

How does PDE order affect the convergence of PINNs?

Changhoon Song, Yesom Park, Myungjoo Kang

24.11.06

Contents

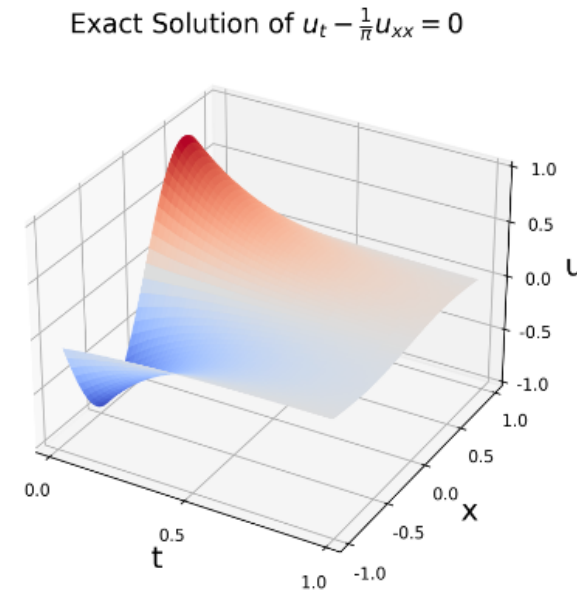
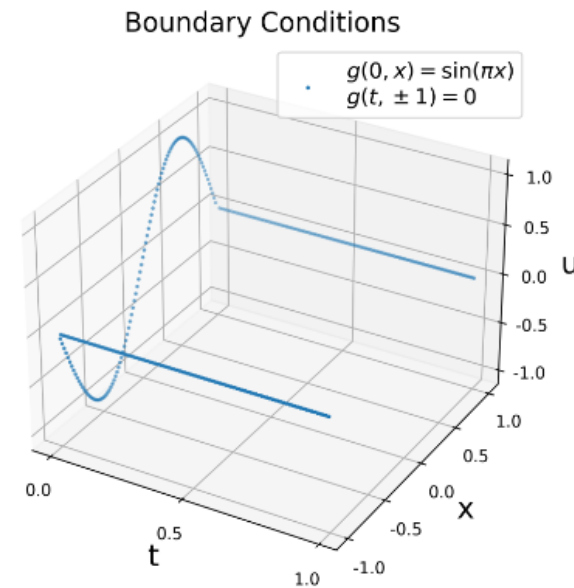
- I. Introduction of physics-informed neural network (PINNs)
- II. Convergence of PINNs
- III. Width condition for PINNs to converge
- IV. Reduction of PDE order enhance the condition

Partial Differential Equations

A partial differential equation(PDE) is an equation that computes a function between various partial derivatives of a multivariate function.

Examples:

- $\frac{\partial^2}{\partial x^2} u(x, y) + \frac{\partial^2}{\partial y^2} u(x, y) = 0.$
- $\frac{\partial}{\partial t} u(t, x) - \frac{\partial^2}{\partial x^2} u(t, x) = 0.$



Physics-Informed Neural Networks

A neural network u_θ is a solution of PDE if it satisfies

$$\begin{cases} \mathcal{N} [u_\theta, Du_\theta, D^2 u_\theta] (\mathbf{x}) = f (\mathbf{x}), & \mathbf{x} \in \Omega, \\ u_\theta (\mathbf{x}) = g (\mathbf{x}), & \mathbf{x} \in \partial\Omega, \end{cases}$$

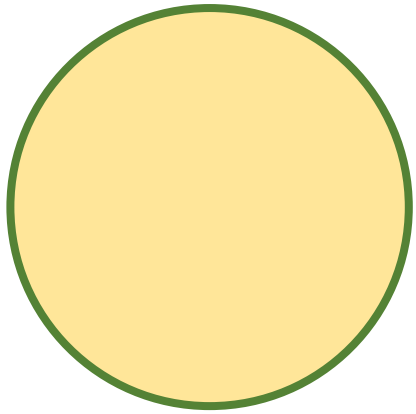
Physics-Informed Neural Networks (PINNs) [DPT94, RPK19]

PINNs learn a solution by minimizing the residual of the PDE:

$$\mathcal{L} (u_\theta) := \|\mathcal{N} [u_\theta] - f\|_{L^2(\Omega)} + \|u_\theta - g\|_{L^2(\partial\Omega)}.$$

Physics-Informed Neural Networks

Theoretical Setting



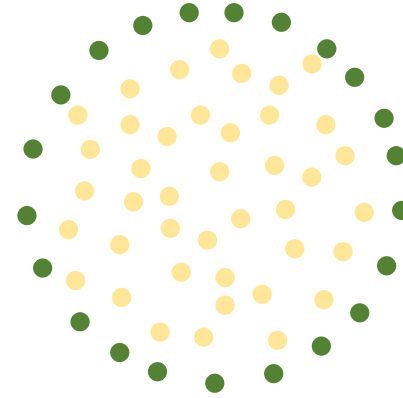
$$\mathcal{N}[u_\theta] = f, \quad x \in \Omega$$

$$\mathcal{B}[u_\theta] = g, \quad x \in \partial\Omega$$

$$\mathcal{L}(u_\theta) = \|\mathcal{N}[u_\theta] - f\|_{L^2(\Omega)} + \|\mathcal{B}[u_\theta] - g\|_{L^2(\partial\Omega)}$$

$$\theta = \arg \min_{\theta} \mathcal{L}(u_\theta)$$

Practical Setting



$$\mathcal{N}[u_\theta](x_i) = f(x_i), \quad x_i \in \Omega$$

$$\mathcal{B}[u_\theta](\tilde{x}_j) = g(\tilde{x}_j), \quad \tilde{x}_j \in \partial\Omega$$

