

All about deformations of cyclic quotient surface singularities

신동수

2021.12.20 대수기하 심포지엄

Correspondence between various descriptions of deformations of cyclic quotient surface singularities via the semi-stable minimal model program

What is ... a cyclic quotient surface singularity?

$$\frac{1}{n}(1, a) = \mathbb{C}^2 / \mu_n \text{ via } \zeta \cdot (x, y) = (\zeta x, \zeta^a y)$$

- Hirzubruch-Jung continued fractions

$$\frac{n}{a} = b_1 - \cfrac{1}{b_2 - \cfrac{1}{\ddots - \cfrac{1}{b_r}}}, \quad b_i \geq 2$$

- Minimal resolutions



Example

$$\frac{1}{19}(1, 7)$$

- Hirzbruch-Jung continued fractions

$$\frac{19}{7} = 3 - \frac{1}{4 - \frac{1}{2}}$$

- Minimal resolutions


$$\longrightarrow \bullet \frac{1}{19}(1, 7)$$

Three descriptions of deformations

- **Equations**
- **P-resolutions**
- **Picture deformations**

Equations

$$z_{i+1}z_{i-1} = z_i^{a_i} + t \cdot z_i^{k_i}$$

$$\frac{1}{n} (1, a)$$

- Dual Hirzebruch-Jung continued fractions

$$\frac{n}{n-a} = [a_1, \dots, a_e]$$

$$K(n/n-a) = \{ (k_1, \dots, k_e) \mid [k_1, \dots, k_e] = 0 \text{ and } \begin{matrix} k_i \geq 1 \\ + k_i \leq a_i \end{matrix} \}$$

$$\downarrow$$

 $[1, 1]$

$$\downarrow$$

 $[2, 1, 2]$

$[3, 1, 2, 3]$

Example

$$\frac{1}{19}(1, 7)$$

- Dual Hirzebruch-Jung continued fractions

$$\frac{19}{19-7} = [2, 3, 2, 3]$$

$$K(19/19-7) = \{ (1, 2, 2, 1), (1, 3, 1, 2), (2, 2, 1, 3) \}$$

↕
reducible
components

P-resolutions

Let $(X, 0)$ be a rational surface singularity and let \mathcal{X} be the total space of a one-parameter smoothing of $(X, 0)$. Then the canonical algebra

$$\sum_{n=0}^{\infty} \mathcal{O}_{\mathcal{X}}(nK_{\mathcal{X}})$$

is a finitely generated $\mathcal{O}_{\mathcal{X}}$ -algebra.

$$\mathcal{X} = \{ x_0 \rightsquigarrow x_1 \}$$

For any rational surface singularity X_0 , there is a one-to-one correspondence between irreducible components of the reduced miniversal deformation space of X_0 and P-modifications of X_0 .

$$\begin{array}{ccc}
 \mathbb{E} \mathcal{A} = \mathbb{E} \{ Y_0 & \xrightarrow{\text{P-modification}} & Y_t \} \\
 \downarrow \text{red} & \downarrow & \\
 \mathcal{X} = \{ X_0 & \rightsquigarrow & X_t \} \text{ given}
 \end{array}$$

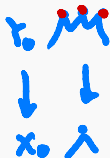
Kollár Conjecture holds for ...

- smoothings over the Artin component
 - rational double points, rational triple points
- quotient surface singularities; [Kollár-Shepherd-Barron 1988]
- quotients of simple elliptic and cusp singularities; [Kollár-Shepherd-Barron 1988]
- rational quadruple points; [Stevens 1991]

For any quotient surface singularity X_0 , there is a one-to-one correspondence between irreducible components of the reduced miniversal deformation space of X_0 and P-resolutions of X_0 .

What is ... a P-resolution?

