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Weighted scalar curvature rigidity for weighted area-minimizing hypersurface

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Introduction				

First variation formula
 Let F : Σ × (−ε, ε) → M be a variation of Σ with compact support.

$$rac{d}{dt}_{t=0} extsf{Vol}(F(\Sigma,t)) = \int_{\Sigma} \langle F_t, H
angle extsf{dvol}_{\Sigma},$$

where F_t is the variational vector field and H is the mean curvature.

Definition 1

A submanifold Σ is said to be a *minimal submanifold* if its mean curvature vanishes, H = 0. In other words, Σ is a critical point of the volume functional. Moreover, if Σ is (n-1)-dimensional, then Σ is called a *minimal hypersurface*.

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• Second variation formula

$$\frac{d^2}{dt^2}_{t=0} \operatorname{Vol}(F(\Sigma, t)) = \int_{\Sigma} |\nabla^{\Sigma} \varphi|^2 \\ -\varphi^2 \left(\operatorname{Ric}^M(N, N) + |B|^2\right) \operatorname{dvol}_{\Sigma},$$

where N is the normal vector on Σ , B is the second fundamental form of Σ , and $\varphi \in C^{\infty}(\Sigma)$.

Definition 2

We say that Σ is *stable* if

$$rac{d^2}{dt^2}_{t=0}$$
 Vol $(F(\Sigma,t))\geq 0.$

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 (Schoen and Yau (1979)) Let M be a complete 3-dimensional Riemannian manifold with R^M > 0. If M contains a closed, two-sided, immersed, stable minimal hypersurface Σ, then the hypersurface must have genus 0.

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3-manifolds				

 (Schoen and Yau (1979)) Let M be a complete 3-dimensional Riemannian manifold with R^M > 0. If M contains a closed, two-sided, immersed, stable minimal hypersurface Σ, then the hypersurface must have genus 0. Moreover, any area-minimizing surface is homeomorphic to either S² or ℝP².

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3-manifolds				

- (Schoen and Yau (1979)) Let M be a complete 3-dimensional Riemannian manifold with R^M > 0. If M contains a closed, two-sided, immersed, stable minimal hypersurface Σ, then the hypersurface must have genus 0. Moreover, any area-minimizing surface is homeomorphic to either S² or RP².
- (Fischer-Colbrie and Schoen (1980)) If R^M ≥ 0, then the genus of Σ must be zero or one.

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3-manifolds				

- (Schoen and Yau (1979)) Let M be a complete 3-dimensional Riemannian manifold with R^M > 0. If M contains a closed, two-sided, immersed, stable minimal hypersurface Σ, then the hypersurface must have genus 0. Moreover, any area-minimizing surface is homeomorphic to either S² or RP².
- (Fischer-Colbrie and Schoen (1980)) If $R^M \ge 0$, then the genus of Σ must be zero or one. Moreover, if the genus is one, then
 - (i) Σ is totally geodesic,
 - (ii) the normal Ric^M vanish all along Σ .

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۰	(Shen and Zhu (199 closed, two-sided, sta	7)) If $R^M \ge R$ able minimal s	$\mathcal{D}_0,$ then the area of an urface Σ with genus β	iy $eta eq 1,$

satisfies

$$\begin{cases} A(\Sigma) \leq 4\pi & \text{if } R_0 = 2 \text{ and } \beta = 0\\ A(\Sigma) \geq 4\pi(\beta - 1) & \text{if } R_0 = -2 \text{ and } \beta \geq 2. \end{cases}$$

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 - (Shen and Zhu (1997)) If $R^M \ge R_0$, then the area of any closed, two-sided, stable minimal surface Σ with genus $\beta \ne 1$, satisfies

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• (Bray, Brendle, Neves (2010)) If

$$\begin{cases} A(\Sigma) = 4\pi & \text{if } R_0 = 2 \text{ and } \beta = 0\\ A(\Sigma) = 4\pi(\beta - 1) & \text{if } R_0 = -2 \text{ and } \beta \ge 2, \end{cases}$$

then

(i) Σ is totally geodesic,
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 - (Shen and Zhu (1997)) If $R^M \ge R_0$, then the area of any closed, two-sided, stable minimal surface Σ with genus $\beta \ne 1$, satisfies

