

Analytic and numerical methods for active matter research

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Preface

2025D 10 6-9| UH Postech | X APCTP 22(μ \ddot{A} $<$ \neg " , YP (22th KIAS-APCTP Winter School on Statistical Physics)X 5Ü Ü \neg X \ddot{D} \ddot{d} x P \neg ... Èä .

\ddot{U} $<$ \ À Á t " $<$ ' \ | 1 active matter systems \ddot{D} \ μ \ddot{A} $<$ \neg „ | X \ddot{d} | " Vicsek, Czirók, Ben-Jacob, Cohen, Shochett 1995 \ddot{D} \ \ Physical Review Letters | 8 [VCJ+95] \ddot{D} Do È μ Èä . t | 8 @ $<$ ' X \ddot{U} x ' Ü 1 (motility) t ä ' Ä Ñ è Á X ô , 1 D ° X " u ì x í Y D ô ù \ ä " P È D ü à ^ μ Èä . è X t Ä e ø \ ' ° ü | ô ì ü " toy model @ J „ Æ t \ à Š Ñ Èä . ø X X ~ D \ddot{D} L ^ X Vicsek ñ X " @ € • Æ Ä \ À 30 D t À œ \$ ~ L À Ä μ \ddot{A} $<$ \neg ð | • \ddot{D} Æ È \ ' ð | \ddot{D} \ D ^ ì | $<$ \ddot{a} ^ μ Èä . μ \ddot{A} $<$ \neg ð | • ä @ t ` ð | | μ t 9 @ Ý < ä Ø „ | @ X Ü ð | | μ t \ddot{U} x ' Ü 1 t ì Ü " È \ ' Ü í Y < È Á Ü , D É Á t , topological defects, pattern formations ñ D \ ^ ð | X à ^ μ Èä .

t X " ä ' \ m 1 D " active matters ' p polar order m 1 D " Ä X D É Á t ì D ä è à ^ μ Èä . t ü | ... • 0 ð | \ddot{D} 0 ø t " Vicsek ñ X " ü active Brownian particles " D μ t ä ð f ... Èä . GPU | \ © \ molecular dynamics 0 • @ ... • 0 " Ä X Á t | ä è " % \ X ð |) • ... Èä . \ , Boltzmann) Ý ü Smoluchowski) Ý @ ... • 0 " Ä | ì ì À t ` x ð |) • D © ` ^ " continuum) Ý < \ 0 ` ^ Æ t Èä . X | μ t • 8 ^ Æ ` P) • ` t active matters \ddot{D} ì D È | ä x ð | „ | \ddot{D} Ä \ © ` ^ 8 0 i Èä .

ä μ D \ddot{D} X " „ ä D t CUDA \ ' 1 molecular dynamic simulation \ ø " ü python3 \ ' 1 anima-

tion \ ø " D õ X µ Èä .CUDA \ ø " D ¬ ©X0 t " C9 @C++, 'Đ \ À Ý t D" X p Nvidia
X gpu D" i Èä [8 à : <https://sites.google.com/view/jdnoh-tcp/cuda-gpu>]. Animation \ ø " D ¬ ©X
0 t " python3@C/C++ compiler D" i Èä . \$, Ì | | µ t t ä ° • ĐĐ ü ` ^ " X ½ D ø ¬
È (t " 8 • Èä .

t X x , " ì ì review papers| 8 p X ì ' 1 ^ LD ™Èä [MJR⁺13, PBGC14, Cha20].

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1.1 Active matter란?

à x ä´ Ä | I 1 X” ...•X Ùí YD Ý t ô• .à ½ Ä Ð ...•X ´ Ù@° ` x ´ Ù) Ý D
 0 x ä .Ä ô x 9 @Dô x x € X ½ü Á 8´ ©Xà ^ ä t ...•X ´ Ù@U` x •1 D Ä Langevin
) Ý<\ 0 ä . | ä´ (Ä Tt à damping coefficient 1/µx ´ Ð Brown ...• ” x % Ð à Ä
 ä ÈD I 1 X” ...• ä ü X 4´ x ©ì X ¥ D ”ä . Overdamped limitÐ Brown ...• iX X r_i”
 ä LX stochastic Langevin) Ý D 0 x ä :

$$\dot{r}_i = \mu F_i + \sqrt{2D}\eta_i(t) \quad [\text{diffusion constant } D = \mu k_B T, \langle \eta_i(t) \rangle = 0, \langle \eta_i(t)\eta_j(t') \rangle = \delta_{ij}\delta(t-t')] \quad (1.1)$$

ì } Brown ...• 3X x € X ½<\ € 0 Ð À | a X ì t | í Y Ð À\ X` ^ ä t , ...• ”
 stochastic noise ηÐ X\< Ù x ´ Ù Ð T t • t à ¥ Ù x ´ Ù D ` ^ œ ä . ¥ Ù´ Ù X • %D v_0,
) ¥ D è ì 0 n\ ~ À´ t ...•X ´ Ù) Ý @

$$\dot{r}_i = v_0 n(t) + \mu F_i + \sqrt{2D}\eta_i(t) \quad (1.2)$$

X 4 D OE p, v_0 @ n \ • ´ X Ù í Y D OE ä . • x ´ Ù 1 (motility) D " ... • \ | 1 < È D
¥ Ù < È (active matter) t | € x ä .

¥ Ù < È t D Ì ½ ° Ð Ä ... • ä @ ´ Ù 1 D È ^ ä . ^ OE \ Brown ... • ø \ x t p , D É
µ Ä í Y Ð T ^ ä è " driven lattice gas systems í Ü À Á t " ... • \ t è ´ 8 ^ ä . Motility @ mobility |
D ½ ^ | ^ " | „ D Ü X 0 " ´ 5 À Ì , ´ < \ ¥ Ù < È @ persistence • 1 t ^ " ... • \ | 1
Ä | À m \ ä .

¥ Ù < È X " • ð Ä , 1 ^ Ý < Y Ä Ð } OE > D ^ ä . 8 ì ´ X active cytoskeleton € 0 D ä È " È Ð
t t " Ý < Y x ¥ Ù < È Ä " Ý T Y Ð À | motility X Ð Ì ¼ " ä . Á t \ T Y p 1 D " ´ t < \
t è ´ Ä Janus particle, • 0 ¥ < \ | Ù " Quincke roller, 0 Ð À \ | Ù " \ ñ @ x õ < \ i 1
¥ Ù < È X \ ä Ø ð | Ð \ © à ^ ä .

1.2 Ñ 단 거동 Ð 대 \ µ 계 < 리 ð 구 P 림

p Ü Ä X Ñ è p Ù Ð \ µ Ä < ¬ ð | X P „ D è T t 0 t ô • . µ x µ Ä < ¬ Y X 4 " © • (lat-
tice) ä . © • Ð à ´ ^ p ~ © • ¬ t | t Ù X " ... • 9 @ ¢ @ ä X Á t @ Ù í Y • ™ Á Ð \
ð | \ X OE Ä % È à , ø ° ü \ õ X (Ð , m 1 , ô t • Y ñ t p Ü Ä Ñ è p Ù X ô , 1 D ° X "
" \ " OE „ D L OE È ä .

õ j ð ° Ý 1 ^ ™ Ä Æ " ð ° Ý X ¬ @ µ Ä < ¬ Y X 4 | T ± U ¥ Ü 0 ä . õ j ð ° Ý X x Ü Ð
à 9 @ Á | µ t ´ Ù X " ... • @ ¢ @ ä D ¬ © t ä ´ \ ð | Ä % È à , t ì \ Ü Ä " µ Ä < ¬ Y X
" ü | õ Y / x 8 / ¬ OE „ | X õ j Ä Ð L À ä .

¥ Ù < È Ä " ... • 9 @ ¢ @ X ' € Á Ü @ T ^ ' X L À Ù í Y x À ä " Đ µ Ä < ¬ Y ð I X
È \ ' (ì ä „ < \ • ¬ j à ^ ä . ¥ Ù < È Ä Đ " ... • X õ x • Ä @ ¢ @ ñ X ' € • Ä X Œ
° i ' ^ ä . t Đ à \$ À J X X È \ ' ... X X ° i @ µ Ä < ¬ Y ð I • Đ Œ Î @ ð I ü | X 8 ü à ^ ä .

2

Vicsek model

2.1 Vicsek model

Vicsek \tilde{n} @ È 4 \rightarrow X $\frac{1}{4}$ ÀL Á D \$...X 0 t ¹ “self-driven particles” \ t è ‘ Ä ” Ä | Ä ...X à Monte Carlo simulation ð | | %oXì» @ È \ ‘ ...XX Á t | ô à X ä [VCJ+95]. t ù | 8 X • ” 5...t Àì ,” à 8 Ì Ð ø ï t | 8 Ð Ü \ ” D Vicsek” t | € t ä . Vicsek” X ¹ Ö D - t ô • .

