

# Induced second-order gravitational waves

Jinn-Ouk Gong

Korea Astronomy and Space Science Institute  
Daejeon 34055, Korea

Survey Science Group Workshop 2020  
High1 Resort, Korea  
10th Febuary, 2020

# Outline

- 1 Introduction
- 2 Equation of motion for GWs
- 3 2nd order solutions
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs
- 5 Conclusions

- 1 Introduction
- 2 Equation of motion for GWs
- 3 2nd order solutions
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs
- 5 Conclusions

# Why non-linear tensor perturbations a.k.a. GWs?

- Persistent (even during dS)
- Observable signature on small scales
- A new window to the universe

# Induced gravitational waves?

## Test of GR or any modification and possible observational signatures

- 1 Introduction
- 2 Equation of motion for GWs**
- 3 2nd order solutions
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs
- 5 Conclusions

# Reduction of traceless equation

In ADM formulation, dynamics in the (3D) geometric objects e.g.  $K_{ij}$

Traceless part of evolution of  $g_{ij}$  + SVT decomposition

$$g_{ij} = a^2(t) \left[ (1 + 2\varphi)\delta_{ij} + 2\gamma_{,ij} + 2C_{(i,j)} + 2h_{ij} \right]$$

$$\Rightarrow \ddot{h}_{ij} + 3H\dot{h}_{ij} - \frac{\Delta}{a^2} h_{ij} + \frac{1}{a^2} \left( \partial_i \partial_j - \frac{\delta_{ij}}{3} \Delta \right) (-\varphi + \dots)$$

$$= (\text{non-linear combinations of perturbations}) \equiv s_{ij}$$

# Evolution equation for GWs

Decomposition using polarization tensors  $e_{ij}^\lambda(\mathbf{k})$  ( $\lambda = +$  and  $\times$ )

$$h_{ij}(t, \mathbf{x}) = \int \frac{d^3 k}{(2\pi)^3} e^{i\mathbf{k}\cdot\mathbf{x}} \sum_{\lambda=+, \times} h_\lambda(t, \mathbf{k}) e_{ij}^\lambda(\mathbf{k})$$

$$\underbrace{\ddot{h}_\lambda + 3H\dot{h}_\lambda + \frac{k^2}{a^2} h_\lambda}_{\text{linearized in tensor perturbations}} = e_{ij}^{\lambda}(\mathbf{k}) s_{ij}(\mathbf{k})$$

linearized in tensor perturbations



# Non-linear sources

## Scalar-vector-tensor components are all mixed

- **Scalar-scalar** (Mollerach et al. 2004, Ananda et al. 2007, Baumann et al. 2007, Assadullahi et al. 2009...)  
Newtonian gauge, other gauges only very recently

(Hwang, Jeong and Noh 2017, Tomikawa and Kobayashi 2019, De Luca et al. 2019, Inomata and Terada 2019...)

- **Scalar-vector**
- **Vector-vector**
- **Vector-tensor**

Interesting in the presence of vector source, e.g. magnetic field

- ✓ **Scalar-tensor**
- ✓ **Tensor-tensor**

# How the sources look like

$$s_{ij}^{(ss)} = \frac{1}{a^3} \frac{d}{dt} \left[ a \left( 2\varphi\chi_{,ij} + \varphi_{,i}\chi_{,j} + \varphi_{,j}\chi_{,i} \right) \right] + \frac{1}{a^2} \left( \kappa\chi_{,ij} - 4\varphi\varphi_{,ij} - 3\varphi_{,i}\varphi_{,j} \right) + \frac{1}{a^4} \chi^{,k}_{,i}\chi_{,jk} \\ + \frac{1}{a^2} \left[ 2\alpha\dot{\chi}_{,ij} - H\alpha\chi_{,ij} + \dot{\alpha}\chi_{,ij} - 2(\alpha + \varphi)\alpha_{,ij} - \alpha_{,i}\alpha_{,j} - 2\varphi_{,(i}\alpha_{,j)} \right] + 8\pi G(\rho + p)v_{,i}v_{,j}, \quad (46)$$