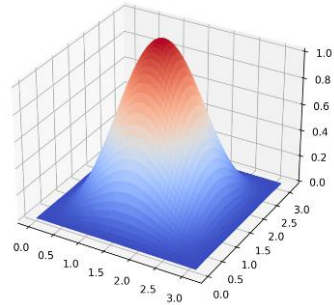
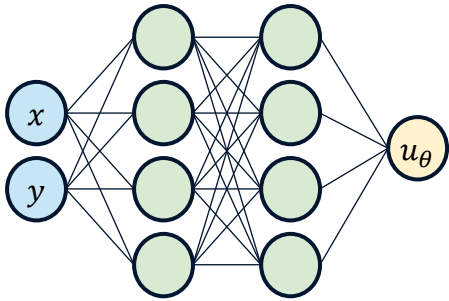
$$\mathcal{L}(u_\theta) = \sum_i (\mathcal{N}[u_\theta](x_i) - f(x_i))^2 + \sum_j (\mathcal{B}[u_\theta](\tilde{x}_j) - g(\tilde{x}_j))^2$$

$$\theta(t+1) = \theta(t) - \eta \nabla \mathcal{L}(u_{\theta(t)})$$

$$\dot{\theta}(t) = -\nabla \mathcal{L}(u_{\theta(t)})$$

Convergence of PINNs

Network \approx Exact sol.

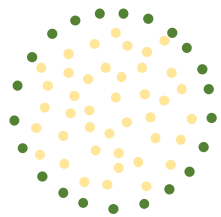
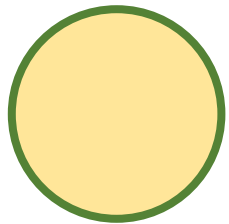


Minimize residual \approx Minimize error

$$\mathcal{L}(u_\theta) = \|\mathcal{N}[u_\theta] - f\|_{L^2(\Omega)} + \|\mathcal{B}[u_\theta] - g\|_{L^2(\partial\Omega)}$$
$$\theta = \arg \min_{\theta} \mathcal{L}(u_\theta)$$

$$\|u_\theta - u^*\| \leq C\mathcal{L}(u_\theta)$$

Expected residual \approx Sampled residual



$$\mathcal{L}(u_\theta) = \|\mathcal{N}[u_\theta] - f\|_{L^2(\Omega)} + \|\mathcal{B}[u_\theta] - g\|_{L^2(\partial\Omega)}$$

$$\mathcal{L}(u_\theta) = \sum_i (\mathcal{N}[u_\theta](x_i) - f(x_i))^2 + \sum_j (\mathcal{B}[u_\theta](\tilde{x}_j) - g(\tilde{x}_j))^2$$

Training result \approx Loss minimizer

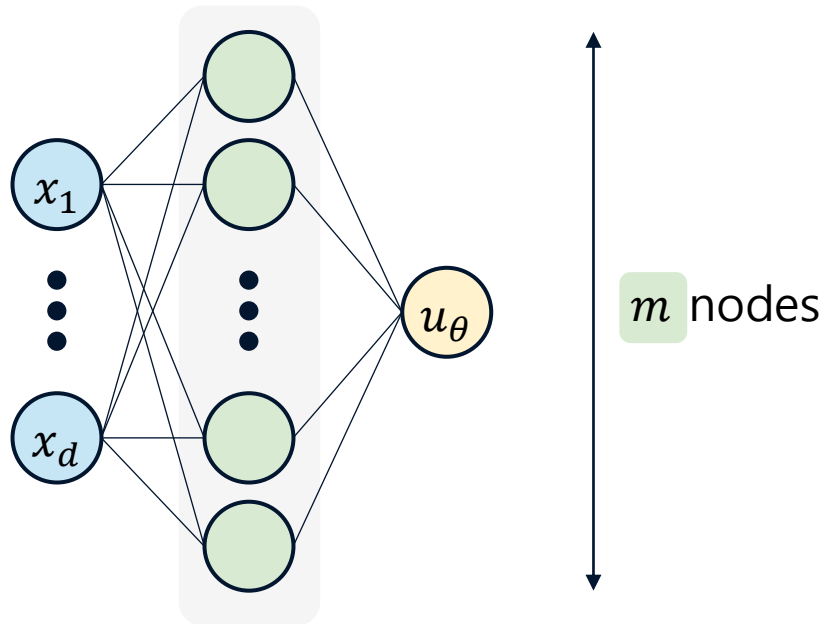
$$\theta(t+1) = \theta(t) - \eta \nabla \mathcal{L}(u_{\theta(t)})$$

$$\dot{\theta}(t) = -\nabla \mathcal{L}(u_{\theta(t)})$$

$$\lim_{t \rightarrow \infty} \theta(t)$$

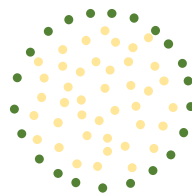
$$\theta = \arg \min_{\theta} \mathcal{L}(u_\theta)$$

Training Convergence of PINNs



$$u_\theta = \frac{1}{\sqrt{m}} \sum_{r=1}^m a_r \sigma(W_{ij} x_j + b_i)$$

$$\sigma(x) = \max\{0, x\}^p$$



$$\mathcal{N}[u_\theta](x_i) = f(x_i), \quad x_i \in \Omega$$

$$u_\theta(\tilde{x}_j) = g(\tilde{x}_j), \quad \tilde{x}_j \in \partial\Omega$$

$$\mathcal{N}[u] = \sum_{|\alpha| \leq k} a_\alpha(x) \frac{\partial^\alpha u(x)}{\partial x^\alpha}, \quad \mathcal{B}[u] = \sum_{|\alpha| \leq 1} \tilde{a}_\alpha(x) \frac{\partial^\alpha u(x)}{\partial x^\alpha}$$

$$\mathcal{L}(u_\theta) = \sum_i (\mathcal{N}[u_\theta](x_i) - f(x_i))^2 + \sum_j (\mathcal{B}[u_\theta](\tilde{x}_j) - g(\tilde{x}_j))^2$$