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then

(i) Σ is totally geodesic, (ii) the normal Ric^M vanishes along Σ . Moreover, if Σ is area-minimizing and $A(\Sigma) = 4\pi$, then M is isometric to $\mathbb{S}^2 \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

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Theorem 1 (Micallef and Moraru (2015))

Let M be a complete 3-dimensional Riemannian manifold with $R^M > R_0$. Assume that M contains a closed, two-sided, embedded, area-minimizing hypersurface Σ . (1) Suppose that $R_0 = 2$ and $A(\Sigma) = 4\pi$. Then Σ has $\beta = 0$ and it has a neighborhood which is isometric to the product $g_1 + dt^2$ on $\mathbb{S}^2 \times (-\epsilon, \epsilon)$. (2) Suppose that $R_0 = 0$ and Σ has $\beta = 1$. Then Σ has a neighborhood which is isometric to the product $g_0 + dt^2$ on $\mathbb{T}^2 \times (-\epsilon, \epsilon).$ (3) Suppose that $R_0 = -2$ and that Σ has $\beta \ge 2$ and $A(\Sigma) = 4\pi(\beta - 1)$. Then Σ has a neighborhood which is isometric to the product $g_{-1} + dt^2$ on $\Sigma \times (-\epsilon, \epsilon)$.

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Proof of Theorem 1. By second variation of area for minimal hypersurface, we have

$$0 \leq \int_{\Sigma} |\nabla^{\Sigma} \varphi|^2 - \varphi^2 \left(\operatorname{Ric}^{M}(N, N) + |B|^2 \right) d\operatorname{vol}_{\Sigma},$$

where ∇^{Σ} and $dvol_{\Sigma}$ are the gradient and the area element of Σ .

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Proof of Theorem 1. By second variation of area for minimal hypersurface, we have

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where ∇^{Σ} and $dvol_{\Sigma}$ are the gradient and the area element of Σ . Choosing $\varphi = 1$ and using Gauss equation, we obtain

$$\begin{array}{lll} 0 & \leq & \displaystyle \int_{\Sigma} - \frac{R^{M}}{2} + \mathcal{K}^{\Sigma} - \frac{|B|^{2}}{2} \mathit{dvol}_{\Sigma} \\ & \leq & \displaystyle - \frac{R_{0}}{2} \mathcal{A}(\Sigma) + \displaystyle \int_{\Sigma} \mathcal{K}^{\Sigma} \mathit{dvol}_{\Sigma}. \end{array}$$

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Proof of Theorem 1. By second variation of area for minimal hypersurface, we have

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where ∇^{Σ} and $dvol_{\Sigma}$ are the gradient and the area element of Σ . Choosing $\varphi = 1$ and using Gauss equation, we obtain

$$\begin{array}{lll} 0 & \leq & \displaystyle \int_{\Sigma} - \frac{R^{\mathcal{M}}}{2} + \mathcal{K}^{\Sigma} - \frac{|B|^2}{2} \textit{dvol}_{\Sigma} \\ & \leq & \displaystyle - \frac{R_0}{2} \mathcal{A}(\Sigma) + \int_{\Sigma} \mathcal{K}^{\Sigma} \textit{dvol}_{\Sigma}. \end{array}$$

By Gauss-Bonnet theorem, we get

$$R_0A(\Sigma) \leq 4\pi\chi(\Sigma) = 8\pi(1-\beta),$$

where $\chi(\Sigma)$ is the Euler characteristic of Σ .

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If $R_0A(\Sigma) = 8\pi(1-\beta)$, then every inequality above is in fact an equality. So we have Ric(N, N) = 0 and B = 0 on Σ .

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If $R_0A(\Sigma) = 8\pi(1-\beta)$, then every inequality above is in fact an equality. So we have Ric(N, N) = 0 and B = 0 on Σ . Then we can use Jacobi equation $L = \Delta_{\Sigma} + Ric^M + |B|^2$ to construct a constant mean curvature foliation in a neighborhood of Σ .

