} \int dx_{i} \int dx_{f} \int_{x_{i}}^{x_{f}} \mathcal{D}x_{+} \int_{x_{f}}^{x_{i}} \mathcal{D}x_{-} \\ &\times e^{\frac{i}{\hbar} (\Sigma_{+}[x_{+};\lambda] + \Sigma_{-}[x_{-};\lambda])} e^{\frac{i}{\hbar} \widehat{S}_{+}[x_{+};\lambda] + \frac{i}{\hbar} \widehat{S}_{-}[x_{-};\lambda] - \frac{1}{\hbar} \Psi[x_{+},x_{-}]}, \end{split}$$

• Change the path integral variables from x_{\pm} to \tilde{x}_{\pm} : Jacobian=1

$$\left\langle e^{\frac{i}{\hbar} (\Sigma_{+} [x_{+};\lambda] + \Sigma_{-} [x_{-};\lambda])} \right\rangle = \frac{1}{Z(0)} \int dx_{i} \int dx_{f} \int_{x_{f}}^{x_{i}} \mathcal{D}x_{+} \int_{x_{i}}^{x_{f}} \mathcal{D}x_{-} \\ \times e^{\frac{i}{\hbar} \widehat{S}_{+} [x_{+};\tilde{\lambda}] + \frac{i}{\hbar} \widehat{S}_{-} [x_{-};\tilde{\lambda}] - \frac{1}{\hbar} \Psi[x_{+},x_{-}]}$$

• Normalization with the reverse protocol $\tilde{\lambda}$ except for the factor of 1/Z(0).

$$\left\langle e^{rac{i}{\hbar}(\Sigma_+[\mathsf{x}_+;\lambda]+\Sigma_-[\mathsf{x}_-;\lambda])}
ight
angle = rac{Z(t)}{Z(0)} \equiv e^{-eta(\mathcal{F}(t)-\mathcal{F}(0))},$$

• If we identify

QM work-like quantity on fluctuating trajectory

$$\frac{1}{\hbar}(\Sigma_{+}[x_{+};\lambda]+\Sigma_{-}[x_{-},\lambda])\equiv -\beta \mathcal{W}$$

we have

Jarzynski-like Equality

$$\left\langle e^{-\beta \mathcal{W}} \right\rangle = e^{-\beta \Delta \mathcal{F}}$$

• To the lowest order of $O(\hbar)$,

$$F_{\pm}(s) \simeq \pm \frac{i\hbar\beta}{4}\dot{\lambda}_{s}\partial_{\lambda}V,$$

and

$$\Sigma_{\pm}[x_{\pm},\lambda] \simeq rac{i\hbareta}{2} \int_0^t ds \ \dot{\lambda}_s \partial_\lambda V(x_{\pm}(s\pm rac{i\hbareta}{4}),\lambda_s).$$

 $\bullet\,$ To the leading order in $\hbar\,$

$$\mathcal{W} \simeq rac{1}{2} \int_0^t ds \; \dot{\lambda_s} \partial_\lambda \Big[V(x_+(s);\lambda_s) + V(x_-(s);\lambda_s) \Big].$$

• System Hamiltonian

$$H_{\rm S}=\frac{p^2}{2m}+\frac{1}{2}m\omega_0^2(x-\lambda_s)^2$$

$$\Sigma_{\pm}[x_{\pm};\lambda] = -2im\omega_0 \int_0^t ds \ \dot{\lambda}_s(x_{\pm}(s\pm \frac{i\hbar\beta}{4})-\lambda_s)\sinh(\frac{\beta\hbar\omega_0}{4}).$$

QM work: pulled harmonic oscillator

$$\mathcal{W} = -\frac{4}{\beta \hbar \omega_0} \sinh(\frac{\beta \hbar \omega_0}{4}) \int_0^t ds \ m \omega_0^2 \dot{\lambda}_s(x_c(s) - \lambda_s),$$

where

$$x_c(s) \equiv \frac{1}{2} [x_+(s + \frac{i\hbar\beta}{4}) + x_-(s - \frac{i\hbar\beta}{4})]$$

Classical Limit

Saddle point (small $\hbar)$ analysis in terms of

classical and quantum fields

$$egin{aligned} &x_c(s)\equiv rac{1}{2}\left[x_+(s+rac{i\hbareta}{4})+x_-(s-rac{i\hbareta}{4})
ight]\ &x_q(s)\equiv x_+(s+rac{i\hbareta}{4})-x_-(s-rac{i\hbareta}{4}) \end{aligned}$$