Theorem (Brief)

$$m = \Omega \left(\log \frac{m}{\delta} \right)^{4p} \implies P \left(\lim_{t \rightarrow \infty} \mathcal{L}(u(t)) = 0 \right) \geq 1 - \delta.$$

Main result 1

Theorem (Special Case)

There exists a constant C , independent of d , k , and p , such that for any $\delta \ll 1$, if

$$m > C \binom{d+k}{d}^{14} p^{7k+4} 2^{6p} \left(\log \frac{md}{\delta} \right)^{4p}$$

then with probability of at least $1 - \delta$ over the initialization, we have

$$\mathcal{L}_{PINN}(\mathbf{w}(t), \mathbf{v}(t)) \leq \exp(-\lambda_0 t) \mathcal{L}_{PINN}(\mathbf{w}(0), \mathbf{v}(0)), \quad \forall t \geq 0.$$

Main result 1

Theorem (Special Case)

There exists a constant C , independent of d , k , and p , such that for any $\delta \ll 1$, if

$$\boxed{m} \underset{\text{Width}}{>} C \binom{d+k}{d}^{14} p^{\boxed{k}+4} \overset{\text{PDE order}}{2^{6p}} \left(\log \frac{md}{\delta} \right)^{4p}$$

then with probability of at least $1 - \delta$ over the initialization, we have

$$\boxed{\mathcal{L}_{PINN}(\mathbf{w}(t), \mathbf{v}(t))} \leq \exp(-\lambda_0 t) \boxed{\mathcal{L}_{PINN}(\mathbf{w}(0), \mathbf{v}(0))}, \quad \forall t \geq 0.$$

Loss at time t

Initial loss

- Higher k and p requires exponentially wide width.
- $p = k + 1$ is optimal order for RePU, since $p \geq k + 1$.

Main result 1

Theorem (Special Case)

There exists a constant C , independent of d , k , and p , such that for any $\delta \ll 1$, if

$$\boxed{m} > C \binom{d+k}{d}^{14} \boxed{p}^{7k+4} 2^{6\boxed{p}} \left(\log \frac{md}{\delta} \right)^{4\boxed{p}}$$

Width ReLU power

then with probability of at least $1 - \delta$ over the initialization, we have

$$\boxed{\mathcal{L}_{PINN}(\mathbf{w}(t), \mathbf{v}(t))} \leq \exp(-\lambda_0 t) \boxed{\mathcal{L}_{PINN}(\mathbf{w}(0), \mathbf{v}(0))}, \quad \forall t \geq 0.$$

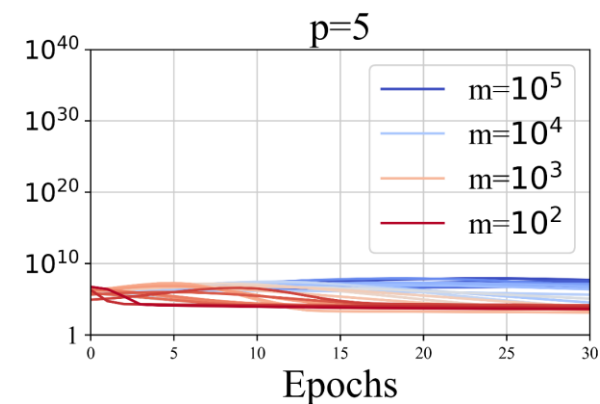
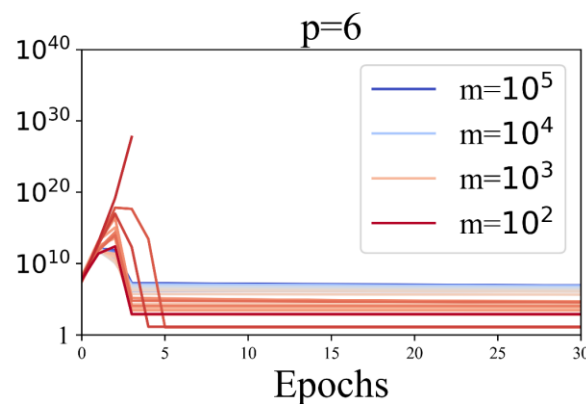
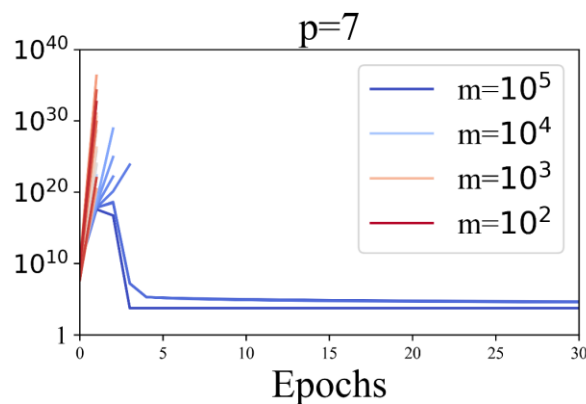
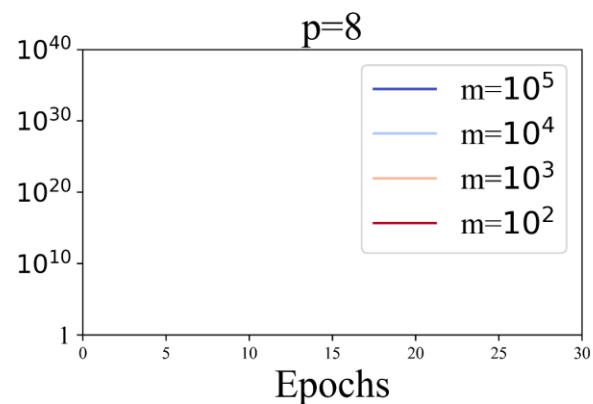
Loss at time t