A partial resolution $f: Y \rightarrow X$ with T-singularities and the ample K_Y relative to f



What is ... a T-singularity?

$$\frac{1}{dn^2}(1, dna - 1) \text{ (or RDP)}$$

- one-parameter \mathbb{Q} -Gorenstein smoothing

- Generating algorithm

$$\boxed{d=1} \quad \frac{1}{n^2}(1, na-1)$$

$$[4]$$

$$\frac{1}{4}(1, 1)$$

$$[b_1, \dots, b_r] : \text{T-sing.}$$

$$\Rightarrow [2, b_1, \dots, b_{r-1}, b_r+1] \\ [b_1+1, b_2, \dots, b_r, 2]$$

$$\bullet [4]$$

$$\bullet [2, 5]$$

$$2 - \frac{1}{5} = \frac{9}{5}$$

$$= \frac{1}{3^2}(1, 5)$$

$$\bullet [5, 2]$$

Example

$$\frac{1}{19}(1, 7)$$

[3, 4, 2]

- $3 - 4 - [2]$



- $3 - [4] - 2$



- $[4] - 1 - [5, 2]$



Picture deformations

A normal surface singularity that admits a birational morphism to \mathbb{C}^2

$$(V, E) \rightarrow (X, o) \longrightarrow (\mathbb{C}^2, o)$$

Digression: Why ... a sandwiched surface singularity?



Digression: Why ... a sandwiched surface singularity?

J. Nash asked to H. Hironaka in the early sixties:

“

Does a finite succession of Nash transformations resolve the singularities of algebraic varieties?

”

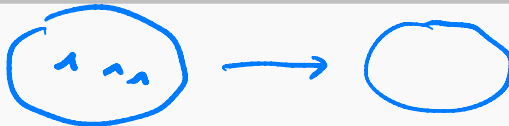
Digression: Why ... a sandwiched surface singularity?

H. Hironaka proved in 1983 that:

“

After a finite succession of normalized Nash transformations we obtain a surface which birationally dominates a non-singular surface.

”



Digression: Why ... a sandwiched surface singularity?

M. Spivakovsky proved in 1990 that:

“

Sandwiched singularities are resolved by a finite sequence of normalized Nash transformations.

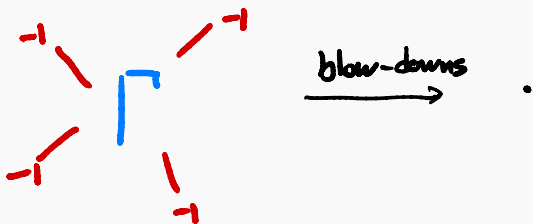
”

What is ... a sandwiched surface singularity?

Sandwiched singularities are rational and characterized by their dual resolution graphs.

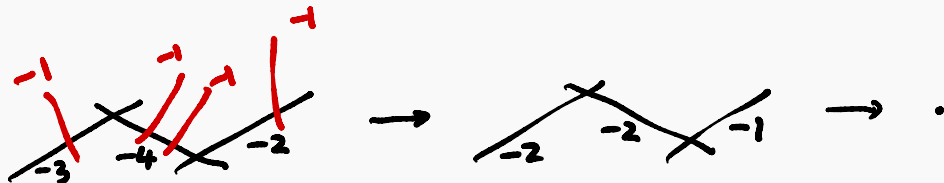
What is ... a sandwiched graph?

A dual resolution graph that blows down to a smooth point by adding (-1) -vertices to some of vertices.



Example

$$\frac{1}{19}(1, 7)$$



Examples of sandwiched surface singularities

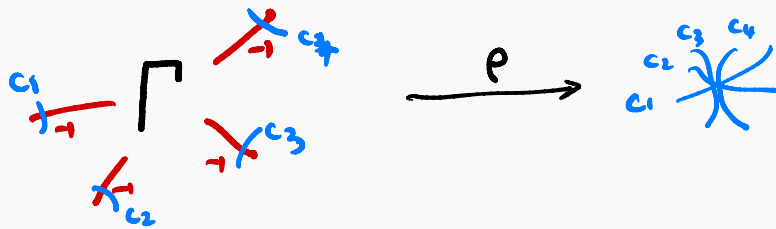
- Cyclic quotient surface singularities
- Weighted homogeneous surface singularities with “big” central nodes
- Rational surface singularities with the reduced fundamental cycles