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If $R_0A(\Sigma) = 8\pi(1-\beta)$, then every inequality above is in fact an equality. So we have Ric(N, N) = 0 and B = 0 on Σ . Then we can use Jacobi equation $L = \Delta_{\Sigma} + Ric^M + |B|^2$ to construct a constant mean curvature foliation in a neighborhood of Σ .

(i)
$$R_0 = 2$$
 and $A(\Sigma) = 4\pi$,
(ii) $R_0 = 0$ and $\beta = 1$,
(iii) $R_0 = -2$, $\beta \ge 2$ and $A(\Sigma) = 4\pi(\beta - 1)$.
Using the Jacobi equation,We can show that a constant mean
curvature foliation is an area-minimizing surface in all cases.

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n-manifolds

• Einstein-Hilbert functional

$$Y(g) := \frac{\int_M R^M dvol}{Vol(M)^{(n-2)/n}}.$$

• Writting $\tilde{g} = u^{\frac{4}{n-2}}g$ for a positive function u on M, then

$$Y_{g}(u) = \frac{\int_{M} \left(\frac{4(n-1)}{n-2} |\nabla u|^{2} + R^{M} u^{2}\right) dvol}{\left(\int_{M} u^{2n/(n-2)} dvol\right)^{(n-2)/n}}$$

Yamabe invariant

$$Q_g(M) := \inf_{u>0} Y_g(u)$$

• σ -constant (or Yamabe constant)

$$\sigma(M) := \sup_{[g] \in \mathcal{C}} Q_g(M),$$

where C is the space of conformal classes on M.

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Remark 1

When n = 3 and $R_0 = -2$, then $\sigma(\Sigma) = 4\pi\chi(\Sigma) = 8\pi(1 - \beta)$, where $\chi(\Sigma)$ and β are the Euler characteristic and genus of Σ . i.e., in some sense, the σ -constant can be view as a generalisation of the Euler characteristic to higher dimensions.

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Remark 1

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Theorem 2 (Moraru (2016))

Let *M* be an *n*-dimensional Riemannian manifold $(n \ge 4)$ with $R^M \ge R_0$. Assume that Σ be a closed, two-sided, embedded, area-minimizing hypersurface.

(1) If $R_0 < 0$ and $\sigma(\Sigma) < 0$, then $R_0 A(\Sigma)^{\frac{2}{n-1}} \leq \sigma(\Sigma)$. Moreover, if equality holds, then M is isometric to $\Sigma \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

(2) If $R_0 = 0$ and $\sigma(\Sigma) \le 0$, then $\sigma(\Sigma) = 0$ and M is isometric to $\Sigma \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

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Proof of Theorem 2. By second variation of area for minimal hypersurface, we have

$$0 \leq \int_{\Sigma} |\nabla^{\Sigma} \varphi|^2 - \varphi^2 \left(\operatorname{Ric}^{M}(N, N) + |B|^2 \right) \operatorname{dvol}_{\Sigma},$$

where ∇^{Σ} and $dvol_{\Sigma}$ are the gradient and the area element of Σ .

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where ∇^{Σ} and $dvol_{\Sigma}$ are the gradient and the area element of Σ . From the Gauss equation, we obtain

$$\begin{array}{ll} 0 & \leq & \displaystyle \int_{\Sigma} 2 |\nabla^{\Sigma} \varphi|^{2} + (R^{\Sigma} - R^{M} - |B|^{2}) \varphi^{2} d\textit{vol}_{\Sigma} \\ & \leq & \displaystyle \int_{\Sigma} \left(\frac{4(n-2)}{n-3} |\nabla^{\Sigma} \varphi|^{2} + R^{\Sigma} \varphi^{2} \right) d\textit{vol}_{\Sigma} - \int_{\Sigma} R^{M} \varphi^{2} d\textit{vol}_{\Sigma}, \end{array}$$

where in the last inequality we have used that $2 < \frac{4(n-2)}{n-3}$ for all $n \ge 4$.