$$s_{ij}^{(tt)} = \frac{d}{dt} \left( 2h_i^k \dot{h}_{jk} \right) + 3H \left( 2h_i^k \dot{h}_{jk} \right) \\ + \frac{1}{a^2} \left[ 2h^{kl} \left( h_{il,jk} + h_{jl,ik} - h_{ij,kl} - h_{kl,ij} \right) - 2h_i^k \Delta h_{jk} - h^{kl}_{,i} h_{kl,j} + 2h_i^{k,l} \left( h_{jl,k} - h_{jk,l} \right) \right], \quad (47)$$

$$s_{ij}^{(st)} = \frac{d}{dt} \left[ \dot{h}_{ij}\alpha + 2 \left( \varphi\dot{h}_{ij} + \dot{\varphi}h_{ij} + \frac{1}{a^2} h_i^k \chi_{,jk} \right) + \frac{\chi^{,k}}{a^2} \left( h_{ik,j} + h_{jk,i} - h_{ij,k} \right) \right] \\ + 3H \left[ \dot{h}_{ij}\alpha + 2 \left( \varphi\dot{h}_{ij} + \dot{\varphi}h_{ij} + \frac{1}{a^2} h_i^k \chi_{,jk} \right) + \frac{\chi^{,k}}{a^2} \left( h_{ik,j} + h_{jk,i} - h_{ij,k} \right) \right] \\ + \alpha \frac{d}{dt} \left( \dot{h}_{ij} \right) - \frac{1}{a^2} \chi^{,k} \dot{h}_{ij,k} + \kappa \dot{h}_{ij} + \frac{1}{a^2} \left[ -2h_i^k \alpha_{,jk} - \left( h_{ik,j} + h_{jk,i} - h_{ij,k} \right) \alpha^{,k} \right] + \frac{1}{a^2} \chi_{,i}{}^{,k} \dot{h}_{jk} - \frac{1}{a^2} \chi_{,j}{}^{,k} \dot{h}_{ik} \\ + \frac{1}{a^2} \left[ 2 \left( -2\varphi\Delta h_{ij} + h_j^k \varphi_{,ik} - h_{ij}\Delta\varphi \right) + \varphi^{,k} \left( h_{ik,j} + h_{jk,i} - 3h_{ij,k} \right) \right]. \quad (48)$$

- 1 Introduction
- 2 Equation of motion for GWs
- 3 2nd order solutions**
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs
- 5 Conclusions

# Green's function solution

Let the homogeneous solutions of  $Ly(x) = r(x)$  be  $y_1(x)$  and  $y_2(x)$

$$y(x) = (\text{combination of } y_1 \text{ and } y_2 \text{ according to B.C.}) \\ + \int d\tilde{x} r(\tilde{x}) \underbrace{\frac{y_1(\tilde{x})y_2(x) - y_2(\tilde{x})y_1(x)}{y_1(\tilde{x})y_2'(\tilde{x}) - y_2(\tilde{x})y_1'(\tilde{x})}}_{\equiv G(x,\tilde{x})}$$

Linear solutions for scalar and tensor perturbations are well known

# Integral form of induced GWs

If sourced by 2 linear perts  $X$  and  $Y$ , during both MD and RD,

$$\begin{aligned}
 h_\lambda(\eta, \mathbf{k}) &= \frac{1}{a} \int_0^\eta d\tilde{\eta} \left[ a^3(\tilde{\eta}) e_\lambda^{ij}(\mathbf{k}) s_{ij}(\mathbf{k}) \right] G(\eta, \tilde{\eta}) \\
 &= \int \frac{d^3q}{(2\pi)^3} \left[ e_\lambda^{ij}(\mathbf{k})(\dots)_{ij} \right] X_0(\mathbf{k}-\mathbf{q}) Y_0(\mathbf{q}) \int_0^x d\tilde{x} K(\tilde{x}, \mathbf{k}, \mathbf{q})
 \end{aligned}$$