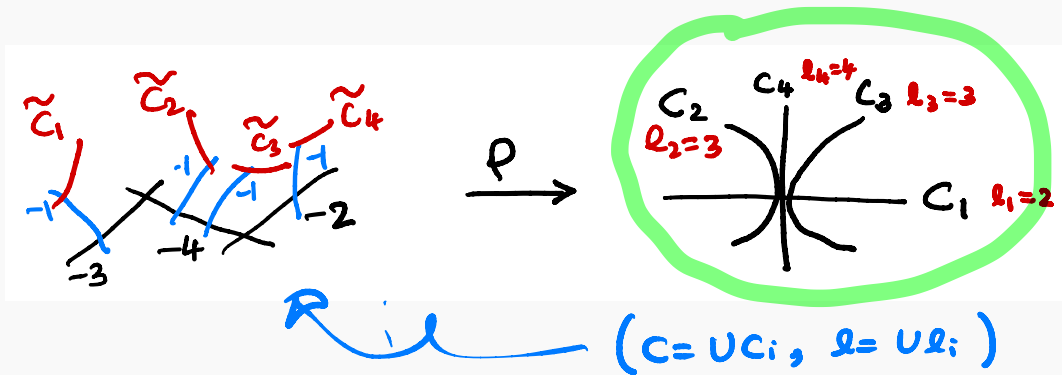
All the **one-parameter deformations** of a sandwiched surface singularity are obtained by **one-parameter deformations of the corresponding decorated curve**. Moreover, all the smoothings of the singularity are provided by **picture deformations** of the decorated curves.

What is ... a decorated curve?

A **decorated curve** (C, l) is a union C of small pieces of curves C_i intersecting each sandwiched (-1) -curves F_i together with integers l_i recording the **number** of blow-ups occurring on the strict transformations of C_i starting from the smooth point.



Example

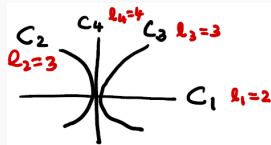


What is ... a picture deformation?

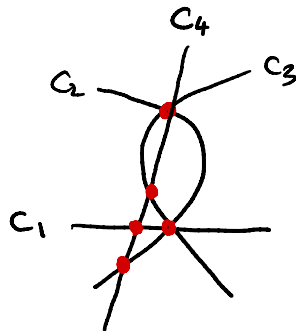
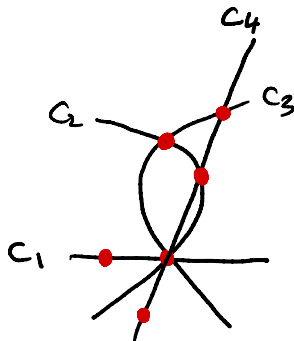
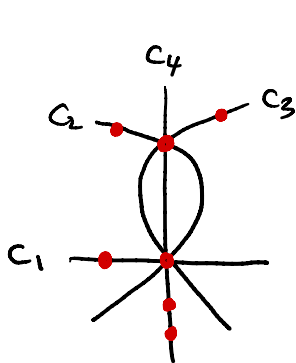
A picture deformation of a decorated curve (C, l) over S consists of

- (a) a δ -constant deformation $C_S \rightarrow S$ of C ,
- (b) a flat deformation $l_S \subset \tilde{C}_S = C_S \times S$ of the scheme l such that
- (c) $m_S \subset l_S$, where the relative total multiplicity scheme m_S of $\tilde{C}_S \rightarrow C$ is defined as the closure $\bigcup_{s \in S \setminus 0} m(C_s)$.
- (d) for generic $s \in S \setminus 0$ the divisor l_s on \tilde{C}_s is reduced.

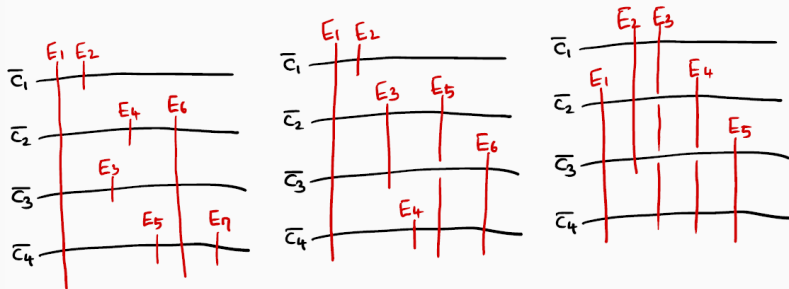
Example



$$\mathcal{C} = \left\{ \begin{array}{c} \text{---} \end{array} \right\} \left\{ \begin{array}{c} \text{---} \end{array} \right\} \xleftarrow{\text{blow-ups on the ideals}} \{x \rightsquigarrow x_t\}$$