Connection with MSRJD fields

$$r(s) \equiv \frac{1}{2}(x_+(s) + x_-(s)),$$
 $\hat{x}(s) \equiv \lim_{\hbar \to 0} \frac{1}{\hbar}(x_+(s) - x_-(s)).$

$$x_c(s)=r(s)+O(\hbar^2), \qquad \qquad x_q(s)=\hbar(\hat{x}(x)+rac{ieta}{2}\dot{r}(s))+O(\hbar^2).$$

Classical Limit of Influence Functional

• Write
$$K(s) = N(s) - \frac{i}{2}D(s)$$
 where

$$N(s) = \sum_{n} \frac{c_n^2}{2m_n\omega_n} \coth(\frac{1}{2}\beta\hbar\omega_n)\cos(\omega_n s), \quad D(s) = \sum_{n} \frac{c_n^2}{m_n\omega_n}\sin(\omega_n s).$$

• In the $\hbar \to 0$ limit, ${\it N}(s) \to (1/\hbar)(1/eta)\gamma(s)$, where

$$\gamma(s) \equiv \sum_{n} \frac{c_n^2}{m_n \omega_n^2} \cos(\omega_n s).$$

• Classical Limit of Influence Functional

$$\lim_{\hbar \to 0} \frac{1}{\hbar} \Psi = \frac{1}{2\beta} \int_0^t ds \int_0^t du \, \hat{x}(s) \gamma(s-u) \hat{x}(u)$$
$$+ i \int_0^t ds \, \hat{x}(s) \int_0^s du \, \gamma(s-u) \dot{r}(u).$$

Classical Limit of Path Integral

• In the classical limit, quantum path integral behaves as a path integral over $Z^{-1}(0) \int Dr(s) \int D\hat{x} \exp[S_{\text{MSRJD}}[r, \hat{x}]]$, where

$$\begin{split} S_{\text{MSRJD}} &= -\frac{1}{2\beta} \int_0^t ds \int_0^t du \, \hat{x}(s) \gamma(s-u) \hat{x}(u) \\ &- i \int_0^t ds \, \hat{x}(s) \int_0^s du \, \gamma(s-u) \dot{r}(u) \\ &- i \int_0^t ds \, \hat{x}(s) \{ m\ddot{r}(s) + \partial_r V(r(s); \lambda_s) \} - \beta \mathcal{H}_{\text{S}}(0). \end{split}$$

• This is exactly the MSRJD action for the generalized Langevin equation

$$m\ddot{r}(s) + \partial_r V(r;\lambda_s) + \int_0^s du \ \gamma(s-u)\dot{r}(u) = \xi(s), \tag{1}$$

where the noise $\xi(s)$ satisfies

$$\langle \xi(s) \rangle = 0, \qquad \langle \xi(s)\xi(s') \rangle = \frac{1}{\beta}\gamma(s-s'). \tag{2}$$

Classical Limit of Field Transformations

$$\tilde{x}_c(s) = \frac{1}{2} [x_+(t-s+i\hbar\beta/4) + x_-(t-s-i\hbar\beta/4)] = r(t-s) + O(\hbar^2).$$

 $\tilde{r}(s) = r(t-s).$

$$egin{aligned} & ilde{x}_q(s) = x_+(t-s+i\hbareta/4) - x_-(t-s-i\hbareta/4) \ &= \hbar[\hat{x}(t-s) - rac{ieta}{2}\partial_s r(t-s)] + O(\hbar^3). \end{aligned}$$

On the other hand, we have $\tilde{x}_q(s) = \hbar[\tilde{\hat{x}}(s) + (i\beta/2)\partial_s \tilde{r}(s)].$

$$\tilde{\hat{x}}(s) = \hat{x}(t-s) - i\beta\partial_s r(t-s).$$

These are transformations used in classical stochastic systems to obtain FTs

Joonhyun Yeo (Konkuk)

- Identified the field transformations for open quantum systems which leave the action invariant in equilirium
- FDR follows from the symmetry
- When there is an external time-dependent protocol, the action is not invariant
- In nonequilibrium, using the change in the action under the transformation, we were able to find a version of quantum FT (not based on TPM)
- In the process, we identified quantum work defined on the quantum path.
- Is it possible to identify "entropy production" from these transformations? (e.g. no time-dependent protocol but initial product state of system and bath or a general initial state)