The Resource Theoretic Paradigm of Quantum Thermodynamics with Control POSTECH, 13/11/2019

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- Continuous time dynamical models (often t-independent Hamiltonian)
 - $\geq e^{-it\hat{H}_{\rm SB}}(\rho_{\rm S}\otimes\tau_{\rm B})e^{it\hat{H}_{\rm SB}}$ $e^{-it\mathcal{L}_{\rm S}}(\rho_{\rm S})$



M. Mitchison, Contemp. Phys. (2019) Book: Thermodynamics in the Quantum Regime (2019)

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• Continuous time dynamical models (often t-independent Hamiltonian)

$$\succ e^{-it\hat{H}_{\rm SB}}(\rho_{\rm S}\otimes\tau_{\rm B})e^{it\hat{H}_{\rm SB}}$$

$$e^{-it\mathcal{L}_{\rm S}}(\rho_{\rm S})$$

• Discrete time steps model (uses circuit model)

$$\succ \ \rho_{\rm S}^0 \longrightarrow \rho_{\rm S}^1 \longrightarrow \rho_{\rm S}^2 \longrightarrow \dots$$



M. Mitchison, Contemp. Phys. (2019) Book: Thermodynamics in the Quantum Regime (2019)



Can we achieve a dynamical model without hidden thermodynamic costs?

- Talk overview:

- Yes: derive a continuous time dynamical model for circuit model
- But: difficult due to "catalytic embezzling"
- New physics: 3rd law without light cone
 - laws only apply in equilibrium





s.t. $\rho_{\mathrm{S}}^1 = \mathrm{tr}_{\mathrm{B}}[U_1(\rho_{\mathrm{S}}^0 \otimes \tau_{\mathrm{B}})U_1^{\dagger}]$

M. Horodecki, J. Oppenhem, Nat. Commun (2013). F. Brandão et. al. (2015)



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- David Jennings, 3rd KIAS workshop on Q. Info & and Thermo (2017).

Hamiltonian formulation of transitions

Assume transition occurs during time interval $t \in (t_1, t_2)$



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Open quantum system



Time independent Hamiltonian formulation of transitions



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• Ideally need $ho_{
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- "free" resource, i.e. a "dynamic catalyst": $\rho_{\rm C}(t) = e^{-it\hat{H}_{\rm C}}\rho_{\rm C} e^{it\hat{H}_{\rm C}} \quad \text{for } t \in [0, t_1] \cup [t_2, t_3]$

• Solution: yes, buy unphysical: $\hat{H}_{\mathrm{C}}=\hat{p}_{\mathrm{C}}$

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Requires Infinite energy !

• Therefore need inexact catalysis

Why is there a potential issue? N. Ng et al NJP (2015)

• Consider Inexact Catalysis:

$$\rho_{\rm S}^0 \otimes \rho_{\rm Cat}^0 \xrightarrow[]{\rm NO} \rho_{\rm S}^1 \otimes \rho_{\rm Cat}'$$

• Where

$$\|\rho_{\mathrm{Cat}}^0-\rho_{\mathrm{Cat}}'\|_1=\frac{d_{\mathrm{S}}}{1+(d_{\mathrm{S}}-1)\mathrm{log}_{d_{\mathrm{S}}}d_{\mathrm{Cat}}}\to 0 \ \text{as} \ d_{\mathrm{Cat}}\to\infty$$

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Consider Inexact Catalysis:

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• Where

• A lot is still unknown about inexact catalysis

Conclusion:

• Consider implementation of CTO : $ho^0_{
m S} \xrightarrow[]{
m CTO}
ho^1_{
m S}$

 $\rho^{F}_{\rm SCatBC}(t) = e^{-it\hat{H}_{\rm SCatBC}}(\rho_{\rm S} \otimes \rho^{0}_{\rm Cat} \otimes \tau_{\rm B} \otimes \rho_{\rm C})e^{it\hat{H}_{\rm SCatBC}}$

- Dynamics to be close to ``idealized" case:
 - \blacktriangleright After tracing out the bath, for all times $t \in [0, t_1] \cup [t_2, t_3]$

$$\begin{aligned} \|\rho_{\mathrm{SCatC}}^{F}(t) - \rho_{\mathrm{S}}(t) \otimes \rho_{\mathrm{Cat}}^{0} \otimes \rho_{\mathrm{C}}(t)\|_{1} \to 0 \quad \text{as} \quad d_{\mathrm{C}} \to \infty \\ &= e^{-it\hat{H}_{\mathrm{C}}}\rho_{\mathrm{C}} \, e^{it\hat{H}_{\mathrm{C}}} \\ &\left\{ \begin{array}{l} \rho_{\mathrm{S}}^{0} \ \text{for} \ t \in [0, t_{1}] \\ \rho_{\mathrm{S}}^{1} \ \text{for} \ t \in [t_{2}, t_{3}] \end{array} \right. \end{aligned}$$

This is not sufficient to conclude CTO!