Example



$$\begin{array}{c}
 \mathbf{C_1} \\
 \mathbf{C_2} \\
 \mathbf{C_3} \\
 \mathbf{C_4}
 \end{array}
 \begin{array}{c}
 \mathbf{E_1} \quad \mathbf{E_2} \qquad \qquad \mathbf{E_3} \\
 \left[\begin{array}{ccccccc}
 1 & 1 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 1 & 0 & 1 & 0 \\
 1 & 0 & 1 & 0 & 0 & 1 & 0 \\
 1 & 0 & 0 & 0 & 1 & 1 & 1
 \end{array} \right],
 \end{array}
 \begin{array}{c}
 \left[\begin{array}{cccccc}
 1 & 1 & 0 & 0 & 0 & 0 \\
 1 & 0 & 1 & 0 & 1 & 0 \\
 1 & 0 & 1 & 0 & 0 & 1 \\
 1 & 0 & 0 & 1 & 1 & 1
 \end{array} \right],
 \end{array}
 \begin{array}{c}
 \left[\begin{array}{ccccc}
 0 & 1 & 1 & 0 & 0 \\
 1 & 1 & 0 & 1 & 0 \\
 1 & 1 & 0 & 0 & 1 \\
 1 & 0 & 1 & 1 & 1
 \end{array} \right]
 \end{array}$$

Correspondence between the three descriptions

- **Equations**
- **P-resolutions**
- **Picture deformations**

Example

$$\frac{1}{19}(1, 7)$$

$\text{Def}(x_0)$ is reducible
Components

- **Equations**

- $(1, 2, 2, 1), \quad (1, 3, 1, 2), \quad (2, 2, 1, 3)$

- **P-resolutions**

- $3 - 4 - [2], \quad 3 - [4] - 2, \quad [4] - 1 - [5, 2]$

- **Picture deformations**

- $\begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}, \quad \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 1 & 1 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 1 \end{bmatrix}$

Correspondence using topology

The topological method in [Némethi-Popescu-Pampu 2010]

Equations \rightarrow Symplectic fillings \leftarrow Picture deformations

What is ... a symplectic filling?

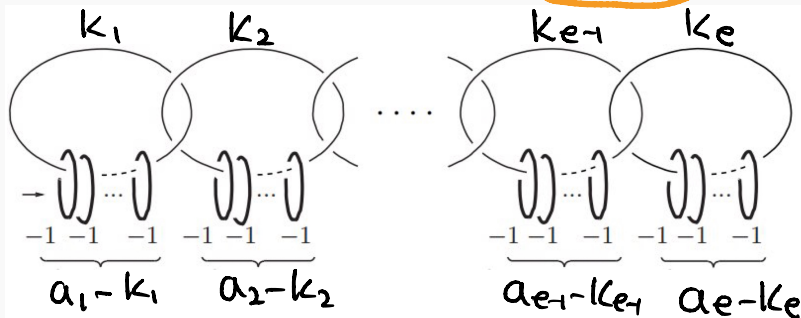
A symplectic 4-manifold with boundary that is compatible with the Milnor fillable contact structure of the boundary



$$W_{n,a}(\underline{k})$$

$$\underline{k} \in K(n, n-a)$$

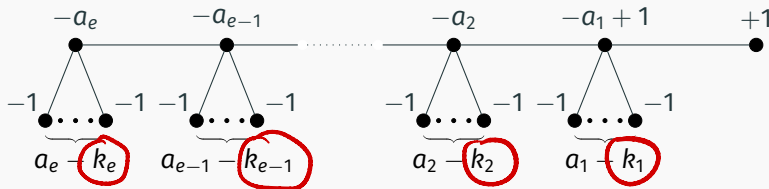
$$\frac{1}{n} \text{char} = L(n, a)$$



$$W_{n,a}(\underline{k})$$

= complement of

$$[a_1, \dots, a_e] = \frac{n}{n-a} \quad \checkmark$$



$\subset \mathbb{C}P^2 \# n\mathbb{C}P^2$

$$\longleftrightarrow (\underline{k}_1, \dots, \underline{k}_e) \in K(n/n-a)$$

$$\begin{array}{l}
 W_{n,a}(\underline{k})^* \not\cong W_{n,a}(\underline{k}')^* \quad \text{if} \quad \underline{k} \neq \underline{k}' \\
 \hline
 \cong \quad \Leftrightarrow \quad \underline{k} = \underline{k}'
 \end{array}$$