- $L^2 \ll 0 \ll X \ll 2 \ll \text{Ð} \ll \text{É} \ll t \ll \text{Ð} \ll N = \rho N^2 \ll X \ll \dots \ll | \ll 1$

- ... • $iX \text{ Á } \ddot{U}$ X $r_i(t) @ \bullet \ddot{A} v_i(t) = v_0(\cos \theta_i(t), \sin \theta_i(t)) \backslash$ t À à , • % @ $|v_i| = v_0 \backslash |$ X ä .

¹¼À ‘ äÈ” Ù < Ð \ artificial life” @ 1986 Ð Ð ° ü Y • x Craig Reynolds Ä ... \ ^ ä . Boid = B(irds) + (andr)oid \ \ ” (• ì ” <https://www.red3d.com/cwr/boidsÐ> U x ` ^ ä .

2 Vicsek model

• $\Delta t = 1$ X \ddot{U} \odot $\ddot{U}H$ " \grave{a} ...•X X @ • \ddot{A} $\ddot{U}\ddot{U}\ddot{D}\ddot{A}$ p t , \ddot{a} .

$$\mathbf{r}_i(t+1) = \mathbf{r}_i(t) + \mathbf{v}_i(t), \quad \theta_i(t+1) = \text{Arg} \left[\sum_{j \in \mathcal{N}_i} e^{i\theta_j(t)} \right] + \zeta_i(t) \quad (2.1)$$

\mathcal{N}_i : ...• i @ X p \neg $r_0 = 1$ \hat{o} \ddot{a} ' @ ...• \ddot{a} X \ddot{N} i

$\zeta_i(t)$: uncorrelated random noise uniformly distributed in the interval $[-\eta : \eta/2]$

• ...• " • \grave{a} X • \ddot{A}) \neq D \ddot{u} ...•X \acute{E} \grave{a} ' \ddot{U}) \neq \ddot{u} , X \grave{a} • \ \ddot{a} .

• • \ddot{A} , \acute{A} 8 ' \odot @ \ \ p \neg $r_0 = 1$ ' \ddot{D} \grave{I} ' \odot X " short range interactiont \ddot{a} .

• • \ddot{A} , \acute{A} 8 ' \odot @ • \ddot{A}) \neq \ddot{A} θ | „XX \ddot{A} ϕ | | T X " ($\theta \rightarrow \theta + \phi$) \ddot{o} • x \odot \ddot{A} X \ddot{D} t m t \ddot{a} .

• ...•X motility| x X t ...•X • \ddot{A}) \neq \ddot{A} " • 1 XY " \ddot{u} @ m 1 D " \ddot{a} . t \grave{i} \ t \ Vicsek " X ...• | flying XY spin, Vicsek " D active XY " t | \grave{a} \in t 0 \ddot{A} \ \ddot{a} .

• 1 • 1 D " alignment \acute{A} 8 ' \odot @ " \grave{a} ...• @) \neq < \ \acute{A} \acute{A} t " $\frac{1}{4}$ \acute{A} L (flocking) \ddot{N} \grave{e} p \ddot{U} D | < \neg \hat{a} . ' ...•X \acute{E} \grave{a} • \ddot{A} " $\frac{1}{4}$ \acute{A} L \acute{A} X order parameter \acute{I} \ D \ \ddot{a} .

$$v_a = \frac{1}{N v_0} \left\langle \left| \sum_{i=1}^N \mathbf{v}_i \right| \right\rangle_s \quad (2.2)$$

1995 D X | 8 \ddot{D} • \ddot{a} @ ...• \ddot{A} ρ @ aligning interactionD) t X " \acute{I} L X | 0 η | \hat{O} p X \ddot{A} \circ D % \circ X \acute{i} \ddot{a} L \ddot{u} @ \circ \ D » \acute{E} \ddot{a} .

2 Vicsek model

- $v_a = 0$ disordered (gas) phase
- $v_a \neq 0$ ordered (flocking) phase
- gas phase @ flocking phase \rightarrow order-disorder transition

$$v_a \sim |\eta_c - \eta|^{0.45 \pm 0.07}, \quad v_a \sim |\rho - \rho_c|^{0.35 \pm 0.06} \quad (2.3)$$

active matters $\mu < \dots$

2.2 Mermin-Wagner theorem

Mermin-Wagner (9 @ Hohenberg-Mermin-Wagner) \rightarrow "Continuous symmetries cannot be spontaneously broken at finite temperature in systems with sufficiently short-range interactions in dimension $d \leq 2$ " [Hoh67, MW66].

$d(\dots)$

$$H = -J \sum_{\langle i,j \rangle} \cos(\theta_i - \theta_j) \quad [\text{ferromagnetic coupling constant } J > 0] \quad (2.4)$$

\dots nearest neighbor interaction \dots

2 Vicsek model

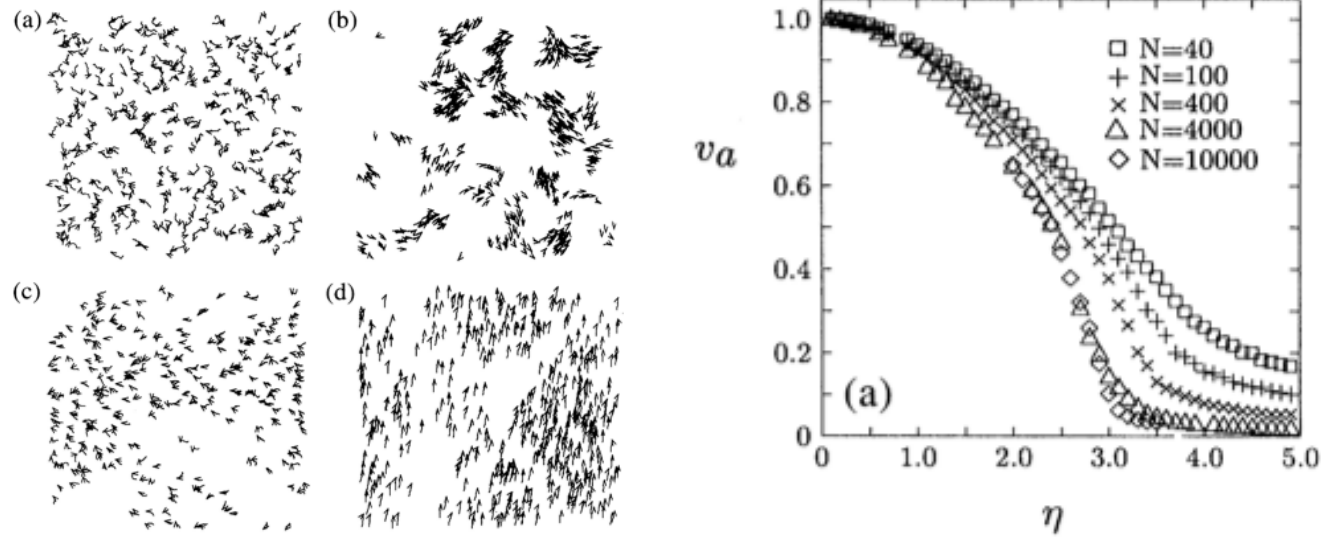


Figure 2.1: Vicsek model snapshots and order parameter scaling. (from [VCJ+95])

2 Vicsek model

\ RG Ä° D μ t 2(ĐĐ roughness exponent χ@ anisotropy exponent ζX U\ D I ^ ä .

$$\chi = -\frac{1}{5}, \quad \zeta = \frac{3}{5} \quad (2.11)$$

Roughness exponent LX D 0 Đ • ÄX " Û@ p - @' É] ' à ä . %o, " Ût flocking ordered state| 4` ÆLDX ø\ ä . Toner-TuX °ü " Mermin-Wagner -| 0 t " ô É ÄĐ @ " i - active matterĐ ð • m1 t • <\ • 4 ^LD t <\ ô x \ X Ä <\ ü à ^ ä .

ø ì ~ , Toner-TuX t ` @ Ä ~ X OE Á ` t à l ' x " ÄTX Ä ^, ...Xä"è D à ^ ä . T p ä ~ Toner" 2012ĐĐ œ \ | 8 Đ Toner-Tu " Đ à \$ X Ä J @ È \ ' D mD " \ Ä ...Xt Toner-Tu RG Ä° X Ä 1 t -| ĐĐ ô ä [Ton12]. 0 | Toner-TuX t ` @ Mermin-Wagner - @ @ Ä \ t ` <\ D ä t 0 ô ä" ü - x t ` <\ D ä t " f t Ä ù X ä .

2(Đ Vicsek " X ordered phase íĐ X <\ Ä° \ Á Ä h " Ý (2.10)ü @ anisotropic power law scalingD 0 x ä [MGC19]. è ,, Ä Ä X @ χ = -0.31(2), ζ = 0.95(2)t p Toner-TuX ü } X (t | ô x ä .

2.4 ð • Á tx 가 ^ ð • Á tx 가?