Initial loss

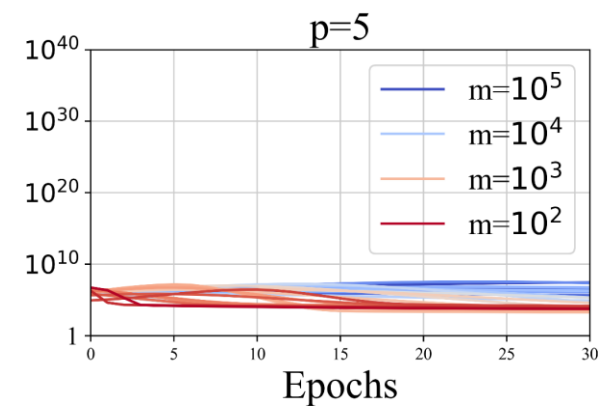
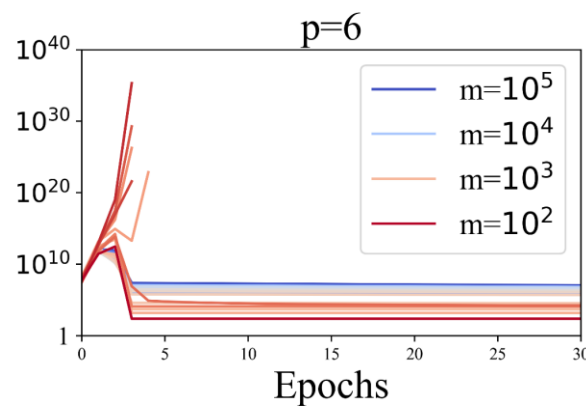
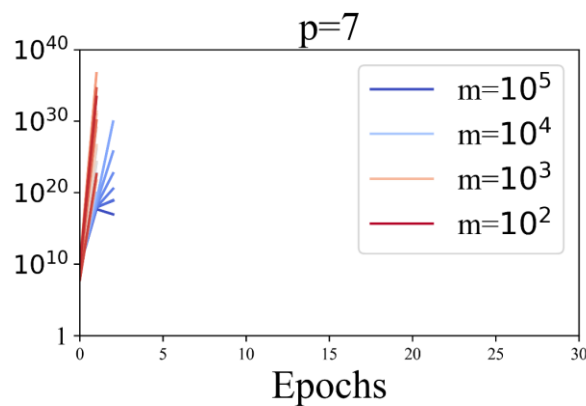
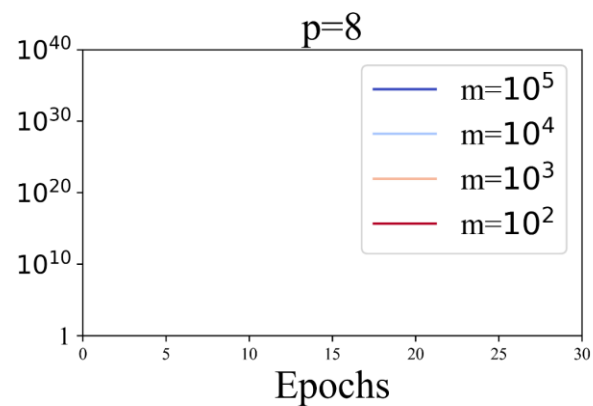
- Higher k and p requires exponentially wide width.
- $p = k + 1$ is optimal order for RePU, since $p \geq k + 1$.

Experiment 1

Harmonic equation: $u_{xx} + u_{yy} = f_1$



Biharmonic equation: $u_{xxxx} + 2u_{xxyy} + u_{yyyy} = f_2$



Variable Splitting

Higher-order PDEs

$$\Delta u = f$$

primary variable

$$u_t - u_{xx} = f$$



System of lower-order PDEs

$$\begin{cases} \nabla \cdot \mathbf{V} = f \\ \mathbf{V} = \nabla u \end{cases}$$

Auxiliary variable

$$\begin{cases} u_t - v_x = f \\ v = u_x \end{cases}$$

Auxiliary variable

Variable Splitting

Higher-order PDEs

$$\begin{cases} \mathcal{N}[u](\mathbf{x}) = f(\mathbf{x}), \\ \mathcal{B}[u](\mathbf{x}) = g(\mathbf{x}), \end{cases}$$

$$\mathcal{N}[u] = \sum_{|\alpha| \leq k} a_\alpha \frac{\partial^\alpha}{\partial \mathbf{x}^\alpha} u$$

System of lower-order PDEs

$$\begin{cases} \hat{\mathcal{N}}[\phi_0, \dots, \phi_L](\mathbf{x}) = f(\mathbf{x}), \\ \frac{\partial^\beta}{\partial \mathbf{x}^\beta} (\phi_{\ell-1})_\alpha(\mathbf{x}) = (\phi_\ell)_{\alpha+\beta}(\mathbf{x}) \\ \mathcal{B}[\phi_0](\mathbf{x}) = g, \end{cases}$$

$$\mathcal{N}[u] = \sum_{\ell} \sum_{|\alpha| \leq \xi_\ell} \sum_{|\beta| \leq \Delta \xi_{\ell+1}} \hat{a}_{\ell, \alpha, \beta} \frac{\partial^{\Delta \xi_{\ell+1}}}{\partial \mathbf{x}^\beta} (\phi_\ell)_\alpha$$

$$0 = \xi_0 \leq \xi_1 \leq \dots \leq \xi_{L+1} = k$$

$$\Delta \xi_\ell = \xi_{\ell+1} - \xi_\ell$$

Main result 2

Theorem (General Case)