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where in the last inequality we have used that $2 < \frac{4(n-2)}{n-3}$ for all $n \ge 4$. By the assumption $R^M \ge R_0$ and hence, by Holder inequality, the above inequality gives

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$$\begin{array}{ll} 0 & \leq & \displaystyle \int_{\Sigma} \left(\frac{4(n-2)}{n-3} |\nabla^{\Sigma} \varphi|^2 + R^{\Sigma} \varphi^2 \right) d\textit{vol}_{\Sigma} \\ & & \displaystyle -R_0 A(\Sigma)^{\frac{2}{n-1}} \left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} d\textit{vol}_{\Sigma} \right)^{\frac{n-3}{n-1}}. \end{array}$$

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$$0 \leq \int_{\Sigma} \left(\frac{4(n-2)}{n-3} |\nabla^{\Sigma} \varphi|^{2} + R^{\Sigma} \varphi^{2} \right) dvol_{\Sigma} \\ -R_{0} A(\Sigma)^{\frac{2}{n-1}} \left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} dvol_{\Sigma} \right)^{\frac{n-3}{n-1}}.$$

Dividing the last inequality by $\left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} dvol_{\Sigma}\right)^{\frac{n-3}{n-1}} > 0$, we get

$$R_0 A(\Sigma)^{\frac{2}{n-1}} \leq \frac{\int_{\Sigma} \left(\frac{4(n-2)}{n-3} |\nabla^{\Sigma} \varphi|^2 + R^{\Sigma} \varphi^2\right) dvol_{\Sigma}}{\left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} dvol_{\Sigma}\right)^{\frac{n-3}{n-1}}}.$$

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$$0 \leq \int_{\Sigma} \left(\frac{4(n-2)}{n-3} |\nabla^{\Sigma} \varphi|^{2} + R^{\Sigma} \varphi^{2} \right) dvol_{\Sigma} \\ -R_{0}A(\Sigma)^{\frac{2}{n-1}} \left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} dvol_{\Sigma} \right)^{\frac{n-3}{n-1}}.$$

Dividing the last inequality by $\left(\int_{\Sigma} \varphi^{\frac{2(n-1)}{n-3}} dvol_{\Sigma}\right)^{\frac{n-3}{n-1}} > 0$, we get

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Therefore,

$$R_0A(\Sigma)^{\frac{2}{n-1}} \leq \sigma(\Sigma).$$

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Remark 2

Let $\Sigma := \mathbb{S}^{n-2} \times \mathbb{S}^1(\ell)$, where \mathbb{S}^{n-2} is the (n-2)-dimensional unit sphere and $S^1(\ell)$ is the circle of radius ℓ . Let $M := \Sigma \times \mathbb{S}^1$ with the product metric. Then $R^M = (n-2)(n-3) := R_0^+ > 0$ and $\sigma(\Sigma) = \sigma(\mathbb{S}^{n-1})$. That is, $\sigma(\Sigma)$ is independent of both R_0^+ and ℓ . Therefore, the area of Σ is arbitrarily large when ℓ increases.

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• (Mendes (2019)) Let M^5 be a Riemannian manifold with $R^M \ge R_0 > 0$ and $Ric^M \ge 0$. If Σ^4 is a two-sided, closed, embedded, area-minimizing hypersurface, then

$$A(\Sigma)\left(rac{R_0}{12}
ight)^2 \leq A(\mathbb{S}^4) + rac{1}{12}\int_{\Sigma}|\mathring{
m {\it Ric}}|^2 d{\it vol}_{\Sigma},$$

where Ric is the traceless Ricci curvature. If equality holds, then M is isometric to $\mathbb{S}^4 \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

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• Gauss-Bonnet-Chern formula: When n = 5

$$8\pi\chi(\Sigma) = \int_{\Sigma} \left(\frac{1}{4}|W^{\Sigma}|^2 + \frac{1}{24}|R^{\Sigma}|^2 - \frac{1}{2}|\mathring{Ric}^{\Sigma}|^2\right) dvol_{\Sigma},$$

where W^{Σ} and \mathring{Ric} are the Weyl and the traceless Ricci tensor of Σ .