• ð • m1 • 4 @ T ^ ' flocking Á tX • 1 \ | ∈ D ^ i | < 0 ä . Vicsek ø ù @ 1995DX | 8 t ~ \ flocking Á t ð • Á t | à ü ≠ X ä (Ý (2.3) 8 p). ø ì ~ , p l 0 Đ 4 Ü ÛH %o X Ä° @ flocking Á t ^ ð • Á t, D ô ì ü È ä . e ø m OE Ä (ρ₀, η) É t Đ X Á É ø ¼ @ a ' -0 ' Á t | a " ' X Á É ø ¼ ü - X ä [Cha20].

2 Vicsek model

- homogeneous disordered (gas) phase ($v_a = 0$): $\langle v \rangle = 0$, $\langle v^2 \rangle = \frac{1}{2}$.
- polar ordered/homogeneous ordered/flocking (liquid) phase ($v_a > 0$): ... $\langle v \rangle = v_a$, $\langle v^2 \rangle = \frac{1}{2} + v_a^2$ (giant number fluctuation). $\langle (\delta n_{\xi})^2 \rangle \sim \langle n_{\xi} \rangle^{\alpha}$ with $\alpha = 8/5$ (Toner-Tu), 1.67 (simulation) [MGC19].
- band (coexistence) phase: $0 < v_a < \frac{1}{2}$ (microphase separation) | $\langle v \rangle = v_a$, $\langle v^2 \rangle = \frac{1}{2} + v_a^2$ (bands) ... $\langle v \rangle = v_a$, $\langle v^2 \rangle = \frac{1}{2} + v_a^2$.

2 Vicsek model

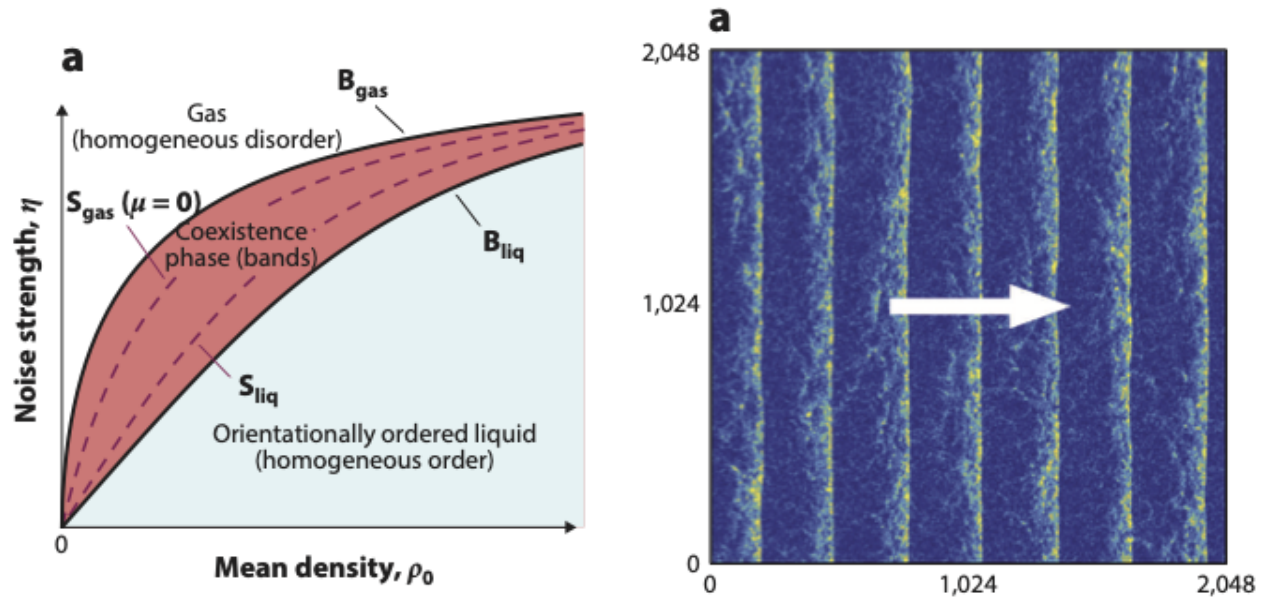


Figure 2.2: Vicsek model phase diagram and simulation. ([Cha20])

3

X ð 7)•

3.1 Self-propelled particle 모

...• 0 X active matter" ' p ¥ \ x f t self-propelled particles (SPP)" t ä. ...X Á Ü"

$X_i \in \mathbb{R}^2, v_i \in \mathbb{R}^2, (r, v) \in \mathbb{R}^4, t \in \mathbb{R}$ $X_i \in \mathbb{R}^2, v_i \in \mathbb{R}^2, (r, v) \in \mathbb{R}^4, t \in \mathbb{R}$

$t \in \mathbb{R}$ $X_i \in \mathbb{R}^2, v_i \in \mathbb{R}^2, (r, v) \in \mathbb{R}^4, t \in \mathbb{R}$ $v_0 \in \mathbb{R}^2, \theta \in \mathbb{R}$ polar angle $-\pi < \theta \leq \pi$ $v = v_0 n(\theta)$ $n(\theta) = (\cos \theta, \sin \theta)$

3.1.1 Vicsek-type 모

- discrete time $t = n \times \Delta t$, continuum space $r \in \mathbb{R}^2$

- è p ñ • Ä , Á 8 ' © D ì h \ ' Ù) Ý

$$r_i(t+1) = r_i(t) + v_0 n(\theta_i(t)) \tag{3.1}$$

$$\theta_i(t+1) = \text{Arg} \left[\sum_{j \in \mathcal{N}_i(r_0)} e^{i\theta_j(t)} \right] + \xi_i(t) \tag{3.2}$$

$\mathcal{N}_i(r_0)$...• Ì € 0 X p ñ r_0 t X x ...• ä Ñ i D ~ À ' à , $\xi_i(t)$ I $[-\frac{\eta}{2} : \frac{\eta}{2}]$ ñ t Ð à | X €
 „ ì X à Á Ä Æ” jLD ~ À , ä .

3.1.2 Active Brownian Particle (ABP) ☐

- continuous time, continuum space $r \in \mathbb{R}^2$

- è p ñ Á 8 ' © ì P \ Wü • Ä , Á 8 ' © D ì h \ ' Ù) Ý

$$\begin{aligned} \frac{dr_i}{dt} &= v_0 n(\theta_i) - \nabla_{r_i} W + \sqrt{2D_t} \zeta_i(t) \\ \frac{d\theta_i}{dt} &= -\frac{J}{|\mathcal{N}_i(r_0)|} \sum_{j \in \mathcal{N}_i(r_0)} \sin(\theta_i - \theta_j) + \sqrt{2D_r} \tilde{\zeta}_i(t) \end{aligned} \tag{3.3}$$

- ...• ñ t Ð è p ñ ™%t ' © X à • Ä , Á 8 ' © t Æ D L (J = 0), ABP ” @ motility-induced phase separation (MIPS) Á D |< ” ä [FM12].

3 X ð |)•

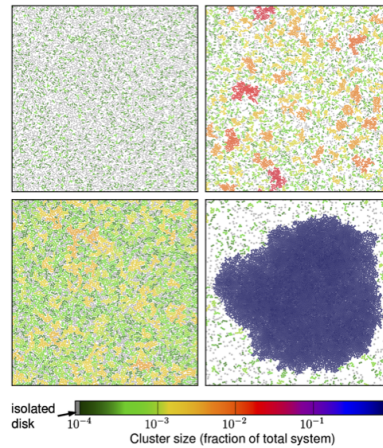


Figure 3.1: ABP ð | ' ~ " MIPS ([FM12] ð ì).

3.2 Molecular dynamics L 고리듬

...• 0 " ð \ „ • Ù í Y L à ñ ì D L D ô • . S P P X ´ Ù) Ý D X „ ` L ¥ ´ \$ ´ | @ è p ñ
 Á 8 ´ © X | 0 | Ä ° X " f t ä . ì } ...• X Á 8 ´ © Ý N_i(r₀) D | X 0 t " à ...• X X | € \ ä
 t è Ü © Δ t Ù H ð % o t | X " Ä ° ´ @ ´ ...• / X ñ N² ð D @ ` f t ä . t Ä ° D " (< \
 % o X " f t „ • Ù í Y Ä ° X u ì ü t ä .

3.2.1 Cell linked-list

Cell linked list 9 @ cell list| ¬©Xt ü p ¬ Á 8 ‘ © Ä° Ð D” \ Ä° ‘ D O(N) < \ • 0 < \ |
 ^ ä 1. ø ¼ 3.2X 2(Ð | ô p cell linked-list| Ì Ü” ü D ´ ´ ô • .

1. 4 × 4X 2(Ð ð Ð 8 X ...• „ ì X à ^ ä .
2. ´ ð D r₀ × r₀ | 0 X cellä \ „ \ ä . r₀ = 1x ½° 16 X @t Ý 4 ä .
3. ...•X @ ü Œ | Ä° \ ä (0^ ...• 10^ @, 1^ ...• 4^ @, ...).
4. ...• ä D @ ü Œ 0 < \ sortingX à , ...•X x q x | @ ü Œ \ ¬ \$ \ ä .
5. @Ð ì h ...•X 8 ¬ ^ 8 @, ¬ ^ 8 | ¥ \ ä (1^ @Ð” 0 ~ 0^ ...• , ..., 10^ @Ð” 4 ~ 5^ ...• , ...). D ´ ^ ” @X 8 ¬ ^ 8 @, ¬ ^ 8” NULL \ \$ \ ä .

t ü D È Xt (i) ...• ” ” à • 1 D ô t \ D \ x q x Ì à (ii) @@ • à Ð ì h ...• ä X ©]
 (8 ¬ ^ 8 @, ¬ ^ 8 ¬ t)D Œ ä .