- ①  $e_\lambda^{ij}(\mathbf{k})(\dots)_{ij}$ : Projection of  $e_\lambda^{ij}(\mathbf{k})$
- ②  $X_0(\mathbf{k})$  and  $Y_0(\mathbf{k})$ : Initial amp of  $X$  and  $Y$ , i.e.  $\mathcal{R}(\mathbf{k})$  and/or  $h_0^\lambda(\mathbf{k})$
- ③  $\int_0^x d\tilde{x} K$ : Kernel as a function of time and momenta

# Scalar-scalar induced GWs

In the Newtonian gauge

$$h_{\lambda}(\eta, \mathbf{k}) = \frac{6}{5} \int \frac{d^3 q}{(2\pi)^3} \left[ e_{\lambda}^{ij}(\mathbf{k}) q_i q_j \right] \mathcal{R}(\mathbf{k} - \mathbf{q}) \mathcal{R}(\mathbf{q}) \left[ 1 - 3 \frac{j_1(k\eta)}{k\eta} \right]$$

# Scalar-scalar induced GWs

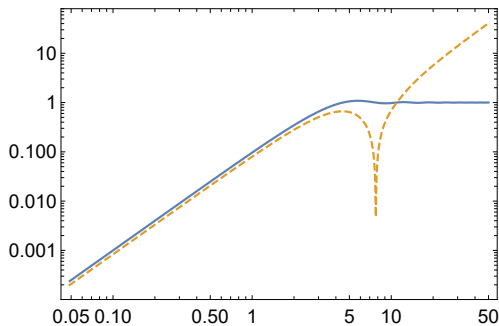
In the Newtonian gauge and comoving gauge

$$h_{\lambda}(\eta, \mathbf{k}) = \frac{6}{5} \int \frac{d^3 q}{(2\pi)^3} \left[ e_{\lambda}^{ij}(\mathbf{k}) q_i q_j \right] \mathcal{R}(\mathbf{k} - \mathbf{q}) \mathcal{R}(\mathbf{q}) \left[ 1 - 3 \frac{j_1(k\eta)}{k\eta} - \frac{(k\eta)^2}{60} \right]$$

# Scalar-scalar induced GWs

In the Newtonian gauge and comoving gauge

$$h_{\lambda}(\eta, \mathbf{k}) = \frac{6}{5} \int \frac{d^3 q}{(2\pi)^3} \left[ e_{\lambda}^{ij}(\mathbf{k}) q_i q_j \right] \mathcal{R}(\mathbf{k} - \mathbf{q}) \mathcal{R}(\mathbf{q}) \left[ 1 - 3 \frac{j_1(k\eta)}{k\eta} - \frac{(k\eta)^2}{60} \right]$$





# Scalar-tensor induced GWs

Scalar-tensor case can be analytically soluble

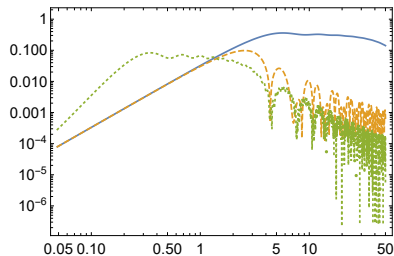
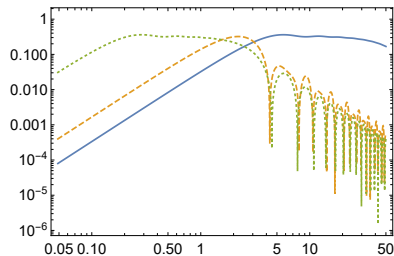
- Newtonian gauge

$$h_{\lambda}(\eta, \mathbf{k}) = \frac{18}{5} \int \frac{d^3 q}{(2\pi)^3} \left[ e_{\lambda}^{ij}(\mathbf{k}) e_{ij}^{\lambda'}(\mathbf{q}) \right] \mathcal{R}(\mathbf{k} - \mathbf{q}) h_0^{\lambda'}(\mathbf{q}) \left[ \frac{j_1(q\eta)}{q\eta} + \frac{j_1(k\eta)}{k\eta} \right] \frac{q^2 + k^2}{q^2 - k^2}$$