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where W^{Σ} and \mathring{Ric} are the Weyl and the traceless Ricci tensor of Σ .

• (Deng (2021)) Let M be an n-dimensional Riemannian manifold $(n \ge 4)$ with $R^M \ge R_0 > 0$ and $Ric^M \ge 0$. If Σ^{n-1} is a two-sided, closed, embedded, area-minimizing hypersurface with $Ric^{\Sigma} = \frac{R^{\Sigma}}{n}g_{\Sigma}$, then

$$A(\Sigma)^{\frac{2}{n}}R_0 \leq n(n-1)A(\mathbb{S}^{n-1})^{\frac{2}{n}}.$$

If the equality holds, then M is isometric to $\mathbb{S}^{n-1} \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

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• Gauss-Bonnet-Chern formula: When n = 5

$$8\pi\chi(\Sigma) = \int_{\Sigma} \left(\frac{1}{4}|W^{\Sigma}|^2 + \frac{1}{24}|R^{\Sigma}|^2 - \frac{1}{2}|\mathring{Ric}^{\Sigma}|^2\right) dvol_{\Sigma},$$

where W^{Σ} and \mathring{Ric} are the Weyl and the traceless Ricci tensor of Σ .

• (Deng (2021)) Let M be an n-dimensional Riemannian manifold $(n \ge 4)$ with $R^M \ge R_0 > 0$ and $Ric^M \ge 0$. If Σ^{n-1} is a two-sided, closed, embedded, area-minimizing hypersurface with $Ric^{\Sigma} = \frac{R^{\Sigma}}{n}g_{\Sigma}$, then

$$A(\Sigma)^{\frac{2}{n}}R_0 \leq n(n-1)A(\mathbb{S}^{n-1})^{\frac{2}{n}}.$$

If the equality holds, then M is isometric to $\mathbb{S}^{n-1} \times (-\epsilon, \epsilon)$ in a neighborhood of Σ .

The author assumed that the Σ is Einstein.

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$$(M, g, e^{-f} dv_g)$$
, where $f \in C^{\infty}(M)$.

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$$(M, g, e^{-f} dv_g)$$
, where $f \in C^{\infty}(M)$.

• Example of a weighted manifolds (Gaussian soliton) $(\mathbb{R}^n, g_0, e^{-\frac{1}{4}|x|^2} dv_{g_0}),$

where g_0 is the standard Euclidean metric on \mathbb{R}^n .

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$$(M, g, e^{-f} dv_g)$$
, where $f \in C^{\infty}(M)$.

• Example of a weighted manifolds (Gaussian soliton) $(\mathbb{R}^{n}, g_{0}, e^{-\frac{1}{4}|x|^{2}} dv_{g_{0}}),$

where g_0 is the standard Euclidean metric on \mathbb{R}^n . • Bakry-Emery Ricci tensor

$$\begin{cases} \operatorname{Ric}_{f}^{m} := \operatorname{Ric} + \operatorname{Hess} f - \frac{1}{m} df \otimes df, \\ \operatorname{Ric}_{f} := \operatorname{Ric} + \operatorname{Hess} f. \end{cases}$$

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$$(M, g, e^{-f} dv_g)$$
, where $f \in C^{\infty}(M)$.

• Example of a weighted manifolds (Gaussian soliton) $(\mathbb{R}^{n}, g_{0}, e^{-\frac{1}{4}|x|^{2}} dv_{g_{0}}),$

where g_0 is the standard Euclidean metric on \mathbb{R}^n .