There exists a constant C , independent of d , k , $|\xi|$, and p , such that for any $\delta \ll 1$, if

$$m > C \binom{d+k}{d}^6 \binom{d+|\xi|}{d}^8 p^{7|\xi|+4} 2^{6p} \left(\log \frac{md}{\delta} \right)^{4p},$$

$|\xi| = \max \Delta \xi_\ell$

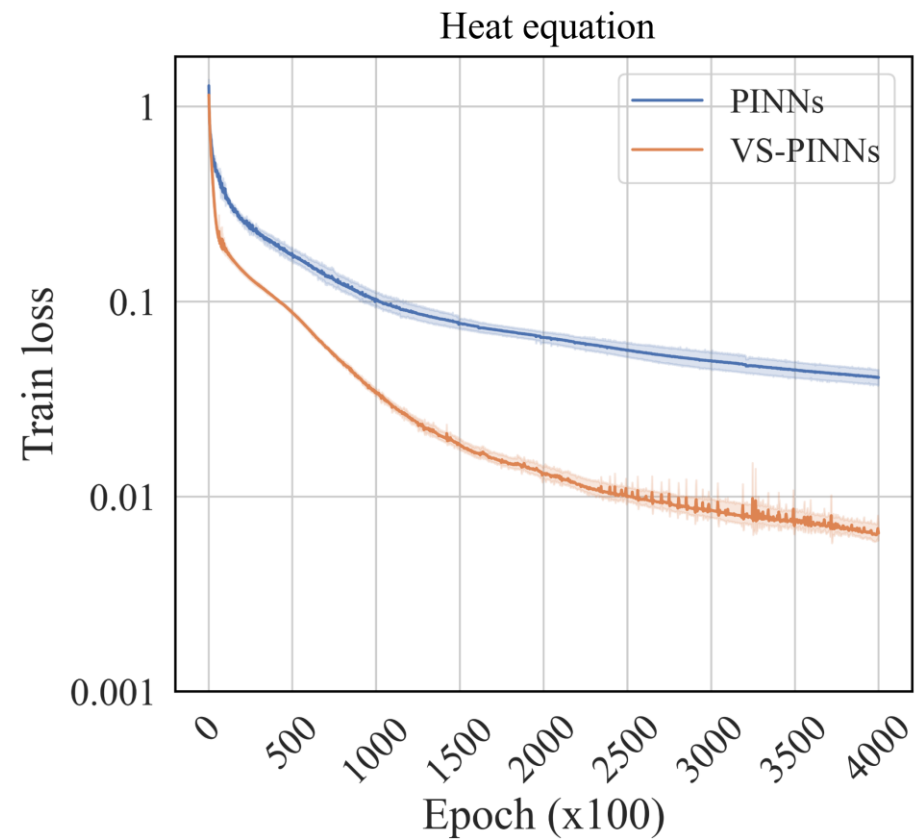
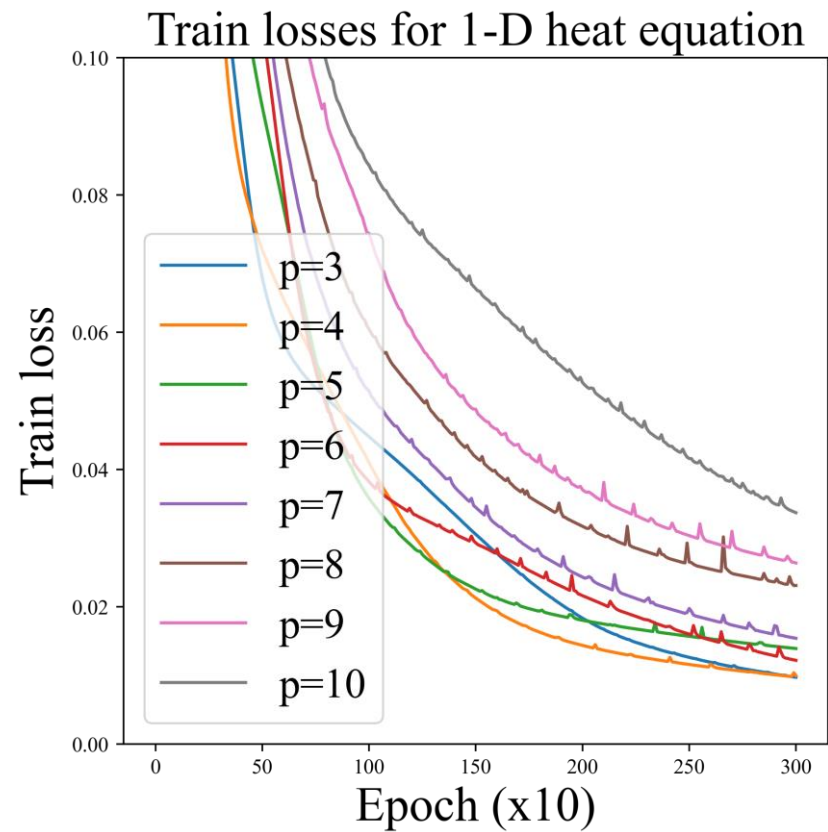
then with probability of at least $1 - \delta$ over the initialization, we have

$$\mathcal{L}_{PINN}^{VS}(\mathbf{w}(t), \mathbf{v}(t)) \leq \exp(-\lambda_0 t) \mathcal{L}_{PINN}^{VS}(\mathbf{w}(0), \mathbf{v}(0)), \quad \forall t \geq 0.$$

- Lower $|\xi|$ reduces width requirement.
- $p = |\xi| + 1$ is optimal order for RePU.