- Comoving gauge

$$h_{\lambda}(\eta, \mathbf{k}) = 6 \int \frac{d^3 q}{(2\pi)^3} \left[ e_{\lambda}^{ij}(\mathbf{k}) e_{ij}^{\lambda'}(\mathbf{q}) \right] \mathcal{R}(\mathbf{k} - \mathbf{q}) h_0^{\lambda'}(\mathbf{q}) \times \left[ \frac{q^2 + 5k^2}{5(q^2 - k^2)} \frac{j_1(k\eta)}{k\eta} - \frac{5q^2 + 7k^2}{10(q^2 - k^2)} \frac{j_1(q\eta)}{q\eta} + \frac{1}{10} j_0(q\eta) \right]$$

# Kernels for scalar-tensor induced GWs

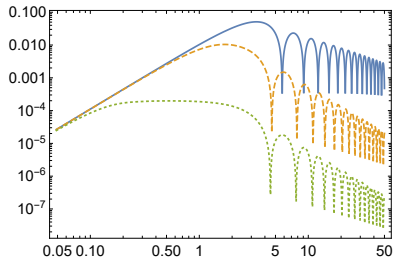
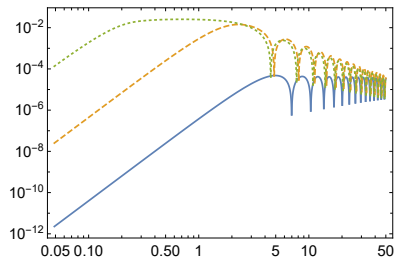


Comoving gauge kernel exhibits more rapid oscillations

# Solutions with tensor-tensor sources

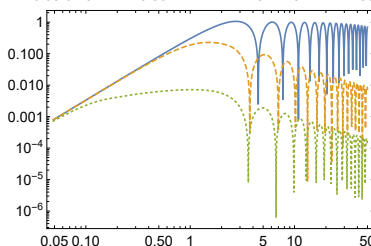
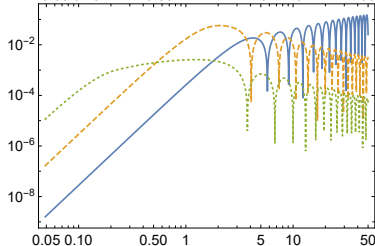
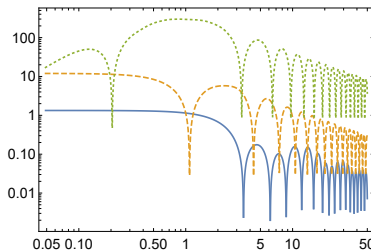
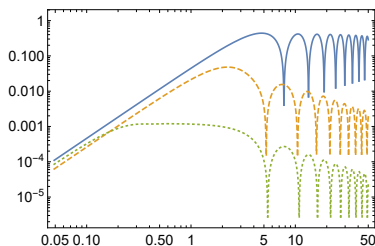
Tensor-tensor source is also analytically soluble

$$h_{\lambda}(\eta, \mathbf{k}) = \int \frac{d^3 q}{(2\pi)^3} \left[ (\dots) F_{\text{MD}}(\eta, \mathbf{k}, \mathbf{q}) + (\dots) G_{\text{MD}}(\eta, \mathbf{k}, \mathbf{q}) \right]$$