3.2.2 Á 8 ‘ © Ý > 7 |

Cell linked list| ¬©t ...• iX Á 8 ‘ © Ý D > ”)• D LD ô • . í Ü ø ¼ 3.2X 2(Ð | µ t \$...X ä .

¹D• ” cell listÐ 0 \ „ • Ü í Y 0 • D 2012D 1Ô 30| Ð 2Ô 3| Ù H POSTECHÐ ô° 9(µ Ä < ¬ ” , YPÐ 0 à ä .
 %X à © \ X Ä° • D L \$ ü à KISTIX à ¬ Ø Ä ì < \ ¬ X x ¬ | , ° ä .

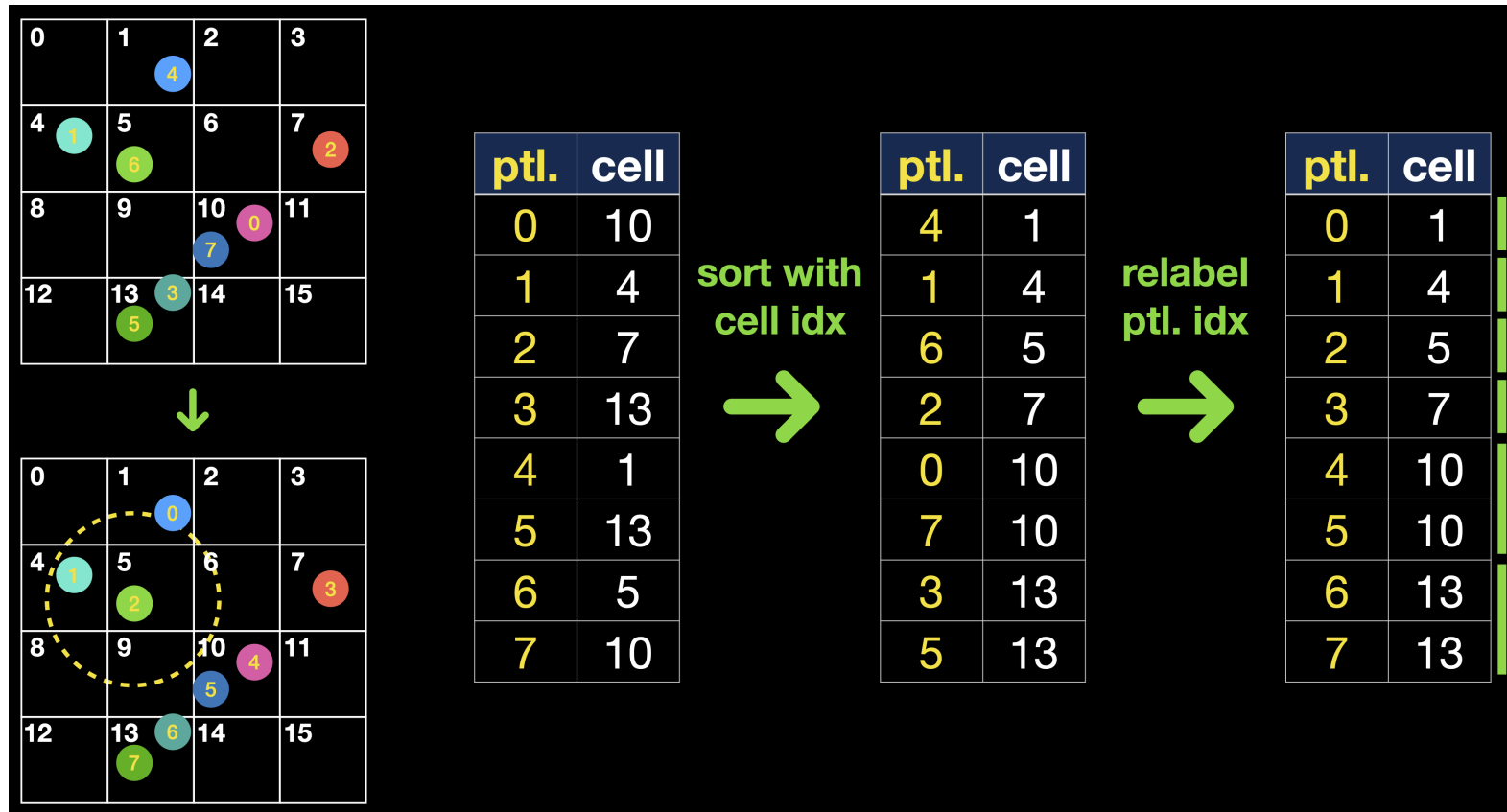


Figure 3.2: Cell linked-list $\hat{l} \hat{a} 0$.

3 X ð |)•

- ...• i • \ cell $ü$ $ü$ X X i $ø$ $à$ $^$ " cell 9 | $à$ \$ \ $ä$. ($i = 2t t \{0, 1, 2, 4, 5, 6, 8, 9, 10\}$)
 - @Ð ¥ ...•X 8 \rightarrow , , \rightarrow $^$ 8 \hat{o} | \rightarrow ©X i 9 @Ð i h " $à$...•X \tilde{N}_i A | | \ $ä$. ($i = 2t t t A = \{0, 1, 2, 4, 5\}$)
 - AÐ • \ ...• ' p ...• i @X p \rightarrow Á 8 ' © $\frac{1}{2} r_0 \hat{o}$ $ä$ '@ ...• $ä$ > D $\mathcal{N}_i(r_0)$ Ð ¥ \ $ä$. ($i = 2t t \mathcal{N}_2(r_0) = \{1\}$)
- \ ...• $ù$ 9 X @Ð i h ...• @X p \rightarrow ì D DPX 0 L 8 Ð typical caseÐ $\ddot{A}^\circ \acute{E} @ O(N)t \ddot{a}$.

3.3 GPU를 \ ©\ Ñ렬 계°

GPU" " $à$...•X• \ddot{A} \ddot{U} Ð 1 $à$ " (parallel update), • \ddot{U} \acute{Y} \ddot{A}° D \tilde{N} , \sim \rightarrow X" p \ T \ddot{o} ¥ X t \ddot{a} . GPU \ddot{A} \ddot{A}° ¥ %D 100| < , \ ©X \$ t gpuX hardware ' \ddot{U} Ð \rightarrow Ð \ J @ t t D" X \ddot{A} ì , D \ddot{o} \rightarrow ©•X ...¥ Ð t " \ddot{a}° ' \$ ' | t \ddot{a} . t X Ð " Nvidia \rightarrow X GPU Ð CUDA (Compute Unified Device Architecture) | \rightarrow © t \tilde{N} , \ddot{A}° D %X" p D" \ \ \mathcal{O} \ X \hat{o} ì D "D• t t X") \acute{Y} < \ " \$...` f t \ddot{a} ² .

3.3.1 GPUX 구p @ ' 동Ð 리

- GPU" LED" \acute{E} 0 \ D ` \hat{a} . " \acute{E} 0 X grid \mathcal{O} \ (m, n) \acute{E} \ddot{a} = @t ì ' 8 \hat{i} , Nvidia \rightarrow X GPU Ð" \ddot{o} ° D %` \hat{a} \hat{a} X grid \mathcal{O} \ (m, n) 9 @ (l, m, n) D \ddot{A} ` \hat{a} " \mathcal{O} X cuda cores

² \rightarrow t , <https://sites.google.com/view/jdnoh/lecturesÐ> tutorialÐ \rightarrow © cuda@python source code| \ddot{a} ' \ \ddot{U} ` \hat{a} .

ì ´ 8 ì ´ 8 ^ ä .

- ø ~ = ô ü ´ À t ¨ È 0 X = @ t OE\ Ð ` ù rgb à 8 | Ù Ü Ð œ % X i t , cuda cores” • à X ø Ñ Ü OE\ D 8 p X p h Ä ° D Å ½ < \ Ù Ü Ð % \ ä .
- SPP ...• | cuda coreÐ QÜ ü t „ • Ù í Y Ä ° D Ñ , \ % ` ^ ä .

3.3.2 CUDA kernel

cuda kernel @ cuda cores % ` ´ Å D X \ h 9 @ è ô D À m \ ä . 2¹⁸ (Ð X P ; 0 a, b X i c = a + b D I X \$ t , cuda kernel @ D ~ @ @) Ý < \ X X à

```
__global__ void a_plus_b_equal_c(int *a, int *b, int *c)
{
    unsigned int tid = threadIdx.x + blockIdx.x*blockDim.x;
    c[tid] = a[tid] + b[tid];
}
```

ä LX) Ý < \ 8 œ \ ä .

```
int nBlock = 1024, nThread = 256;
a_plus_b_equal_c<<<nBlock, nThread>>>(a, b, c);
```

^ Ñ © \ D | Ñ © X i \$... D t ´ ô • .