Experiment 2

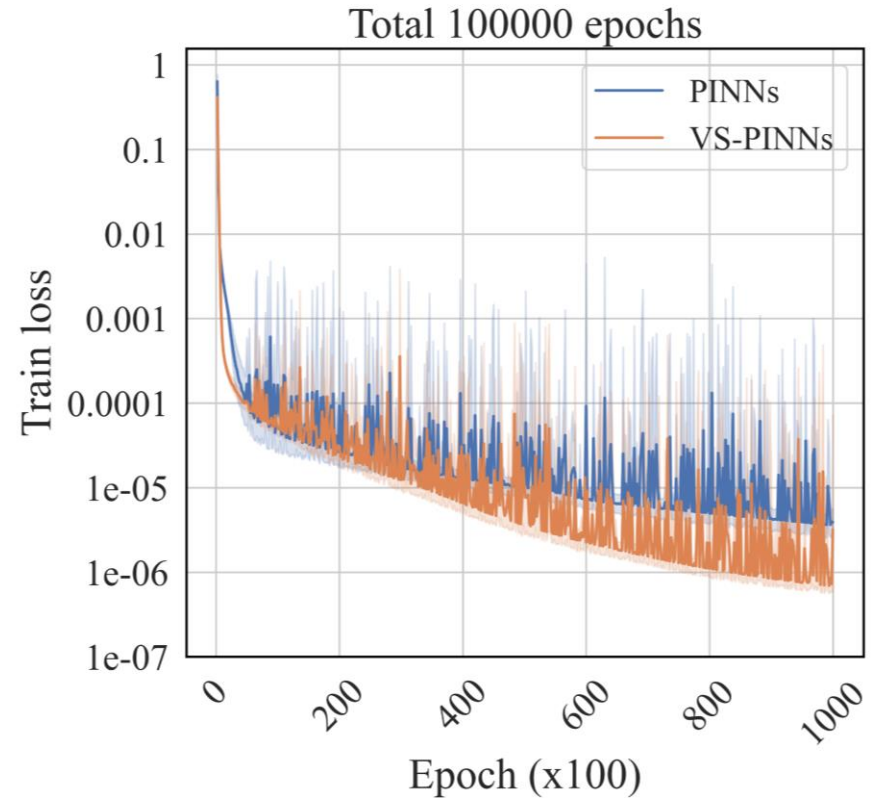
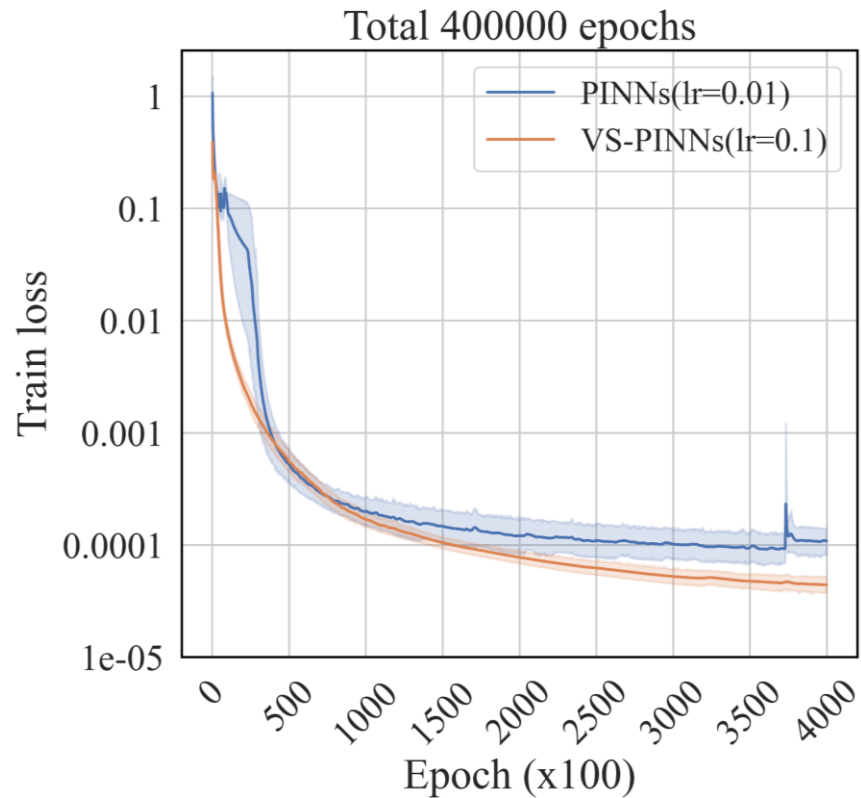
Heat equation
$$\begin{cases} u_t = u_{xx} \\ u(t, -1) = u(t, 1) = 0 \\ u(0, x) = \sin(\pi x) \end{cases}$$