# SS, ST and TT induced GWs during RD

Scalar perts in the Newtonian gauge and we can proceed similarly



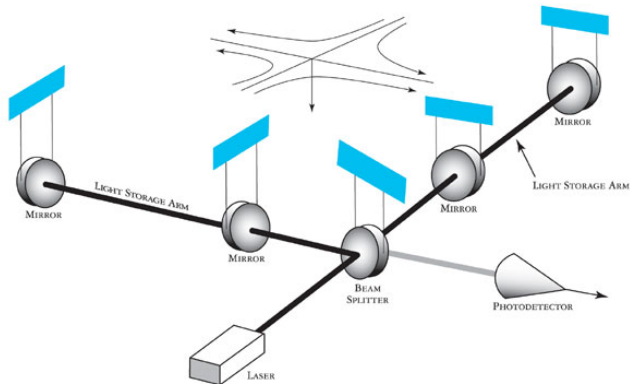
- 1 Introduction
- 2 Equation of motion for GWs
- 3 2nd order solutions
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs**
- 5 Conclusions

# Gauge dependence of induced GWs

Induced (by scalar perts) GWs are **gauge dependent** and thus are not (direct) observable

## But GWs ARE observable

# What we interpret as GWs in experiments



We interpret the **local anisotropic tidal field** as GWs

# Global and local coordinate systems

GW observatories are fixed (= free-falling) on Earth (= weak field approx & local Minkowski space-time)

$$\underbrace{\tilde{g}_{\rho\sigma}(\tilde{x})}_{\text{local Minkowski}} = \frac{\partial x^\mu}{\partial \tilde{x}^\rho} \frac{\partial x^\nu}{\partial \tilde{x}^\sigma} \underbrace{g_{\mu\nu}(x)}_{\text{global FRW}}$$

global ( $x^\mu$ ) to local ( $\tilde{x}^\mu$ ) transformation

We find deviations away from our free-falling observer location

$$ds^2 = -\left(1 + \underbrace{\tilde{R}_{0i0j}\tilde{x}^i\tilde{x}^j}_{\equiv 2\tilde{\Phi}, \text{ local gravitational potential}}\right) d\tilde{t}^2 + \dots$$



# Local GWs from global scalar perturbations

Local gravitational potential  $\tilde{\Phi} = \tilde{R}_{0i0j}\tilde{x}^i\tilde{x}^j/2$  with

$$\tilde{R}_{0i0j} = \left[ (e_0^0)^2 e_i^p e_j^q - 2e_0^p e_i^0 e_0^q e_j^q \right] R_{0p0q} + 2e_0^p e_i^q e_0^0 e_j^r R_{pq0r} + e_0^p e_i^q e_0^r e_j^s R_{pqrs}$$

= complicated 2nd-order expression with global perturbations

## We can read the anisotropic tidal component

Including only global GWs  $g_{ij} = a^2(\delta_{ij} + h_{ij})$  gives what we expect

$$\frac{d^2\tilde{x}^i}{d\tilde{t}^2} = -\frac{\partial\tilde{\Phi}}{\partial\tilde{x}^i} = (\dot{H} + H^2)\tilde{x}^i + \frac{1}{2} \underbrace{\left( \ddot{h}^i_j + 2H\dot{h}^i_j \right)}_{\frac{d^2\tilde{h}_{ij}^{\text{TT}}}{d\tilde{t}^2}} \tilde{x}^j$$

- 1 Introduction
- 2 Equation of motion for GWs
- 3 2nd order solutions
  - How to proceed
  - Induced GWs during MD and RD
- 4 Gauge dependence of induced GWs
- 5 Conclusions**

# Conclusions

- 1 Pure tensor perturbations are of physical interest
- 2 Non-linear evolution allows classical feedback
  - 1 Sourced by all types of linear perturbations
  - 2 Could be relevant on smaller scales
  - 3 Accordance or conflict with PBH formation?
  - 4 “Correct” observable signal?