3 X ð |)•

- <<<1024, 256>>>” 1024 × 256 X = @ ø ñ Ü | Ä Á “ È 0 | Ý 1 X | ” À Ü ´ ä . (1 grid = 1024 blocks, 1 block = 256 threads)
- cuda kernel t 8 œ t = @ (cuda core)@ • à X ø ñ Ü œ \ D ñ Ð \$ \) Ý < \ À X t Ä ´ Ä D %\ ä . (threadIdx. x = 0, ..., 255, blockIdx. x = 0, ..., 1023, blockDim. x = 256)
- blockDim. x(] \ Ð ì h ð Ü X /)” 32X 0 \ !

3.4 CUDA를 \ ©\ ,, • 동기 Y Ñ 려계° pseudo code

pseudo code

```
# Viscsek_Config.cu or Viscsek_Tseries.cu

initialize()

for t = 0, ..., T
    Xupdate<<<nBlock, nThread>>>()
    linked_cell()
    PolarAngleUpdate<<<nBlock, nThread>>>()
    Vupdate<<nBlock, nThread>>>()
    write_order_parameter()
```

```
wri te_conf i g()
```

```
fi nal i ze()
```

package

U• | v i csek_turori al . tgz • Đ

V i csek_Confi g. cu (configurationD œ%X" T x \ ø ")

V i csek_Tseri es. cu (order parameter Ü Ä ô D œ%X" T x \ ø ")

V i csekKernel . cu (cuda kernel)

V i csekModel . cu (class X)

compile and run (CUDA Version 11.6)

```
nvcc -O2 V i csek_Confi g. cu -o V i csek_Confi g. exe -I m -I curand_ static -I cu libos
--extended-lambda
```

```
V i csek_Confi g. exe {l x} {l y} {rho} {v0} {eta} {seed} {tmax} {i c= gas or li q}
```

```
=> | œ%V i csek_Confi g_from_{i c}_state_Lx{l x}Ly{l y}Rho{rho}Eta{eta}V{v0}. dat
```

```
V i csek_Tseri es. exe {l x} {l y} {rho} {v0} {eta} {seed} {tmax} {i c= gas or li q}
```

```
=> | œ%V i csek_Tseri es_from_{i c}_state_Lx{l x}Ly{l y}Rho{rho}Eta{eta}V{v0}. dat
```

3.5 Python< 로 ` 니메t X

PythonX matplotlib.pyplot package| \ ©Xì Vicsek " X Ùí YD animation< \ Ux ` ^ ä . PythonX
 ¥ @€ „ ì \ ð 1 ð ^ À ì , loop Ä ° t À Å X Ö • ñ ä . t | t ° X " ì ì À)• t ^ À ì , D • " u ì
 loop| C/C++\ ' 1 X à t | ô | X à | t ì ñ \ À X \ Ä python ð ^ ì ð ")• D ñ © X à ^ ä .

- package: U • | Vi csekPython. pgz • ð

anim. py, model. py: Vicsek " ü ` È T t X

sub_local_file.d.c: ...•X velocity angleD Å p t , X " Ä ° D ô ù X " C subroutine

SConstruct: C \ ø " D ô | X ì | t ì ñ \ ì Ü " p D " \ ¶ | ½ , |

"scons" software toolD \$ X \ Ä , scons ...9 ´ | ...%X t SConstruct ¶ | ½ , | t Ä Ü X " \ sub_local_file.d.c
 | ô | \ Ä | t ì ñ Ý 1 t ä .

- ä %o python3 anim. py

3.6 8 고 • 료

- CUDA ð Ý H ~ t À <https://developer.nvidia.com/cuda-zone>

CUDA quick start guide, tutorial, CUDA C/C++ programming guide, ...

- Thrust <https://developer.nvidia.com/thrust>

GPUĐ ©\ utilitiesX " L : sort_by_key, fill, reduce, ...

- CuPy H~ t À <https://cupy.dev/>

CUDA with python

4

t ð ñ)•

...• 0 X " ð \ 1 x t t | t Ä • Ä DÜÐ \ ¶t ` D õ € t ô • . ¶t ` @ scalar field
x Ä ρ(r, t) = ∑_i δ(r - r_i(t)) @ vector field x polarization p(r, t) = $\frac{1}{\rho(r, t)} \sum_i \frac{v_i(t)}{|v_i(t)|} \delta(r - r_i(t))$, 9 @ ' Ù É
Ä (magnetic system) D D t • T Ä | m X 0 Ä \ ä) m = ρp ð \ ð •) Ý D Ä X " f < \
Ü ' \ ä .

4.1 Boltzmann) Ý

ü ì) Ý @ ...• Ä X 1 È D one-particle distribution function

$$f(\mathbf{r}, \theta, t) = \left\langle \sum_{i=1}^N \delta(\mathbf{r} - \mathbf{r}_i(t)) \delta(\theta - \theta_i(t)) \right\rangle \quad (\mathbf{r}_i, \theta_i : \text{position and polar angle of the } i\text{th ptl.}) \quad (4.1)$$

D µ t 0 \ ä [BDG09]. <(>) @ U ` x ' Ù ½ \ Ð \ É à D X ø \ ä . f h "

$$\frac{1}{V} \int_V d\mathbf{r} \int_{-\pi}^{\pi} d\theta f(\mathbf{r}, \theta, t) = \frac{N}{V} = \rho_0 \quad (4.2)$$

D ì q \ ä (normalization p t).

4.1.1 Time evolution

$\delta t X \dot{U} H f h X \dot{A} T \delta f = f(\mathbf{r}, \theta, t + \delta t) - f(\mathbf{r}, \theta, t) | \text{ " } t \hat{o} \bullet .$

- self-propulsion: $\mathbf{r} \rightarrow \mathbf{r} + v_0 \mathbf{n}_\theta \delta t$

$$\left. \frac{\delta f}{\delta t} \right|_{s.p.} = \frac{f(\mathbf{r} - v_0 \mathbf{n}_\theta \delta t, \theta, t) - f(\mathbf{r}, \theta, t)}{\delta t} = -v_0 \mathbf{n}_\theta \cdot \nabla f . \quad (4.3)$$

- $\lambda \delta t X U \setminus | \sim \text{ " } \dot{U} \ddot{A} X 4 \text{ ' } x U^\circ$ (self diffusion): $\theta \xrightarrow{\lambda \delta t} \theta + \zeta t \dot{a} \zeta X U \text{ " , } \dot{i} h \text{ " } P_\eta(\zeta) t \ddot{a} (\dot{E} \dot{a} @ 0, \text{ " } @ \eta^2).$

$$\left. \frac{\delta f}{\delta t} \right|_{s.d.} = -\lambda f(\mathbf{r}, \theta, t) + \lambda \int_{-\pi}^{\pi} d\theta' \int d\zeta f(\mathbf{r}, \theta', t) P_\eta(\zeta) \delta_{\text{mod } 2\pi}(\theta - (\theta' + \zeta)) \quad (4.4)$$

$$= \lambda \left[-f(\mathbf{r}, \theta, t) + \int_{-\pi}^{\pi} d\theta' f(\mathbf{r}, \theta', t) P_\eta(\theta - \theta') \right] \quad (4.5)$$

- binary collision: $\ddot{A} \text{ @ } \dot{a} t K t \dot{A} X \dots \bullet \dot{U} \ddot{U} \text{ @ } \dot{i} X \dot{i} \dot{A} 8 \text{ ' } \text{ @ } X \text{ " } \dot{-} t D 4 \dot{U} \text{ ' } \dot{\wedge} \dot{a} \text{ . ' } \dot{U} \ddot{A} (\theta_1, \theta_2) x P \dots \bullet \text{ @ } \dot{i} t \bullet \ddot{A} \text{ , } \dot{A} 8 \text{ ' } \text{ @ } D^a \dot{E} \dot{a} \dot{a} X \bullet \text{ . } \bullet \ddot{A} \text{ , } \text{ @ } \ddot{A} P_\eta \text{ " , } \dot{i} | 0 t \text{ " } \dot{i} L t \text{ ' } \text{ @ } \setminus \dot{a} t \dots \bullet X \text{ ' } \dot{U} \ddot{A} \text{ "}$

$$\theta_1 \xrightarrow{\delta t K(\theta_2 - \theta_1)} \theta_1 + H(\theta_2 - \theta_1) + \zeta, \quad (4.6)$$

$$\theta_2 \xrightarrow{\delta t K(\theta_2 - \theta_1)} \theta_2 - H(\theta_2 - \theta_1) + \zeta'. \quad (4.7)$$