Experiment 3

Convection-Diffusion equation

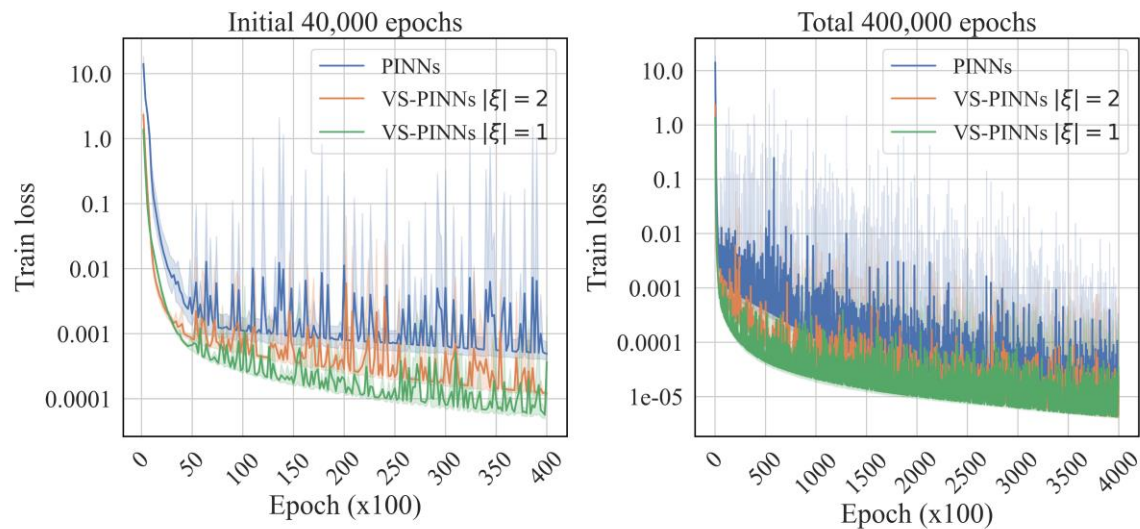
$$\begin{cases} u_t + u_x - \frac{1}{4}u_{xx} = 0 \\ u(0, x) = \sin(x) \\ u(t, 0) = -e^{-\frac{1}{4}t} \sin(t) \\ u(t, \pi) = e^{-\frac{1}{4}t} \sin(\pi - t) \end{cases}$$



Experiment 4

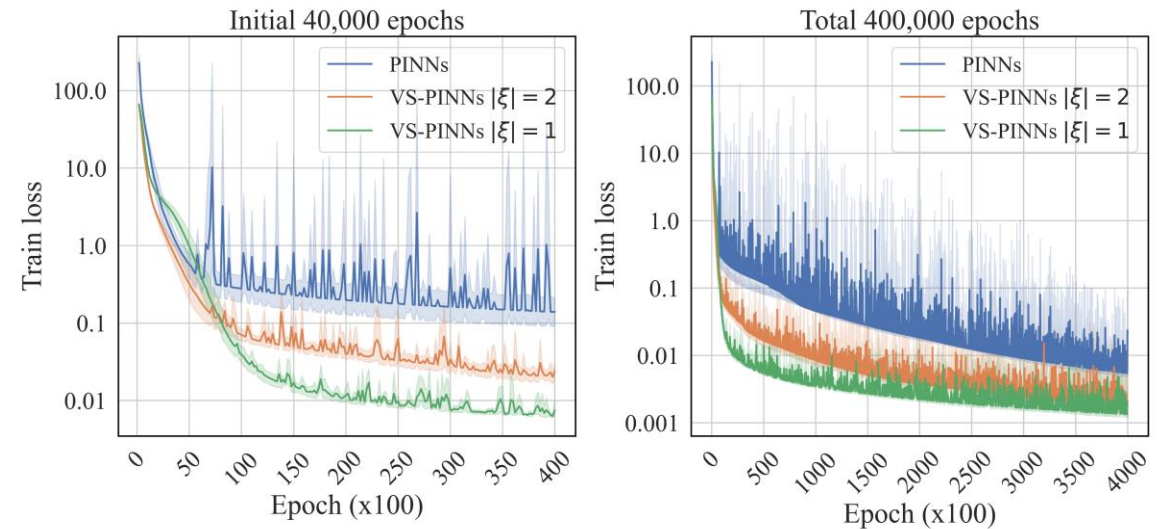
Elastic beam equation

$$\begin{cases} u_t + u_{xxxx} = 0 \\ u(t, 0) = u(t, \pi) = u_{xx}(t, 0) = u_{xx}(t, \pi) = 0 \\ u(0, x) = 2 \sin(x) \end{cases}$$



Bi-harmonic equation

$$\begin{cases} u_{xxxx} + 2u_{xxyy} + u_{yyyy} = f_2 \\ u(x, 0) = u(x, \pi) = u(0, y) = u(\pi, y) = 0 \\ \frac{\partial}{\partial \mathbf{n}} u(x, 0) = \frac{\partial}{\partial \mathbf{n}} u(x, \pi) = \frac{\partial}{\partial \mathbf{n}} u(0, y) = \frac{\partial}{\partial \mathbf{n}} u(\pi, y) = 0 \end{cases}$$



Computational cost

PDE	Method	GPU memory	running time	parameters
Bi-harmonic	PINN	801.052 Mb	0.053 s/epoch	4000
	VS-PINN $ \xi = 2$	481.094 Mb	0.049 s/epoch	9000
	VS-PINN $ \xi = 1$	81,466 Mb	0.053 s/epoch	20000
Beam	PINN	323.772 Mb	0.037 s/epoch	4000
	VS-PINN $ \xi = 2$	240.689 Mb	0.038 s/epoch	9000
	VS-PINN $ \xi = 1$	80.836 Mb	0.040 s/epoch	17000

- Auxiliary variables need additional models.
- Reducing the number of differentiation in loss is more critical.