Thm 1: Consider $\tau_{\rm B} = 1/d_{\rm B}$

$$\rho_{\mathrm{SCatCB}}^{F}(t) := e^{-it\hat{H}_{\mathrm{SCatCB}}}(\rho_{\mathrm{S}}^{0} \otimes \rho_{\mathrm{Cat}}^{0} \otimes \rho_{\mathrm{C}}^{0} \otimes \tau_{\mathrm{B}})e^{it\hat{H}_{\mathrm{SCatCB}}},$$

$$\|\rho_{\mathrm{SCatC}}^{F}(t) - \rho_{\mathrm{S}}^{F}(t) \otimes \rho_{\mathrm{Cat}}^{0} \otimes \rho_{\mathrm{C}}(t)\|_{1} \leq \varepsilon_{emb}(t; d_{\mathrm{S}}, d_{\mathrm{Cat}}d_{\mathrm{C}})$$

• There exists $\sigma_{
m S}(t)$ which is $arepsilon_{res}$ close to $ho^F_{
m S}(t)$, i.e.

$$\|\sigma_{\mathrm{S}}(t) - \rho_{\mathrm{S}}^{F}(t)\|_{1} \leq \varepsilon_{res} \left(d_{\mathrm{S}}, d_{\mathrm{Cat}} d_{\mathrm{C}}, \varepsilon_{emb}(t; d_{\mathrm{S}}, d_{\mathrm{Cat}} d_{\mathrm{C}}) \right)$$

where
$$\rho_{\rm S}^0 \otimes \tilde{\rho}_{\rm Cat}^0 \otimes \rho_{\rm C}^0 \xrightarrow[]{\rm NO} \sigma_{\rm S}(t) \otimes \tilde{\rho}_{\rm Cat}^0 \otimes \rho_{\rm C}(t)$$
 for some $\tilde{\rho}_{\rm Cat}^0$.

• Explicitly:

$$\varepsilon_{res} = 5\sqrt{\frac{d_{\rm S}^{5/3} + 4(\ln d_{\rm S} d_{\rm Cat} d_{\rm C})\ln d_{\rm S}}{-\ln \varepsilon_{emb}}}.$$

• Example 1: $\varepsilon_{emb} \propto d_{\rm C}^{-K}$, • Example 1: $\varepsilon_{emb} \propto e^{-d_{\rm C}}$

Quasi-ideal clock

$$|\psi_{\rm Cl}\rangle, \quad \hat{H}_{\rm Cl} + \hat{V}_{\rm Cl}$$

M. Woods, R. Silva, J. Oppenheim, J. Annales Henri Poincaré (2018)



Thm 2:

• The Quasi-Ideal Clock can achieve $\forall t \in [0, t_1] \cup [t_2, t_3]$

$$\varepsilon_{emb}(t; d_{\rm S}, d_{\rm Cat} d_{\rm C}) = \mathcal{O}\left(poly(d_{\rm C}) \exp\left[-c_0 d_{\rm C}^{1/4}\right]\right), \text{ as } d_{\rm C} \to \infty$$

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• Therefore $\forall t \in [0, t_1] \cup [t_2, t_3], \quad \varepsilon_{res} \to 0, \text{ as } d_{\mathcal{C}} \to \infty$

• Definition: The embezzlement-free Control model

Let
$$\hat{H}_{SCatCB} = \hat{H}_{S} + \hat{H}_{Cat} + \hat{H}_{B} + \hat{H}_{SCatB}^{int} \otimes \hat{H}_{C}^{int} + \hat{H}_{C}$$

and \hat{H}_{SCatB}^{int} satisfy:
1) $[\hat{H}_{S} + \hat{H}_{Cat} + \hat{H}_{B}, \hat{H}_{SCatB}^{int}] = 0$
2) $\operatorname{tr}_{B}[e^{-i\hat{H}_{SCatB}^{int}}(\rho_{S}^{0} \otimes \rho_{Cat}^{0} \otimes \tau_{B})e^{i\hat{H}_{SCatB}^{int}}] = \rho_{S}^{1} \otimes \rho_{Cat}^{0}$
for some $\rho_{S}^{1}, \rho_{Cat}^{0}, \tau_{B}$
 $\rho_{SCatB}^{target}(t) = e^{-i\delta(t)\hat{H}_{SCatB}^{int}}(\rho_{S}^{0}(t) \otimes \rho_{Cat}^{0} \otimes \tau_{B})e^{i\delta(t)\hat{H}_{SCatB}^{int}}$
 $\delta(t) = \begin{cases} 0 & \text{for } t \in [0, t_{1}] \\ 1 & \text{for } t \in [t_{2}, t_{3}]. \end{cases}$

► The deviation from the idealised dynamics is bounded by $\|\rho_{\text{SCatC}}^F(t) - \rho_{\text{S}}^F(t) \otimes \rho_{\text{Cat}}^0(t) \otimes \rho_{\text{C}}^0(t)\|_1^4 \leq d_{\text{S}} d_{\text{Cat}} d_{\text{B}} \text{tr} \left[\tau_{\text{B}}^2\right] \Delta_{\text{C}}(t)$

$\succ \text{ The final state } \rho_{\mathrm{S}}^{F}(t) \text{ is } \\ \|\rho_{\mathrm{S}}^{F}(t) - \rho_{\mathrm{S}}^{\mathrm{target}}(t)\|_{1} \leq \sqrt{d_{\mathrm{S}}d_{\mathrm{Cat}}d_{\mathrm{B}}\mathrm{tr}\left[\tau_{\mathrm{B}}^{2}\right]}\Delta_{\mathrm{C}}(t)$

close to one which can be reached via t-CTO: For all $t \in [0, t_1] \cup [t_2, t_3]$ the transition $\rho_{\rm S}^0 \otimes \rho_{\rm Cat}^0 \otimes \rho_{\rm C}^0$ to $\rho_{\rm S}^{\rm target}(t) \otimes \rho_{\rm Cat}^0(t) \otimes \rho_{\rm C}^0(t)$ is possible via a TO.







Can (in principle) the control be thermodynamically free?





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Yes

Selection Open Questions

- Does the control need to be highly coherent?
- Characterization of 3rd law without light-cone bound
- Do the 2nd laws of quantum thermodynamics hold out of equilibrium?