4 t ð l)•

t à H(φ = θ₂ - θ₁)” D \ • Ä , t | ´ ¬ D L X ° € Ä t ä . Vicsek-type X ½° ð”

$$H(\phi) = \frac{\phi}{2}. \quad (4.8)$$

K(φ)” Ä (t φx P ...•X total scattering rate| X ø \ ä ...•X Á 8 ´ © p ¬ r₀t à Á • Ä X
l 0 v₀|n_φ - n₀| = 2v₀ sin |φ/2|„D à \$ X t ä LD » D ^ ä .

$$K(\phi) = 4r_0v_0K_0(\phi) \quad \left(K_0(\phi) := \sin\left|\frac{\phi}{2}\right| \right) \quad (4.9)$$

0 | ,

$$\left. \frac{\delta f}{\delta t} \right|_{coll} = -4r_0v_0 \int d\theta' K_0(\theta - \theta') f_2(\mathbf{r}, \theta; \mathbf{r}, \theta') \quad (4.10)$$

$$+ 4r_0v_0 \iiint d\theta_1 d\theta_2 d\zeta K_0(\theta_2 - \theta_1) f_2(\mathbf{r}, \theta_1; \mathbf{r}, \theta_2) P_\eta(\zeta) \delta_{2\pi}(\theta - (\theta_1 + H(\theta_2 - \theta_1) + \zeta)) \quad (4.11)$$

$$= -4r_0v_0 \int d\theta' K_0(\theta - \theta') f_2(\mathbf{r}, \theta; \mathbf{r}, \theta') \quad (4.12)$$

$$+ 4r_0v_0 \iint d\theta_1 d\theta_2 K(\theta_2 - \theta_1) f_2(\mathbf{r}, \theta_1; \mathbf{r}, \theta_2) P_\eta(\theta - \theta_1 - H(\theta_2 - \theta_1)). \quad (4.13)$$

X Ý @ two-particles distribution function f₂(r₁, θ₁; r₂, θ₂; t)D ì hX à ^ ä . | < \ n-particles dis-
tribution functionX ´ Ù) Ý @ (n + 1)-particles distribution functionD ì hX à ^ ´ , ´) Ý @
4 \ ^ Î @ „ ì h ä t Ä 5 < \ ° i Bogoliubov–Born–Green–Kirkwood–Yvon (BBGKY) hierarchy
l p | ”ä . t œ D ”t X 0 t É à ¥ ü ¬ 9 @ molecular chaos D D Ý X • .

$$f_2(\mathbf{r}_1, \theta_1; \mathbf{r}_2, \theta_2; t) = f(\mathbf{r}_1, \theta_1, t) f(\mathbf{r}_2, \theta_2, t) \quad (4.14)$$

4 t ö l)•

Ä ®à ...• -...• Á Ä | 4 Ü` ^ ä” D µ t » @ Boltzmann) Ý @ D~ @ ä .

$$\begin{aligned} \partial_t f(\mathbf{r}, \theta, t) + v_0 \mathbf{n}_\theta \cdot \nabla f(\mathbf{r}, \theta, t) = & \lambda \left[-f(\mathbf{r}, \theta, t) + \int_{-\pi}^{\pi} d\theta' f(\mathbf{r}, \theta', t) P_\eta(\theta - \theta') \right] \\ & - 4r_0 v_0 \left[f(\mathbf{r}, \theta, t) \int d\theta' K_0(\theta - \theta') f(\mathbf{r}, \theta', t) \right. \\ & \left. + \iint d\theta_1 d\theta_2 K_0(\theta_2 - \theta_1) f(\mathbf{r}, \theta_1, t) f(\mathbf{r}, \theta_2, t) P_\eta(\theta - \theta_1 - H(\theta_2 - \theta_1)) \right]. \end{aligned} \quad (4.15)$$

TMÄÄX t → t/λ, r → v₀/λ r, f → ρ₀ f D µ t Ü ü À @ Ä | 4 (Ð Ä \ \ Ü X t Ý (4.15)Ð
 λ = v₀ = 1\ “ D ^ à Ý (4.2)Ð Ä ρ₀ = 1\ “ D ^ ä . 4 (Ð) Ý Ð Ý (4.9)X total scattering rate
 h ” K(φ) = 2πκK₀(φ)t à ,• Ä , Á 8 ‘ © X 8 0” 4 (Ð ° i Á κ\ t Ä ä .

$$\kappa = \frac{2r_0 v_0 \rho_0}{\pi \lambda} \quad (4.16)$$

4.1.2 Angular Fourier mode expansion

®@ Ä Ð É à ¥ ü ¬ | è ^ L Ð Ä ^ l X à Boltzmann) Ý @ ì ^ ö j X ä . t ` x ü D t
 one-particle distribution functionX moments, 9 @ Fourier modes| à \$ X • .

$$\hat{f}_k(\mathbf{r}, t) = \int_{-\pi}^{\pi} d\theta f(\mathbf{r}, \theta, t) e^{ik\theta} \Leftrightarrow f(\mathbf{r}, \theta, t) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \hat{f}_k(\mathbf{r}, t) e^{-ik\theta} \quad (4.17)$$

Fourier modesX 1 1 D ¬ t ô • .

- $\hat{f}_{-k}(\mathbf{r}, t) = \hat{f}_k^*(\mathbf{r}, t)$

- $\hat{f}_0(\mathbf{r}, t) = \rho(\mathbf{r}, t): \dots \cdot \ddot{A}$
- $\rho \mathbf{p}(\mathbf{r}, t) = \begin{pmatrix} \text{Re } \hat{f}_1 \\ \text{Im } \hat{f}_1 \end{pmatrix} : \text{ ' } \ddot{U} \dot{E} \ddot{A} (\dots \cdot \ddot{A} \times \text{polarization}) = \text{local flocking order parameter}$
- $\rho \mathbf{Q} = \frac{1}{2} \begin{pmatrix} \text{Re } \hat{f}_2 & \text{Im } \hat{f}_2 \\ \text{Im } \hat{f}_2 & -\text{Re } \hat{f}_2 \end{pmatrix} : \text{nematic tensorial field (' } \ddot{U} \dot{E} \ddot{A} \times \text{D } \ddot{n}) 1)$

Fourier $\ddot{D} \setminus$ convolution $\neg (C(\theta) = \int d\theta' A(\theta - \theta') B(\theta')) \times$ Fourier modes" $\hat{C}_k = \hat{A}_k \hat{B}_k$ | $\setminus \odot \times t \theta$
 $\ddot{o} \ddot{D} \times$ Boltzmann) \dot{Y} (4.15) \ddot{D} Fourier $\ddot{U} \neg t \times \circ i) \dot{Y} < \setminus \cdot \} \odot \dot{E} \ddot{A} \hat{a} 1.$

$$\partial_t f_k(\mathbf{r}, t) + \frac{1}{2}(\partial_x + i\partial_y) f_{k-1} + \frac{1}{2}(\partial_x - i\partial_y) f_{k+1} = -(1 - P_k) f_k + \kappa \sum_{l=-\infty}^{\infty} \mathcal{J}_{kl} f_{k-l}(\mathbf{r}, t) f_l(\mathbf{r}, t), \text{ where } \quad (4.18)$$

$$P_k = \int d\zeta P_\eta(\zeta) e^{-ik\zeta} = e^{-k^2 \eta^2 / 2}, \mathcal{J}_{kl} = P_k l_{k/2-l} - l_l, l_u = \int_{-\pi}^{\pi} d\theta K_0(\theta) e^{iu\theta} = \begin{cases} \frac{4}{1-4u^2}, & u : \text{integer} \\ \frac{4}{1+2u \sin u\pi}, & u : \text{half-integer} \end{cases} \quad (4.19)$$

4.1.3 $\ddot{A} \setminus 4 \dot{E} \ddot{A} \ddot{U}$

$\ddot{a} \setminus 4 \dot{E} \ddot{A} \ddot{U} 9 @ 0 \text{ ' } \ddot{A} \ddot{U} \ddot{D} t \ddot{u} \times \text{ " } \ddot{A} \ddot{U}$

$$f_k(\mathbf{r}, t) = f_{G,k} := \delta_{k0} \quad (4.20)$$

¹ $\$ t \times \ddot{i} \ddot{A} \ddot{A} \dot{E} \ddot{D} \frac{1}{2} \circ$ Fourier modes | $\times \circ \times \text{ " } \hat{0} 8 | \dot{Y} \mu \times \ddot{a} .$

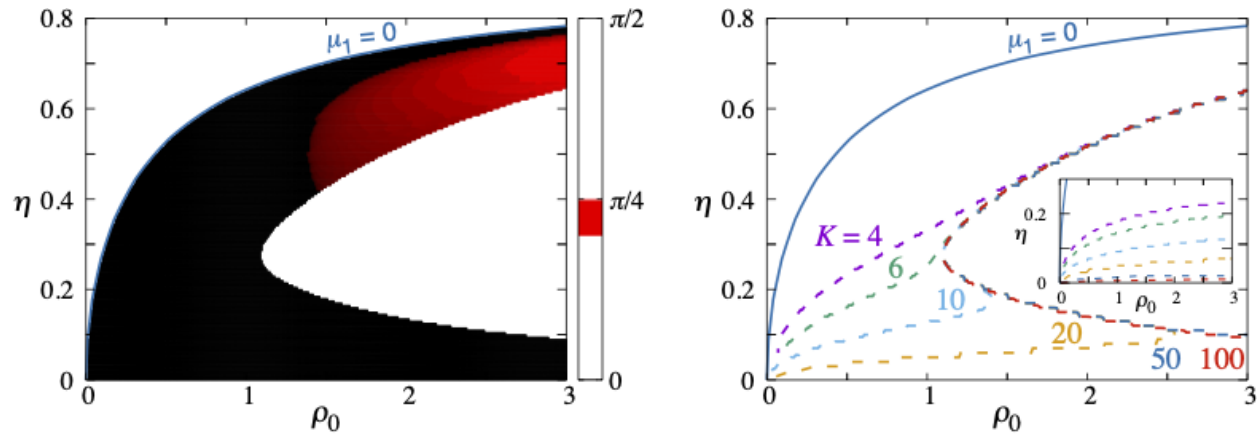


Figure 4.1: Boltzmann) Ý X Á É ø ¼ ([Mah18]Ð ì h . ø ¼ X ρ₀ @ ø 8 X κ ñ t Ð" ρ₀ = πκX Ä ^ ä .)