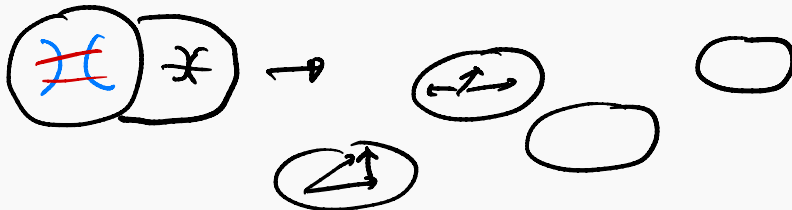
$$X_0 \rightsquigarrow X_t \cong \text{"} \mathbb{CP}^2 \# n \overline{\mathbb{CP}^2} - \star \text{"} \rightarrow \underline{k}$$

Equations \rightarrow Milnor fibers as complements \rightarrow Symplectic fillings $W_{n,a}(\underline{k})$

§II

§II

Picture deformations \rightarrow Milnor fibers as complements \rightarrow Symplectic fillings $W_{n,a}(\underline{k}')$



Correspondence using MMP

Correspondence using MMP

From P-resolutions to Complements

Step 1. Compactifying P-resolutions

$$\mathcal{Z} = \left\{ \boxed{Y_0 - 1 - a_e - \cdots - a_2 - a_1 - 1 - (+1)} \rightsquigarrow \boxed{Y_t - a_e - \cdots - a_2 - a_1 - 1 - (+1)} \right\}$$

$$\begin{array}{ccc} \mathcal{Y} = \{ \gamma_0 \sim \gamma_+ \} & & \\ \downarrow & \downarrow & \\ \mathcal{X} = \{ x_0 \sim x_+ \} & & \end{array}$$

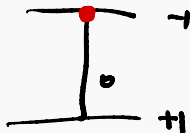
$$\begin{array}{ccc} \mathcal{Z} = \{ \bar{\gamma}_0 \sim \bar{\gamma}_+ \} & & \\ \leftarrow & H^2(\mathcal{Z}, T_{\mathcal{Z}}) = 0 & \end{array}$$

Example

$$\frac{1}{19}(1, 7)$$

$$\{3 - [4] - 2 - 1 - \underline{3 - 2 - 3 - 2} \rightsquigarrow 3 - 2 - 3 - 2\}$$

π_1



Step 2. Applying the semi-stable MMP

By applying only Itaka-Kodaira divisorial contractions and usual flips, one can run MMP to $\mathcal{Z} \rightarrow \Delta$ until we obtain a deformation $\mathcal{Z}' \rightarrow \Delta$ whose central fiber Z'_0 is smooth.

$$\mathcal{Z} = \{Z_0 \rightsquigarrow Z_t\} \xrightarrow{\text{MMP}} \mathcal{Z}^+ = \{Z_0^+ \rightsquigarrow Z_t^+\}$$

Example

$$\{ \overset{E_1}{\overbrace{3-4-2-1}^{\text{green}}} - \overbrace{3-2-3-2}^{\text{pink}} \} \rightsquigarrow \{ \overset{E_1}{\overbrace{3-2-3-2}^{\text{pink}}} \}$$

↓ diagonal contraction

$$\{ \overset{c^-}{3-4-1-x-2-2-3-2} \rightsquigarrow 2-2-3-2 \}$$

↓ flip

$$\{ \overset{c^+}{\overbrace{3-3-x-x-1-2-3-2}^{\text{orange}}} \rightsquigarrow 2-2-3-2 \} = z^+$$

Step 3. Identifying Milnor fibers

- The central fiber Z'_0 is diffeomorphic to a general fiber Z'_t .
- By comparing Z'_0 and Z'_t , one can get the data of positions of (-1) -curves in Z'_t .
- One can get the data of (-1) -curves on Z_t by tracking the blow-downs $Z_t \rightarrow Z'_t$ given by flips and divisorial contractions.