• Bakry-Emery Ricci tensor

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• Weighted scalar curvature

$$\begin{cases} R_f^m := R^M + 2\Delta f - \frac{m+1}{m} |\nabla f|^2, \\ R_f := R^M + 2\Delta f - |\nabla f|^2. \end{cases}$$

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• Weighted mean curvature

$$H_f := H - \langle \nabla f, N \rangle.$$

• Weighted Laplacian

$$\Delta_f := \Delta - \langle \nabla f, \nabla \rangle.$$

• Weighted area

$$A_f(\Sigma) := \int_{\Sigma} e^{-f} dvol.$$

• First variation for weighted area

$$\left. \frac{d}{ds} \right|_{s=0} A_f(\Sigma_s) = \int_{\Sigma} \varphi H_f \ e^{-f} dvol.$$

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• Second variation for weighted area

$$\frac{d^2}{ds^2}\Big|_{s=0} A_f(\Sigma_s) = \int_{\Sigma} |\nabla^{\Sigma}\varphi|^2 -\varphi^2 \left(\operatorname{Ric}_f(N,N) + |B|^2 \right) e^{-f} dvol$$

• Weighted stable minimal hypersurface (or *f*-stable minimal hypersurface)

$$\frac{d^2}{ds^2}\Big|_{s=0} A_f(\Sigma_s) \ge 0.$$

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Theorem 3 (M. Fan (2008))

Let M be a complete 3-dimensional weighted Riemannian manifold with $R_f \ge C_0$ for some positive constant C_0 . If M contains closed, two-sided, immersed, f-stable minimal hypersurfaces Σ , then the genus of Σ is zero.

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Theorem 4 (Castro and Rosales (2014))

Let M be a complete 3-dimensional weighted Riemannian manifold with $R_f \geq C_0 e^{-f}$. Consider a closed, two-sided, embedded, f-area minimizing hypersurface Σ . (1) If $C_0 < 0$ and $A_f(\Sigma) = \frac{8\pi(1-\beta)}{C_0}$ for $\beta \ge 2$, then there is a neighborhood of Σ in M which is isometric to a Riemannian product $\Sigma \times (-\epsilon, \epsilon)$. (2) If $C_0 = 0$ and $\beta = 1$, then Σ is a flat torus and there is a neighborhood of Σ in M which is isometric to a Riemannian product $\Sigma \times (-\epsilon, \epsilon)$. (3) If $C_0 > 0$ and $A_f(\Sigma) = \frac{8\pi}{C_0}$, then $\beta = 0$ and there is a neighborhood of Σ in *M* isometric to a Riemannian product $\Sigma \times (-\epsilon, \epsilon).$

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Remark 3

If we replace R_f to R_f^m , then we can get similar results.

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Theorem 5 (Lee, Park, and Pyo (2022))

Let M be a complete *n*-dimensional weighted Riemannian manifold $(n \ge 4)$ with $R_f^m \ge C_0 e^{-\frac{2f}{n-1}}$ for $m \in (0, \frac{1}{n-3}]$. Assume that M contains an (n-1)-dimensional, closed, two-sided, embedded, *f*-area minimizing hypersurface Σ . (1) If $C_0 < 0$ and $\sigma(\Sigma) < 0$, then we have

$$C_0A_f(\Sigma)^{\frac{2}{n-1}} \leq \sigma(\Sigma).$$

Moreover, if equality holds, then M splits isometrically as a product in a neighborhood of Σ .

(2) If $C_0 = 0$ and $\sigma(\Sigma) \le 0$, then $\sigma(\Sigma) = 0$ and M splits isometrically as a product in a neighborhood of Σ .

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Theorem 6 (Lee, Park, and Pyo (2022))

Let M be a complete *n*-dimensional weighted Riemannian manifold $(n \ge 4)$. If $R_f^m \ge C_0^+$ for some positive constant C_0^+ , then there is no (n-1)-dimensional, closed, two-sided, immersed, *f*-stable hypersurface Σ with $\sigma(\Sigma) \le 0$.

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Theorem 6 (Lee, Park, and Pyo (2022))

Let M be a complete *n*-dimensional weighted Riemannian manifold $(n \ge 4)$. If $R_f^m \ge C_0^+$ for some positive constant C_0^+ , then there is no (n-1)-dimensional, closed, two-sided, immersed, *f*-stable hypersurface Σ with $\sigma(\Sigma) \le 0$.

Remark 4

If we change R_f^m to R_f , then we can get same result.

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Thank you!

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