2. à | \ a ´ Á Ü f_{L,k}Ð wave vector $\mathbf{q} = (q_x, q_y)$ x ^ à x \ É t " Û X linear stability| p ñ \ ä .

$$f_k(\mathbf{r}, t) = f_{L,k} + \delta f_{k,q}(t) e^{i\mathbf{q} \cdot \mathbf{r}} \quad (4.25)$$

ü ñ Ð " Û X ´ Û) Ý @

$$\frac{d}{dt}(\delta f_{k,q}) = \mathcal{M}(\mathbf{q})_{kl}(\delta f_{l,q}) \quad (4.26)$$

t à , H 1 D ° X" %₀, @

$$\mathcal{M}(\mathbf{q})_{k,l} = -(1 - P_k)\delta_{kl}(1 - P_k) - \frac{i}{2}((q_x + iq_y)\delta_{k,l+1} + (q_x - iq_y)\delta_{k,l-1}) + \kappa(\mathcal{J}_{k,l} + \mathcal{J}_{k,k-l}) f_{L,k-l} \quad (4.27)$$

t ä .

t ` ü X (t @ effective reduced temperature μ local density $\rho(r)$ t \ ä” t ä .%,

$$\mu(\rho(r)) = 4\kappa \frac{\rho(r)}{\rho_0} \left(e^{-\eta^2/2} - \frac{2}{3} \right) - \left(1 - e^{-\eta^2/2} \right). \quad (4.32)$$

...X Ä Ð ‘@ ” Ût ÝXt $\rho(r) > \rho_0$ í ü $\rho(r) < \rho_0$ í t ~ XOE ä . Ä ’ DÄ íÐ
 ” μ t ‘ ...• ä t Ñè < \ \) ¥ < \ Ä Át à 0 | ...•X local density” T ± T ’ DÄ ä .
 t Ð X íÐ ” μ tL ü ‘ ...• ä t Èl jt \ Ä Át p ü Ä Ð a ‘ local density” T
 ± T @DÄ ä• Ä Ð Xt X” effective reduced temperature Vicsek-type ” Ð ~ Ä ~ ” bandsÐ
 X\ microphase separationX Tt È ~ „D L ^ ä . Hydrodynamic equationÐ \ • 8 Xà Ä \ Ä ° @
[\[BDG09\]](#)D 8 à X | .

4.2 Smoluchowski) Ý

Boltzmann) Ýt coarse-grain Vicsek-type ” X ¥) ÝÐ ì t Ð, Ý (3.3)ü @ ð • Ü ‘
 Û) ÝD 0 t ” ABP 0 ” X ¥) Ý @ Smoluchowski) Ýt iX ä . t)• @ Langevin Ûí YD
 0 t ” ä ‘ Ä X ¥) ÝD Ä \ DeanX t ` [Dea99]D ABP ” Ð ©X” f t ä [GRBSG14]. ä ‘ Ä X
 U` Ä h Ð œ t í Ý molecular chaos D Ä ...Xt , one-particle distribution function ì q X
 ” Smoluchowski) ÝD Ä ` ^ ä . Boltzmann) Ýü X ì Ñ Smoluchowski) Ý @ multiplicative
 stochastic noiseD ì hX à ^ ä .

5

망

5.1 Beyond mean field theory

Boltzmann) $\dot{Y} \ddot{u}$ Smoluchowski) $\dot{Y}, \varnothing \rightarrow \dot{a} \varnothing \setminus \in 0$ \ddot{A} hydrodynamic) $\dot{Y} \ddot{a} @$ " P molecular chaos] $\setminus \dot{E} \dot{a} \ddot{y} t \setminus t \ddot{a} . \dot{E} \dot{a} \ddot{y} t \setminus < \setminus$ Vicsek-type " \ddot{D} $\dot{Y} X$ " $4 \dot{E} 0 \dot{\prime} \dot{A}, \frac{1}{4} \dot{A} L a \dot{\prime} \dot{A},$
 $\ddot{o} t \dot{A} t t \rightarrow$ " $\dot{A} \dot{E} \varnothing \frac{1}{4}, \varnothing \rightarrow \dot{a}$ $\dot{A} \ddot{U} \ddot{D} X < 1 D t t \setminus \dot{a} . \dot{A} \dot{E} \varnothing \frac{1}{4} \ddot{D} \dot{i} t D \dot{E} |$ " $\ddot{A} \dot{A} X$
 $\ddot{o} , 1 D t$ " $\dot{E} \dot{a} \ddot{y} t \setminus D \ddot{o} \dot{\prime}$ " $t \setminus x \ddot{u} t D$ " $X \ddot{a} .$

$\setminus \dot{\prime} \dot{\prime}$ " $\dot{A} 8 \dot{\prime} @ D P X X$ " $\ddot{y} \ddot{U} \dots X \dot{A} , \rightarrow \dot{A}$ (MIPS, motility-induced phase separation) \ddot{A} hydrodynamic) $\dot{Y} D \mu t \setminus \dot{a} \ddot{o} | \dot{a} \dot{a} . \dot{o} \dot{E} \ddot{A} \ddot{D} | \dot{\prime} \sim$ " $0 \dot{\prime} -a \dot{\prime} \dot{A} , \rightarrow \dot{A} @$ model BX " $\ddot{u} \setminus$
 $, X$ " $\ddot{x} | | \ddot{y}$) $\dot{Y} < \setminus 0 \ddot{a}$ [HH77].

$$\partial_t \phi = -\nabla \cdot (\mathbf{J} + \sqrt{2DM}\Lambda) \tag{5.1}$$

$$\mathbf{J} = -M\nabla \mu_{eq} = -M\nabla \frac{\delta F}{\delta \phi} \quad \text{with } F[\phi] = \int \left\{ \frac{a}{2} \phi^2 + \frac{b}{4} \phi^4 + \frac{K}{2} |\nabla \phi|^2 \right\}$$

X $\dot{Y} \ddot{D}$ • $\ddot{D} \dot{A} m < \setminus \in 0$ $\ddot{A} \dot{A} J$ " $m D$ " $h < \setminus h \dot{o} \dot{E} t \setminus D \ddot{y} \ddot{U} < \dot{E} \ddot{A} \setminus U \ddot{y} \setminus \dot{a} .$

| ä´

$$J/M = -\nabla \left[\frac{\partial F}{\partial F} + \lambda |\nabla \phi|^2 \right] + \zeta (\nabla^2 \phi) \nabla \phi \tag{5.2}$$

\ U¥\ t` x active model B+ (AMB+) ^ ä [TNC18]. X ÝĐ jL mD 0<\ “ @Éà¥t` ì <\ Ä ä° eø\´ Á,, ¬ ÁD ô x ä .Éà¥t` D´ jL mX¨ ü¨ P à\$ stochastic field theory Đ \ ðl D¨ \ Ü t ä .

5.2 Discrete symmetry flocking

Vicsek-type ABP¨ X´ €• ÄĐ t ù X¨ • Ä) ¥ Ä θ¨ ð• Ä X (θ → θ + φ)Đ t m t ä .
 ð• m1 D DT\ ^ ð• Ä X m1 D¨ ¥ Ù < È Ä X Ñ è p Ù @ t` <\ ä° eø\´ ðl ü t ä .
 • Ä) ¥ j 0 n = (cos θ, sin θ) X) ¥ Ä p X ^ ð• x

$$\theta = \frac{2\pi s}{p}, \quad (s = 0, 1, \dots, p-1) \tag{5.3}$$

<\ \ active p-state clock modelD Ý t ô• [CMR22, SCTT22]. Vicsek¨ @ p = ∞x ù \ Đ t ù X p ,
 ¥ è \ p = 2x ½°¨ active Ising model (AIM)Đ t ù \ ä [ST13].