Example

$$\{3 - [4] - 2 - \overset{E_1}{1} - 3 - 2 - 3 - 2 \rightsquigarrow 3 - 2 - 3 - 2\}$$

$$\{3 - [4] - 1 - x - \overset{A_4}{\underset{C^-}{2}} - 2 - 3 - 2 \rightsquigarrow 2 - 2 - 3 - 2\}$$

$$\{3 - \overset{A_4}{\underset{E_2}{3 - x - x - 1}} - 2 - 3 - 2 \rightsquigarrow 2 - 2 - 3 - 2\}$$

$$\{3 - 2 - x - x - x - 1 - 3 - 2 \rightsquigarrow 2 - 1 - 3 - 2\}$$

$$\{3 - 1 - x - x - x - x - 2 - 2 \rightsquigarrow 1 - x - 2 - 2\}$$

$$\{2 - x - x - x - x - x - 1 - 2 \rightsquigarrow x - x - 1 - 2\}$$

$$\{1 - x - x - x - x - x - x - 1 \rightsquigarrow x - x - x - 1\}$$

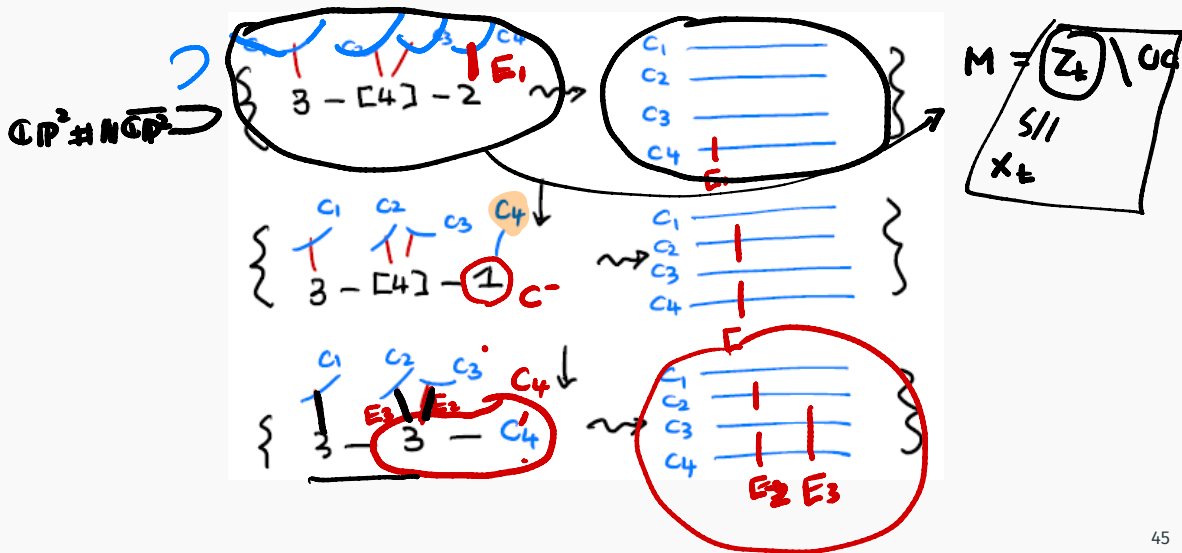
Correspondence using MMP

From P-resolutions to Picture
deformations

For any sandwiched surface singularities, one can obtain picture deformations from P-resolutions via the semi-stable MMP.

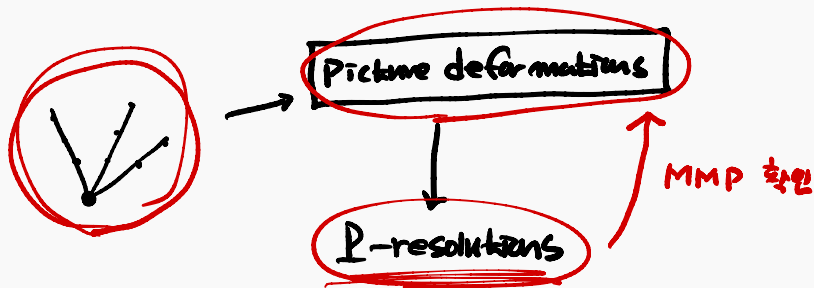
- Step 1. Compactifying P-resolutions
- Step 2. Applying the semi-stable MMP
- Step 3. Identifying Picture deformations

Example



Applications

Try to prove Kollár Conjecture for weighted homogeneous surface singularities with “big” central nodes.



감사합니다!



$$\begin{aligned} (1, 2, 2, 1) &= 3 - 4 - [2] = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix} \\ (1, 3, 1, 2) &= 3 - [4] - 2 = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 1 & 1 \end{bmatrix} \\ (2, 2, 1, 3) &= [4] - 1 - [5, 2] = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 1 \end{bmatrix} \end{aligned}$$