Sketch of Proofs

① $\lambda_0 > 0$

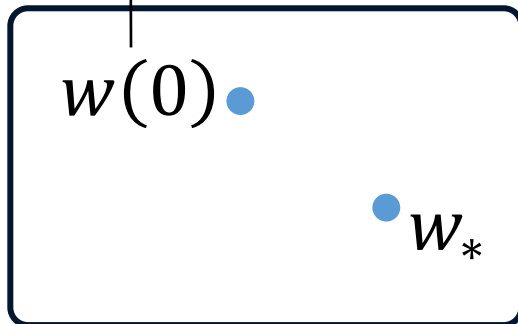
$$G^\infty$$

\approx

③ Small t

$$G(0) \approx G(t)$$

② Large m



Proposition

$\mathbf{G}_v^\infty = \mathbb{E}_{\mathbf{w}, \mathbf{v}} [\mathbf{G}_v(\mathbf{w}, \mathbf{v})]$ is strictly positive definite and independent of m .

Proposition

For $\delta > 0$ and some constant N_1, C_1 and R , if m is large enough so that

$$m \geq \frac{32N_1C_1^2R^{4p}}{\lambda_0^2} \log\left(\frac{2N_1}{\delta}\right),$$

then with the probability of at least $1 - \delta$ over the initialization, we have

$$\|\mathbf{G}_v(\mathbf{w}(0), \mathbf{v}(0)) - \mathbf{G}_v^\infty\|_2 < \frac{\lambda_0}{4}.$$

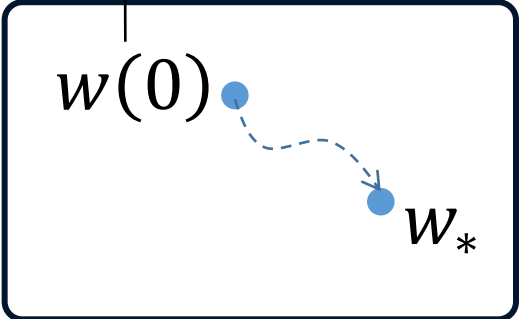
Sketch of Proofs

$$\frac{d}{dt}u(t) = G(t)(y - u(t))$$

$$\frac{d}{dt}w_r(t) = -\frac{\partial}{\partial w_r} \|u(t) - y\|_2^2$$

① $\lambda_0 > 0$
 G^∞
 \gg
③ Small t
 $G(0) \approx G(t) \xrightarrow{\text{④ } \lambda_0(t) > \frac{1}{2}\lambda_0} \|u(t) - y\|_2 \leq \exp(-\lambda_0 t) \|u(0) - y\|$ ⑤ Fast decrease $u(t)$

② Large m



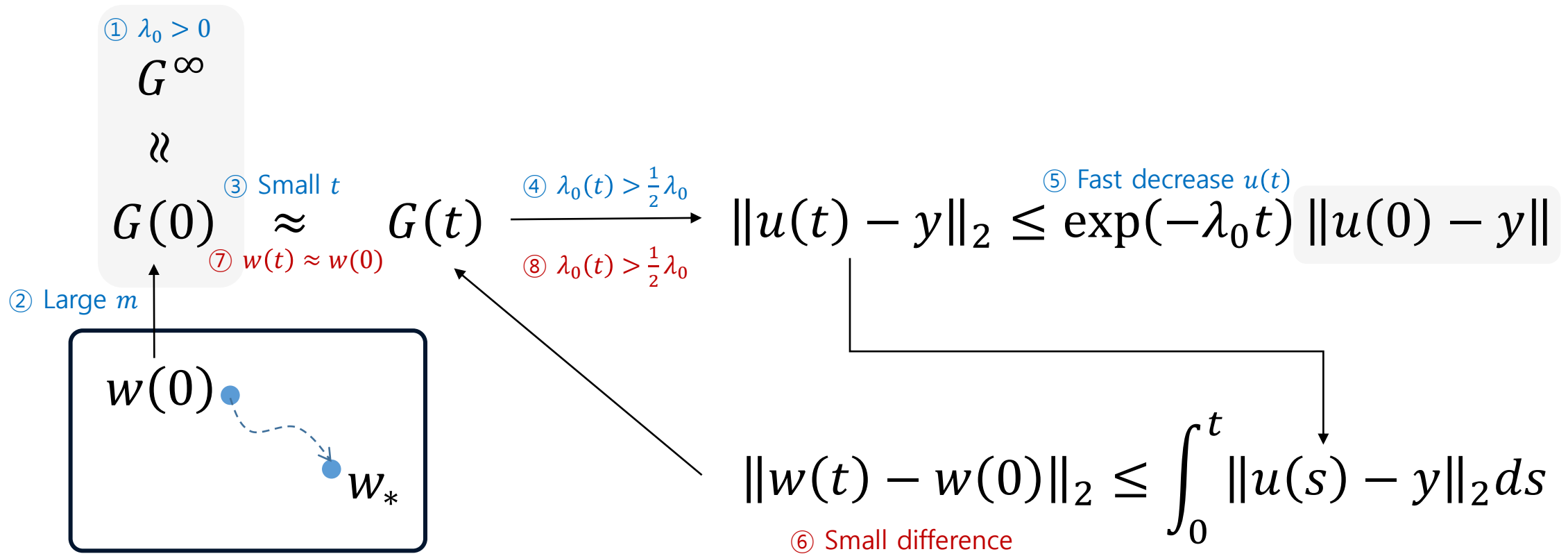
The diagram shows a box containing a point $w(0)$ and a point w_* . A dashed blue arrow points from $w(0)$ towards w_* , indicating the direction of the gradient descent process.

$$\|w(t) - w(0)\|_2 \leq \int_0^t \|u(s) - y\|_2 ds$$

Sketch of Proofs

$$\frac{d}{dt}u(t) = G(t)(y - u(t))$$

$$\frac{d}{dt}w_r(t) = -\frac{\partial}{\partial w_r} \|u(t) - y\|_2^2$$



Thank you