\ t` x eø|´ AIM@ flocking Á t 0´ -a´ Á t @ @ Á,,D U½X¨ p °
 x 0 ì | ^ ä [SCT15]. ø ì ~ ,\ ü Đ È mœ \ ðl °ü¨ ´ à ç @ Ü Ù HĐ %o¨ X Ü %o´ 0 Đ
 » @ ü @ É à ¥ t` 0 D hydrodynamic) ÝĐ » @ ü ¼ È ~ è }¨ ^¨ Ä | ì ä ^
 ô ì ü à ^ ä [BGR+23, WN24]. AIMX ðl X P,, D è ^ ¬ t ô• .

1. AIMX ñ ¥< \ flocking Á tX 0´ Á ð t Á a´ Á tt` X ½ È ä [SCT15].

XW24], Ä ' @ *E. coli*" \ X ' ÜD Ü0 Tt Ð' Ü ÜD ì à ä [CLS+17].t ä Ä | t è " ...• ä @
 chirality| à ^ ' ,• Ä , Á8 ' ©t Vicsek-type" ô ä ä ' \ Ü ÁD ô x ä .

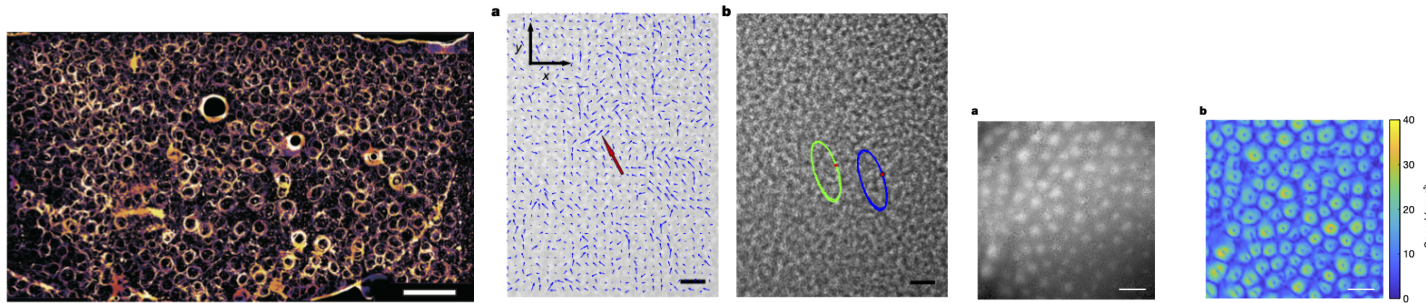


Figure 5.2: vortices in bacteria ([SNS+12, CLS+17, XW24]Ð ì).

Vortex array (4 D \$...X0 t Sumino ñ @ ...Ü x chirality| ì h\ " Ä | ÜX ä [SNS+12]

$$\begin{aligned}
 \mathbf{r}_i &= v_0 \mathbf{n}_\theta \\
 \dot{\theta}_i &= \omega_i + \frac{\alpha}{|\mathcal{N}_i(r_0)|} \sum_{j \in \mathcal{N}_i(r_0)} \sin(\theta_j - \theta_i) \\
 \dot{\omega}_i &= -\frac{1}{\tau} (\omega_i - \omega_0) + \zeta_i(t)
 \end{aligned}
 \tag{5.4}$$

Chirality| ...Ü < \ Ä ...^ 0 L 8 Ð t " t vortex array (4 D ô ì ü " f @ € | ' |t D È ä . \ , Xu

@ Wu” ø ä X ä Ø °ü | ä LX ” < \ ¬ ` ^ ä à ô à X ä :

$$\begin{aligned}
 \mathbf{r}_i &= v_0 \mu_i f_i \mathbf{n}_\theta + \sqrt{2D_r} \mathbf{x}_{i,r_i} \\
 \dot{\theta}_i &= \omega_i + \frac{k_\theta}{|\mathcal{N}_i(r_0)|} \sum_{j \in \mathcal{N}_i(r_0)} \sin(\theta_j - \theta_i) + \sqrt{2D_\theta} \tilde{\zeta}_{\theta,i} \\
 \dot{\omega}_i &= -\frac{\omega_i}{\tau} + \frac{k_\omega}{|\mathcal{N}_i(r_0)|} \sum_{j \in \mathcal{N}_i(r_0)} (\omega_j - \omega_i) + \text{sign}(\omega_i) e^{-|\omega_i| \omega_0} + \sqrt{2D_\omega} \tilde{\zeta}_{\omega,i}(t)
 \end{aligned}
 \tag{5.5}$$

$\omega \leftrightarrow -\omega$ m1 t Ä à ...Ü x chirality| Ä ...X Ä JX L Ð Ä vortex cellt l ä” f @ Á 8 ‘ © Ð
 Xt $\omega \leftrightarrow -\omega$ m1 t • < \ • 4 È LD X ø \ ä . Chiral active ...•X pattern formation@ e ø \ ‘
 ð l ü f t ä .

5.4 Multi-species system

ì ì ...X ¥ Ù ...• < i Ä” active matter ð l X È \ ‘ ¥ Ð ô à ^ ä . A, B P ...< \ t è ‘ Ä Ä Ð
 ...• ¬ tX • Ä , Á 8 ‘ © X • 1 D 2 × 2%o, $J_{\alpha\beta} \sim \hat{A} \cdot (\alpha, \beta = A, B)$.

- Chatterjee@ ð Ù ð l • ä @ $J_{AA} = J_{BB} > 0$ t à $J_{AB} = J_{BA} < 0$ x ½° , %o @ ... • | ¬ ” • Ä | @
) ¥ < \ , X à ä x ... • | ¬ ”) ¥ < \ , X” ½° | ð l X ä [CMW⁺23]. P ...X ...•
 ” antiparallel flocking state@ parallel flocking state| 1 X p \ | 0 TMX \$ ” Á 8 ‘ © D \ © 9 @
 œ < X ”) Ý < \ Ñ è p Ù Ð ô x ä .
- $J_{AB} \neq J_{BA}$ x ½° P ... ¬ tX Á 8 ‘ © @ nonreciprocal 1 È D < p [FHLV21], 1 ^ $J_{AB} \times J_{BA} < 0$

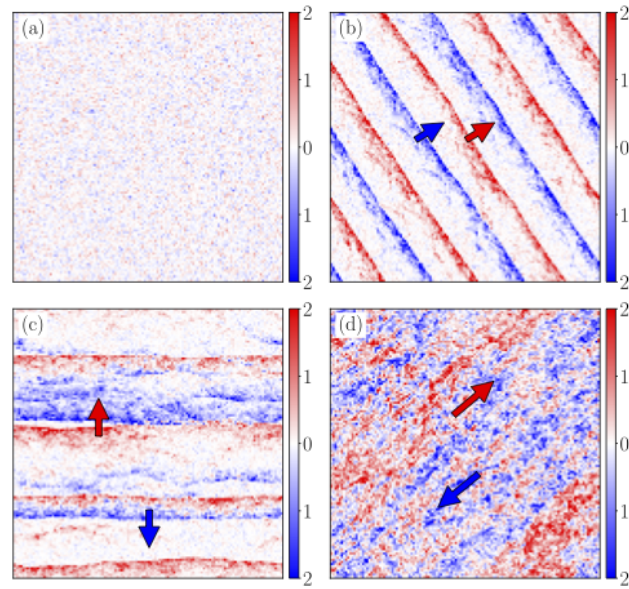


Figure 5.3: Two-species Vicsek “ X antiparallel flocking and parallel flocking states ([CMW⁺23]Đ ĩ).

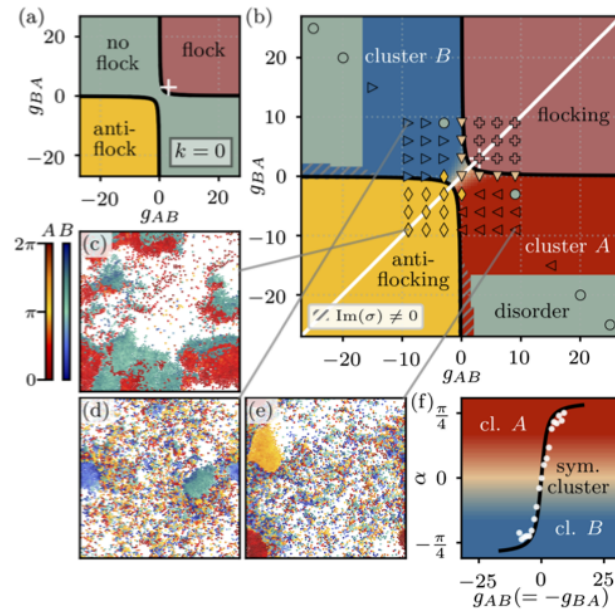


Figure 5.4: Non-reciprocal Vicsek model ([KK24]).

at $\theta = \frac{1}{2}\pi, \dots$ chiral clustering, $\theta = 0$, clustering $\theta = \frac{\pi}{4}$ and $\theta = \frac{3\pi}{4}$ [MSA⁺23, MCNR24, KK24].

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